User's Manual

Vortex Flowmeter VY Series HART Communication Type

IM 01F07A02-01EN



IM 01F07A02-01EN 6th Edition

Vortex Flowmeter VY Series HART Communication Type

IM 01F07A02-01EN 6th Edition

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1. Introduction

This manual explains basic operations of the Vortex Flowmeter VY Series with HART Communication Protocol.

For items which are not covered in this manual, read the applicable user's manuals listed in "Table 1.1 Related Documents" in the Vortex Flowmeter VY Series Installation Manual. These documents can be downloaded from the Yokogawa Electric Corporation website. To ensure the correct use of the product, read these manuals thoroughly and fully understand how to operate the product before operating it. To confirm the model name and specifications of the product, refer to the general specifications.

Website address: https://www.yokogawa.co.jp/library/

Precautions Related to the Protection, Safety, and Alteration of the Product

The following safety symbol marks are used on this product and in this manual.

A WARNING sign denotes a hazard. It calls attention to procedure, practice, condition or the like, which, if not correctly performed or adhered to, could result in serious injury or death of personnel. This document presents precautions for avoiding such hazards should such a situation arise.

A CAUTION sign denotes a hazard. It calls attention to procedure, practice, condition or the like, which, if not correctly performed or adhered to, could result in slight injury to personnel or damage to or destruction of the product. This document presents precautions for avoiding such hazards should there be a physical risk to the user's well-being or damage to equipment.

IMPORTANT

An IMPORTANT sign denotes that attention is required to avoid damage to the instrument or system failure.

NOTE

A NOTE sign denotes information necessary for essential understanding of operation and features.

The following symbols are used in the product and the manual to indicate the accompanying safety precautions:

Functional grounding terminal
 (This terminal should not be used as a protective grounding terminal.)

- Direct current
- A Handling precaution

This symbol indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the product.

For the protection and safe use of the product and the system in which this product is incorporated, be sure to follow the manual whenever you handle the product. Take special note that if you handle the product in a manner that violates these instructions, the protection function of the product may be damaged or impaired. In such a case, Yokogawa Electric Corporation does not guarantee the quality, performance, function, or safety of the product.

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Regarding This User's Manual

- This manual should be provided to the end user.
- The contents of this manual are subject to change without prior notice.
- No part of this manual may be reproduced in any form without Yokogawa Electric Corporation's written permission.
- Yokogawa Electric Corporation makes no warranty of any kind with regard to this manual, including, but not limited to, implied warranty of merchantability and fitness for a particular purpose.
- If any questions arise or errors are found, or if any information is missing from this manual, inform the nearest Yokogawa Electric Corporation sales office.
- The specifications covered by this manual are limited to those for the standard type under the specified model number break-down and do not cover custom-made products.
- Note that changes in the specifications, construction, or component parts of the product may not immediately be reflected in this manual at the time of change, provided that postponement of revisions will not cause difficulty to the user from a functional or performance standpoint.
- This manual is intended for the following personnel:

Engineers responsible for the installation and wiring of the product.

Personnel responsible for the normal daily operation of the product (operator).

• To ensure correct use, read this manual and the applicable manuals thoroughly before starting operation. Read the general specifications for specifications of the product.

Trademarks

- All the brands or names of Yokogawa Electric Corporation's products used in this manual are either trademarks or registered trademarks of Yokogawa Electric Corporation.
- All other company and product names mentioned in this manual are trade names, trademarks or registered trademarks of their respective companies.
- In this manual, trademarks and registered trademarks are not marked with "™" or "®".
- "HART" is the registered trademark of FieldComm Group.

1.1 For Safe Use of Product

For the protection and safe use of the product and the system in which this product is incorporated, be sure to follow the manual whenever you handle the product. Take special note that if you handle the product in a manner that violates these instructions, the protection function of the product may be damaged or impaired. In such a case, Yokogawa Electric Corporation shall not be liable for any indirect or consequential loss incurred by either using or not being able to use the product.

General



Do not open the cover in wet weather or humid environments. When the cover is open, the stated enclosure protection is not applicable.

Operation



Be sure to enable the write protect function to prevent parameters from being overwritten after finishing parameter setting.

Refer to the installation manual for the hardware write protect function, and Section 4.17 for the software write protect function.

Maintenance



Maintenance of this product should be implemented in a maintenance service shop where the necessary tools and environment conditions are provided. The required environmental condition is that the ambient temperature should be 5 to 40°C (the maximum relative humidity is 80% for temperature 5 to 31°C, and decreasing linearly to 50% relative humidity at 40°C at temperatures exceeding 31°C).

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1.2 Warranty

- The warranty shall cover the period described in the quotation presented to the purchaser at the time of purchase. We will make any repairs that may become necessary during the guaranteed term free of charge.
- Contact our sales office if this instrument requires repair.
- If a problem arises with this product, inform Yokogawa Electric Corporation of the nature of the problem and the circumstances under which the problem developed, including the model specification and serial number. Any diagrams, data and other information you can include in your communication will also be helpful.
- The degree of responsibility for repair costs of the problems shall be determined by Yokogawa Electric Corporation based on our investigation.
- The purchaser shall bear the responsibility for repair costs, even during the warranty period, if the malfunction is due to:
 - Improper and/or inadequate maintenance by the purchaser.
 - Failure or damage due to improper handling, use, or storage which does not conform to design conditions.
 - Use of the product in question in a location not conforming to the standards specified by Yokogawa Electric Corporation, or problems due to improper maintenance of the installation location.
 - Failure or damage due to modification or repair by any party except Yokogawa Electric Corporation or an approved representative of Yokogawa Electric Corporation.
 - Malfunction or damage from improper relocation of the product in question after delivery.
 - Reason of force majeure such as fires, earthquakes, storms/floods, thunder/lightning, or other natural disasters, as well as disturbances, riots, warfare, or radioactive contamination.

2. Operation by Display unit

This chapter describes the basic configuration of the display and how to set parameters from the display.

2.1 Basic Operating Procedures

The parameter settings can be changed by using the three switches [SET], [SHIFT] and [INC] on the display.

This product can be also operated by using the dedicated handheld terminal or the FieldMate (Versatile Device Management Wizard). For details about the setting procedure, see Chapter 4.

Be sure to enable the write protect function to prevent parameters from being overwritten after finishing parameter setting.

Refer to the Installation Manual for the hardware write protect function, and Section 4.17 for the software write protect function.

NOTE

Only basic parameters required for use of this product can be set and displayed on the display. Parameters that cannot be set and displayed on the display should be set and checked using the HART configuration tool.

2.2 Configuration and Functions of the Display

The display of the integral flowmeter and remote transmitter has the following functions.

2.2.1 Configuration of Display



1 Upper display	: This displays the instantaneous flow rate data and other setting item Nos.
2 Lower display	: This displays the process data and alarm No. acquired by total data, temperature data and analog
	input.
3 Alarm icon	: This displays if a serious alarm has occurred.
	Serious alarms are system alarms and process alarms.
4 Write protect icon	This displays the write protect status.
5 NE107 category icon	This displays the NE107 category of the target alarm when the alarm No. is displayed.
6 SET switch	This switch is used to change the flow rate data indication and the content of setting data.

Basic operation of switches

The basic operations of the display are done by the three switches [SET], [SHIFT], and [INC]. Switch functions change by holding down two switches in different combinations.

Switch operation	Functions
SET	 Moves to the setting mode Applies parameters and data Moves to next menu
SHIFT	 Sets/resets multiple selectable options (Select type parameter) Moves the cursor right (Numeric type parameter)
INC	 Moves the cursor down (Select type parameter) Increment value (Numeric type parameter) Changes the position of the decimal point (Numeric type parameter)
SHIFT + SET	 Cancels a setting Returns to the previous menu

2.2.2 Operation Levels

On this product, parameters that can be accessed can be restricted by assigning operation levels (user roles) to parameter settings.

The following table summarized	zes the operation	levels that can	be assigned or	n this product
--------------------------------	-------------------	-----------------	----------------	----------------

 Table 2.2.2
 Parameters Settable on The Display and Operation Rights

Operation Bighto	Parameter			
Operation Rights	Read	Write		
Operator	All parameters	Display parameter settings that do not affect processes can be set		
Maintenance	All parameters	Parameters that can be set by Operator levels and test- and adjustment-related parameters can be set.		
Specialist	All parameters	All parameters that can be written can be set		

By default, operation levels are disabled. When operation levels are disabled, the only levels that can be accessed is the Specialist levels.

To enable operation levels, HART communication must be used. Operation levels cannot be enabled on the display. For details about settings, see 4.17.2.

When operation levels are enabled, the pass code must be entered before moving to the setting screen. The screen moves to the setting screen by levels corresponding to the entered pass code.



2.3 Display Items in Display Area

Display Items are categorized into the following three items.

NOTE

There are some influence by changing the setting of display period, see the follows.

Mode Name	Display Content
Flow rate display mode	In this mode, the instantaneous flow rate and totalized value are displayed.
Setting mode	In this mode, the content of parameters is checked in the setting area and data is overwritten. Pressing the [SET] switch in the flow rate display mode moves the display to the setting mode.
Alarm No. display mode	When an alarm occurs in the flow rate display mode, the display alternates between the number indicating the content of the alarm and the normal data display.*1

*1: The display time of the display mode will vary depending on the display period.

Display period	Flow rate display mode	Alarm No. display mode
0.25s	4s	2s
0.5s	8s	4s
1s	16s	8s
2s	32s	16s
4s	64s	32s
8s	128s	64s



• The display enters the setting mode by pressing the [SET] switch in the flow rate display mode.

When operation levels are enabled, the pass code must be entered before moving to the setting screen.

- To toggle between item setting and No. setting, use the [SHIFT] switch.
- The item or No. to set can be changed by the [INC] switch.

2.4 Display Mode

In this mode, the instantaneous flow rate and flow rate totalized values are displayed. The following items can be displayed.

Display Item	Description	Upper display	Lower display
Flow rate % display	The instantaneous flow rate is displayed as a % of the span. In addition to the % display, "F" indicating flow rate is displayed at the top left of the display area. (See figure below.)		x
Engineering unit flow rate display	Engineering unit flow The instantaneous flow rate is displayed by engineering unit.		x
Flow rate total display	The flow rate totalized value is displayed.	х	0
Temperature % display ^{*1}	The measured temperature is displayed as a % of the span. In addition to the % display, "T" indicating the temperature is displayed at the top left of the display area. (See figure below.)	0	x
Actual temperature display ^{*1}	The measured temperature is displayed.	x	0
Analog input process value	The process value acquired by analog input is displayed by engineering unit.	x	0
Without display	Nothing is displayed.	Х	0

*1: Only when equipped with built-in temperature sensor





For details, see 4.13.1 Setting Display Items.

2.4.1 Changing from % Display to Actual Flow Rate Display

The following describes how to change the display content on the upper display of the select type parameters on the display.



IMPORTANT

If this product is turned off before 30 seconds after setting the parameters, the settings will not be stored correctly. Keep the product turned on for over 30 seconds after setting the parameters.

2.4.2 Displaying Totalized Values on the Lower Display



If this product is turned off before 30 seconds after setting the parameters, the settings will not be saved correctly. Keep the product turned on for over 30 seconds after setting the parameters.

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2.5 Setting Mode

This section briefly describes the setting mode.

NOTE

Before changing settings, be sure to check the content of parameters in Chapter 4 "Functions" and Chapter 5 "Parameter Lists."

2.5.1 Configuration of the Setting Mode Display

Pressing the [SET] switch in the flow rate display mode moves the display to the setting mode as shown below. If operation levels are set at this time, the pass code must be entered. For details about operation levels, see 4.17.2.

NOTE

The time to move to the setting mode by pressing the [SET] switch, is needed a little longer cause of avoiding miss touch the switch. Then, it depends on the setting of display period, and it is about 2 times of the period.

Pay attention for the long period setting.



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IMPORTANT

If this product is turned off before 30 seconds after setting the parameters, the settings will not be saved correctly. Keep the product turned on for over 30 seconds after setting the parameters.

2.5.2 Data Setting Procedure

How to enter numerical values

NOTE

There are 6 digit in lower line of this segment type LCD. However, it is restricted to 5 digit in case of numerical value with sign, even though some parameters can be set to 6 digit by the HART communication access.



Example: Change the span from 100 m³/h to 150 m³/h

IMPORTANT

If this product is turned off before 30 seconds after setting the parameters, the settings will not be stored correctly. Keep the product turned on for over 30 seconds after setting the parameters.

How to set selection items

Example: Change contact output to Off (no output) to Alarm switch (alarm contact output)



IMPORTANT

If this product is turned off before 30 seconds after setting the parameters, the settings will not be stored correctly. Keep the product turned on for over 30 seconds after setting the parameters.

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3. Operation with HART Configuration Tool

This chapter describes the connection of this product and the HART configuration tool (FieldMate (Versatile Device Management Wizard)), and the operations using the HART configuration tool. For details about FieldMate, refer to the User's Manual of FieldMate (IM 01R01A01-01).

NOTE

- For more details regarding operation of the HART configuration tool not given in this manual, refer to the User's Manual of the HART configuration tool.
- When using FieldMate as the HART configuration tool, be sure that the revision is R3.04.20 or later.

3.1 Connecting the HART Configuration Tool

The HART configuration tool can interface with this product from the control room, the device site, or any other wiring termination point in the loop, provided there is a minimum load resistance of 250Ω between the connection and the receiving instrument.

To communicate with the HART configuration tool, the HART configuration tool must be connected in parallel with this product. The connections must be non-polarized. Figure 3.1 shows a connection example



Figure 3.1 Connecting the HART Configuration Tool

IMPORTANT

The communication signal is superimposed on an analog output signal during communication. It is recommended to set a low-pass filter (approximately 0.1 s) to the receiver in order to reduce the output effect from the communication signal. Before online-communication, check that the communication signal does not affect the host system.

3.2 HART Configuration Tool and Product Revision

IMPORTANT

The protocol revision supported by the HART configuration tool must be the same as or later than the protocol revision of the product. If it is not, a communication error will occur.

3.2.1 Device Description (DD) and Device Revision

Before using the HART configuration tool, check that the DD of this product is installed in the configuration tool. If the correct DD is not installed in the configuration tool, download the correct DD from the FieldCommGroup official site and install it, or contact the respective vendor of the configuration tool for its upgrade information.

The device description is as follows.			
DD Revision 1 or later			
Device Type	VY Series (0x3713)		
Device Revision	1 (the software revision is R1.01.01 or R1.01.02) 2 (the software revision is R1.01.03 or more)		

Checking the DD revision

- (1) Turn on the power of this product with the configuration tool separated.
- (2) Check the device revision from the installed DD file name according to the procedure provided for the configuration tool.

The DD file name is four digits. The upper two digits indicate the device revision and the lower two digits indicate the DD revision.

NOTE

The device revision of the DD file is annotated in hexadecimal.

Checking the Device revision

Connect the setting tool to this product and confirm the revision by the following parameter.

Menu path

_					
	HART	Device Settings ►	Detailed setup ►	HART config	fld dev rev*1 / Device Revision*2
_					

*1: For Device revision 1 and DD revision 1 or 2

3.2.2 Device Type Manager (DTM) and Device Revision

When using FieldMate as the HART configuration tool, use the following DTM.

DTM Name	VY Series FDT2.0 HART7 DTM
DTM Revision	5.9.7.0 or later (the software revision is R1.01.01 or R1.01.02) ^{*1} 5.9.11.0 or later (the software revision is R1.01.03 or more) ^{*2}
Device Type	VY Series (0x3713)
Device Revision	1 (the software revision is R1.01.01 or R1.01.02) 2 (the software revision is R1.01.03 or more)

*1: The DTM is included in Yokogawa DTM Library HART 8.7 or later.

*2: The DTM is included in Yokogawa DTM Library HART 8.12 or later.

NOTE

The DTM revision can be confirmed by "DTM setup".

Device Files is a medium included in FieldMate.

The user registration site provides Device Files with the latest update programs.

(URL: https://partner.yokogawa.com/japan/fieldmate/)

When updating the DTM, the following operations with "DTM setup" are required.

- Update DTM catalog
- Register DTM to the supported device.

For details, refer to the User's Manual of FieldMate.

3.3 **Basic Setting**

If the dedicated parameters are specified at the time of ordering, this product is shipped with the Tag No. or device information configured.

The Tag No. and device information can be checked and set with the following parameters.

Tag No. (Tag, Long tag)

Menu path

HART Device Settings ► Detailed setup ► HART config ► (see table below)

Parameter	Description
Тад	Up to 8 alphanumeric characters *1
Long tag	Up to 32 alphanumeric characters *2

Device information (Descriptor, Message)

Menu path

HART Device Settings ► Detailed setup ► HART config ► (see below)

Parameter	Description			
Descriptor	Up to 16 alphanumeric characters *1			
Message	Up to 32 alphanumeric characters *1			

*1: Symbols, letters and numbers enclosed by the thick line in the following table are available.

*2: All symbols, letters and numbers in the following table are available.

SP	!	"	#	\$	%	&	'	()	*	+	,	-		/
0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
@	Α	В	С	D	Е	F	G	Н	I	J	К	L	М	Ν	0
Р	Q	R	S	Т	U	V	W	Х	Y	Z	[١]	^	_
`	а	b	с	d	е	f	g	h	i	j	k	Ι	m	n	0
р	q	r	s	t	u	v	w	x	y	z	{		}	~	

* "SP" indicates a space.

3.4

Parameter Configuration

For details of the HART menu tree and parameters, see Chapters 4 and 5. Note that some display parameters are different from those of the HART configuration tools.



CAUTION

Note that parameters cannot be set on the display while communicating with the HART configuration tool.

3.5 **Data Updating and Upload/Download Function**

(1) Updating data The data is automatically updated at 0.5 to 2-second cycles.

Upload/download function (2)

The upload function is used for copying the parameters of the product to the HART configuration tool. The download function is used for setting the copied parameters in the HART configuration tool into another product. The applicable parameters are included in "Upload variables" as follows.

NOTE

Upload variables can be displayed from [Device] -> [Offline Parameters] from the toolbar of the DTM.

When writing parameters from Upload variables, click [Download to device].

Menu path

HART	Upload variables	(see table below))
		(/

Тад	Reynolds adjust	Air pressure	Display period
Long tag	Viscosity unit	Compensation type	Display startup
Descriptor	Viscosity	Steam type	Display NE107
Message	Adjust reynolds number 1	Density unit	Display format flow
Auto delete time	Re adjust value 1	Fixed density	Display format temperature
Burnout recover	Adjust reynolds number 2	Base density	Display format pressure
Alarm status select	Re adjust value 2	Dryness	Nominal size
Alarm record select	Adjust reynolds number 3	Deviation	Body type
Flow sensor alarm action	Re adjust value 3	Temperature coefficient 1	Sensor type
Fluctuating level	Adjust reynolds number 4	Temperature coefficient 2	Connection type
Transient noise count	Re adjust value 4	Enthalpy unit	K factor unit
High vibration action	Adjust reynolds number 5	Fixed enthalpy	K factor
High vibration time	Re adjust value 5	Heat difference select	Memo 1
Critical vibration action	Expansion factor adjust	Heat difference conv unit	Memo 2
Critical vibration level	Fluid type	Heat difference conv factor	Memo 3
Critical vibration time	Flow select	Totalizer rate	Signal level
Clogging time	Volume unit	Totalizer preset value	Trigger level mode
Sensor circuit threshold	Mass unit	Totalizer reset mode	Trigger level(TLA)
Sensor capacitance threshold	Standard/Normal unit	Analog output low limit	Noise balance mode
Sensor resistance threshold	Energy unit	Analog output high limit	Noise ratio(manual)
Auto release time	Time unit	Pulse/Status output mode	
Flow rate gain	Flow span	Pulse output rate	
Instrument error adjust	Flow damping	Frequency output select	
Adjust vortex frequency 1	Flow lowcut	Frequency output zero	
Adjust value 1	Flow user conversion	Frequency output span	
Adjust vortex frequency 2	Flow user unit	Status output direction	
Adjust value 2	Flow conversion factor	Alarm switch select	
Adjust vortex frequency 3	Temperature unit	Limit switch select	
Adjust value 3	Fixed temperature	Limit switch mode	
Adjust vortex frequency 4	Base temperature	Limit switch level	
Adjust value 4	Pressure unit	Limit switch hysteresis	
Adjust vortex frequency 5	Fixed pressure	Display line upper	
Adjust value 5	Base pressure	Display line lower	

3.6 Specific Functions of HART Configuration Tool

3.6.1 **Process Variable Setup (Dynamic Variables)**

The device deals with four data (flow rate, temperature, total flow rate and pressure). These four data are allocated to PV (Primary Variable), SV (Secondary Variable), TV (Tertiary Variable) and QV (Quaternary Variable). The variable of PV is 4 to 20mA current output. Therefore, the total flow rate do not allocate to PV. (Except the built-in temperature sensor (B, D, H) and pressure, each dynamic variables are fixed at factory setting.)

Dynamic Variable	Items	Factory Setting
PV	Flow rate, Temperature	Instantaneous Flowrate
SV	Flow rate, Total, Temperature	Total
TV	Flow rate, Total, Temperature, Pressure	Temperature
QV	Flow rate, Total, Temperature, Pressure	Pressure

• Procedure to call up the Dynamic variable assignments.

Check settings : **[Root Menu]** \rightarrow Detailed Setup \rightarrow HART config \rightarrow Dynamic variables \rightarrow PV is^{*1} / Primary Variable^{*2} / SV is^{*1} / Secondary Variable^{*2} / TV is^{*1} / Tertiary Variable^{*2} / QV is^{*1} / Quaternary Variable^{*2}

Change settings: **[Root Menu]** \rightarrow Detailed Setup \rightarrow HART config \rightarrow Dynamic variables \rightarrow Dynamic variables assignments (METHOD)

Update time period of each measurement value is as follows;

- Flow rate: Flow rate Update time period
- Total: Total Update time period
- Temperature: Temperature Update time period
- Pressure: Pressure Update time period

*1: For Device revision 1 and DD revision 1 or 2

3.6.2 **Burst Mode**

(1) Applicable parameters of the burst mode When the burst mode is enabled, the product continuously sends up to three data via HART communication. Also, it is possible to continuously send an alarm signal when a change to the product settings or a change by self diagnosis is detected.

NOTE

When changing the Burst Mode setting, set the burst mode to "Off". When stopping burst mode, please do Stop burst.

Command Parameter	Burst Command	Trigger Mode	Trigger Source	Trigger Units		
		Continuous				
	Cmd1:PV*1 / Cmd1:Read Primary Variable* ²	Window		Depends on the assigned variable to		
Primary Variable (PV)		Rising				
		Falling				
		On-change				
	Cmd2.% range/	Continuous				
	current*1 /	Window				
Percent Range and	Cmd2:Read	Rising	Dereent Denge	%		
	Percent Range/	Falling	reicent Kange			
	Current*2	On-change				
	Cmd3:Dyn	Continuous				
Dynamic Variables	vars/current*1	Window				
(PV, SV, TV, QV) and	/ Cmd3:Read Dynamic Variables/ Current* ²	Rising	PV	Depends on the		
Loop Current		Falling				
		On-change				
	Cmd0:Dovico	Continuous				
	vars w/ status*1	Window	Process variable	Depends on the assigned variable		
Device Variables with	/ Cmd9:Read	Rising	assigned to the			
Status	Device Variables	Falling	top of Burst Device	to Burst Device		
	with Status*2	On-change	Variables	Variables		
	Cmd33:Device	Continuous				
	variables*1 /	Window	Process variable	Depends on the		
Device Variables	Cmd33:Read	Rising	assigned to the	assigned variable		
	Device	Falling	top of Burst Device	to Burst Device		
	Variables*2	On-change	Variables	Variables		
Additional Device	Cmd48:Read	Continuous				
Status	Additional Device Status	On-change	All statuses			

*1: For Device revision 1 and DD revision 1 or 2

(2) Burst Mode setting The Burst Mode can be set in two modes, Easy Burst Mode or Detailed Burst Mode.

Setting the Easy Burst Mode

In the Easy Burst Mode, one Burst Command can be sent continuously. Easy Burst Mode (Burst Message $\#0^{*1}$ / Burst Message 1^{*2}) can be set by the following parameters.

Menu path

NOTE

When the Easy Burst Mode is used, Event Notification cannot be used.

Setting the Detailed Burst Mode

In the Detailed Burst Mode, up to three Burst Commands can be sent continuously under various conditions. Detailed Burst Mode (Burst Message #1-3*1 / Burst Message 2-4*2) can be set by the following parameters.

Menu path

	Device Settings ► Detailed setup ► HART config ► Burst setting ► Set detailed burst* ¹
HART	Device Settings ► Detailed setup ► HART config ► Burst setting ► Detailed burst setting ► Set
	detailed burst* ²

Set as follows according to the method*.

- Burst Command
- Update Period*1 / Update Rate*2 / Max Update Period*1 / Max Update Rate*2
- Trigger Mode
- A method is a program for simplifying setting of parameters. *.

(3) Setting Burst Command

Select the data to send by the Burst Mode by a Burst Command.

Burst Command	Command Parameter
Cmd1:PV*1 / Cmd1:Read Primary Variable*2	Primary Variable (PV)
Cmd2:% range/current*1 / Cmd2:Read Percent Range/Current*2	Percent Range and Loop Current
Cmd3:Dyn vars/current* ¹ / Cmd3:Read Dynamic Variables/Current* ²	Dynamic Variables (PV, SV, TV, QV) and Loop Current
Cmd33:Device variables*1 / Cmd33:Read Device Variables*2	Device Variables
Cmd9:Device vars w/ status*1 / Cmd9:Read Device Variables with Status*2	Device Variables with Status
Cmd48:Read Additional Device Status	Additional Device Status

*1: For Device revision 1 and DD revision 1 or 2

(4) Setting Burst Device Variables

When Cmd9:Device vars w/ status^{*1} / Cmd9:Read Device Variables with Status^{*2} or Cmd33:Device variables^{*1} / Cmd33:Read Device Variables^{*2} is selected as the Burst Command, Burst Device Variables must be set for which up to four values can be set.

Device Variable Code	Burst Device Variables
0	Flowrate
1	Total
2	Temperature
3	Pressure

(5) Setting the Update Period*1 / Update Rate*2 / Max Update Period*1 / Max Update Rate*2

Set the Update Period*1 / Update Rate*2 / Max Update Period*1 / Max Update Rate*2, which is the update interval of the Trigger Mode. The Trigger Source is checked at the Update Period*1 / Update Rate*2 interval. When it fulfills the conditions of the Trigger Mode, the data is updated. When it does not fulfill the conditions of the Trigger Mode at the Update Period*1 / Update Rate*2 interval and reaches the Max Update Period*1 / Max Update Rate*2 interval, the data is forcibly updated.

Select the Update Period^{*1} / Update Rate^{*2} / Max Update Period^{*1} / Max Update Rate^{*2} from the following.

Update Period*1 / Update Rate*2 / Max Update Period*1 / Max Update Rate*2	
0.5 s	8 s
1 s	16 s
2 s	32 s
4 s	60 s to 3600 s (any value)

NOTE

For the Update Period^{*1} / Update Rate^{*2}, set a value smaller than the Max Update Period^{*1} / Max Update Rate^{*2}.

(6) Setting the Trigger Mode

Set the Trigger Mode. When "Window", "Rising", or "Falling" is set, the Trigger Level must be set.

Trigger Mode	Description
Continuous	Burst Messages are transmitted continuously.
Window	The Trigger Level is the amount of change. The device variable value detects and transmits the amount of change.
Rising	The setting value of the Trigger Level is the high limit value. When the device variable value exceeds the high limit value, this is detected, and a message is transmitted.
Falling	The setting value of the Trigger Level is the low limit value. When the device variable value exceeds the low limit value, this is detected, and a message is transmitted.
On-change	When the device variable value is changed from the previous output, it is detected, and a message is transmitted.

*1: For Device revision 1 and DD revision 1 or 2

3.6.3 Event Notification

Changes to the device settings and changes in the device status by self diagnosis can be detected as events, and alarm signals are sent continuously as a result. Up to five events can be stored as an event history. When Event Notification is used, the Detailed Burst Message must be set and the Burst Message must be enabled.

NOTE

Note that events stored as the event history are cleared from memory when the power is turned off.

(1) Setting Event Notification

The Event Notification can be set by the following parameters.

Menu path

```
HART Device Settings ► Detailed setup ► HART config ► Event notification ► (see table below)
```

Parameter	Description
Set event notification	Sets Event Notification.
Stop event notification	Sets stopping of Event Notification.

Select the Event Notification setting from the table below.

Selection	Description
Event Notification Bit Mask	Sets the device status to trigger detection of an event (mask function). (Cmd48: Read Additional Device Status)
Retry Rate	Sets the interval at which an Event Notification is issued again when an event occurs.
Max Update Rate	Sets the interval at which an Event Notification is issued again when an event has not occurred.
Debounce Interval	Sets the minimum time that an event continues.

(2) Acknowledging events

If an Event is occurring, it must be acknowledged. Acknowledgment of an event can be set by the following parameter.

Menu path

HART

Device Settings ► Detailed setup ► HART config ► Event notification ► Acknowledge event

NOTE

Only the event that occurred first can be acknowledged. When multiple events occur, they must all be acknowledged.

(3) Event Notification flow When Event Notification is enabled, a change in status caused by self diagnosis of the device will activate the alarm Event1. Event1 is continuously transmitted at the interval of Retry Rate until it is acknowledged.

If Event2 occurs before Event1 is acknowledged, the information on Event2 is stored internally and continuously transmitted until Event1 is acknowledged. When Event1 is acknowledged, Event1 disappears and Event2 is continuously transmitted until it is acknowledged. When Event2 is acknowledged, all Events are acknowledged, and are continuously transmitted at the interval of the Max Update Rate.

3.6.4 Multidrop Mode

When the Multidrop Mode is enabled, the product can reference the connection of multiple HART communication devices on one communication transmission line. This product can connect up to 63 devices. To enable the Multidrop Mode, a number from 1 to 63 must be assigned to the polling address. When the Multidrop Mode is enabled, analog output signal settings of 4 to 20 mA must be changed because all the data is transmitted digitally. Set the Multidrop Mode by the following procedure.

(1) Setting the polling address

Assign a number from 1 to 63 to the polling address. The polling address is set in method "Loop current mode" and can be set by the following parameters.

Menu path

HART Device Settings ► Detailed setup ► HART config ► Poll addr*1 / Polling Address*2

NOTE

When the same polling address is assigned to two or more products in the Multidrop Mode, communication with these products is disabled.

(2) Setting analog output

Usually, analog output in the Multidrop Mode is fixed at 4 mA on the product side. However, burnout output is no longer possible if analog output is fixed at 4 mA.

In the case of applications that receive and manipulate analog output, only one variable analog output can be set to variable on only one product per loop.

The analog input of the Multidrop Mode is set in method "Loop current mode" in the same method for the polling address, and can be set by the following parameters.

Menu path

HART Device Settings ► Detailed setup ► HART config ► Loop current mode*1 / Loop Current Mode*2

Select the analog output of the Multidrop Mode mode from the table below.

Selection	Description
Disabled*1 / Disable*2	Sets analog output to 4 mA (fixed).
Enabled*1 / Enable*2	Sets analog output to 4 to 20 mA (variable).

NOTE

In the Multidrop Mode, only the current value is fixed. Measured values are displayed for process values.

*1: For Device revision 1 and DD revision 1 or 2

(3) Enabling the Multidrop Mode

Refer to the User's Manual of the HART configuration tool (1R01A01-01) when setting up polling for the receiving instrument.

(4) Communicating in the Multidrop Mode

- When connection between the product and the HART configuration tool starts, the tool searches for the products set to the Multidrop Mode, and the polling address and tag are displayed.
- After the desired product is selected, normal communication with the selected products becomes possible. However, communication in the Multidrop Mode is slower.

(5) Canceling the Multidrop Mode

To cancel the Multidrop Mode, the following parameter needs to be set.

- Set the polling address of (1) to "0".
- Set the analog output of (2) to "Enabled".
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4. Functions

This chapter describes the functions of the product. The following is an overview of each function.

NOTE

This product inherits many of the parameter numbers of the A items (display items), B items (standard setting items), C items (basic setting items), D items (additional setting items), E items (sensor setting items), J items (test items), and K items (maintenance items) of the display parameter numbers that were defined on the previous product digital YEWFLO series vortex flowmeter. Note, however, that the setting method on this product differs from the setting method on the previous product. Also, new item names are defined for newly added functions. As temperature and pressure correction functions have been enhanced on this product, the names of parameter items and method of use vary considerably with display parameter number F items (temperature setting items) on the previous product.

In consideration of the above, set the parameters on this product while referring to this document.

Flow rate measurement function

Fluids that can be measured are liquid, gas, water, and steam. As measured flow rate options, volumetric flow rate, mass flow rate, Standard/Normal flow rate, heat, and heat difference can be measured.

The measured flow rate can be displayed on the display as the instantaneous flow rate, and can be output as analog output after scaling by the preset span from analog output. The flow rate unit, flow rate span, damping time constant, and lowcut function can be set for the measured flow rate. For details about how to check measured results and the setting procedure, see Section 4.1.

Totalization function

With this function, instantaneous flow rate values can be totaled. The product has a totalization switch function that compares the preset target value with the totalized value to output the result in the form of the status output. The product also has a function for resetting the totalized value and a totalization preset function for starting totalization from a preset value. For details about how to check the totalized flow rate and setting procedure, see Section 4.2.

Temperature measurement function

On a type with built-in temperature gauge, temperature can be measured by the built-in temperature gauge. This measured temperature can be displayed on the display, and used for analog output after scaling. On an analog input type, the measured temperature value can be acquired from the temperature transmitter connected to the analog input and displayed on the display.

For details about how to check the temperature measurement function and setting procedure, see Section 4.3.

Pressure measurement function

On an analog input type, the measured pressure value can be acquired from the pressure transmitter connected to the analog input. This measured pressure can be displayed on the display.

For details about how to check the pressure measurement function and setting procedure, see Section 4.4.

Density measurement function

On the analog input type, the measured density value can be acquired from the density transmitter connected to the analog input. This measured density can be displayed on the display.

For details about how to check the density measurement function and setting procedure, see Section 4.5.

Analog output function

One analog output is available. Analog output is performed after the instantaneous flow rate is scaled by 4 to 20 mA of the set span setting value. Also, the measured temperature value of the built-in temperature gauge on a type with built-in temperature gauge is output as analog output after scaling. The upper and lower limit if this analog output are restricted. For details about setting procedures for the analog output, see Section 4.6.

Analog input function

In the case of an analog input type (communication and I/O code JB) is selected, one analog input is available. Measured temperature, pressure or density values can be acquired from the temperature transmitter, pressure transmitter or density transmitter connected to the analog input.

For details about setting procedures for the analog input, see Section 4.7.

Pulse/status output function

One pulse/status output is available. One of pulse output, vortex pulse output, frequency output, alarm switch, and limit switch can be output.

Pulse output is output after the instantaneous flow rate is scaled by the set span setting value. Vortex pulse output is output after conversion of the vortex signal detected by the sensor is converted to pulses. For frequency output, the process value selected from one of the instantaneous flow rate, fluid temperature and fluid pressure is output. For alarm switch output, occurrence of alarms and warnings is notified. For limit switch output, upper and lower limit alarms for targets selected from one of instantaneous flow rate, fluid temperature, fluid pressure, and totalization are notified.

For details about setting procedures for pulse/status output, see Section 4.8.

Sensor information

Diameter, sensor type, maximum temperature, maximum pressure, and other sensor information can be checked.

For details about how to check the sensor information, see section 4.9.

Alarms

A detected error can be notified as an alarm or warning. The error status can be displayed in accordance with NAMUR NE107 matched to parameter settings. Analog output operation or display method, etc. when an alarm occurs can be selected. It is also possible to store alarms that occurred in the past as an alarm history, and mask unnecessary alarms so that they are hidden on the display.

For details about contents and setting procedures, see section 4.12.

Display functions

In the flow rate display mode, instantaneous flow rate, totalized values, and other information is displayed. In the setting mode, parameter content is displayed. When an alarm occurs, a number indicating the content of the alarm is displayed.

For details about display settings, see section 4.13.

Device information

With this function, the parameters specified at the time of order, model code, and suffix code of this product can be checked.

For details about how to check the device information, refer to Section 4.14.

Self-diagnostics

The self-diagnostics function can be used to diagnose product failures or process status. For example, this function is useful for diagnosing disconnections on the piezo electric device, diagnosing insulation deterioration, and diagnosing the health of the product by using the verification function.

For details about the self-diagnostics function, see Section 4.15.

Predictive diagnostic function

By using the predictive diagnosis mode, the maintenance timing can be predicted based on the trend of the detection signal from the piezo electric device. For details about the predictive diagnostic function, see 4.15.6.

Frequency analysis function

Product signals can be checked on FieldMate, etc. For details about the frequency analysis function, see 4.15.8.

Test/simulation function

With this function, the process value and the value output from a connection terminal can be arbitrarily set to test a response from the device. For details about the test/simulation function, refer to Section 4.16.

Write protect function

Two parameter write protect functions are available and can be changed by using the hardware write protection switch and the parameter settings (software write protection). For details about the hardware write protection switch, refer to the Startup Manual. For details about the software write protection function, see section 4.17.

NOTE

Only basic parameters required for use of this product can be set and displayed on the display. Parameters that cannot be set and displayed on the display should be set and checked using the HART configuration tool.

4.1 Flow Rate Measurement Function

NOTE

The parameters that need setting vary according to the measured fluid and measured flow rate settings.

Parameters can be set easily by executing HART communication method functions.

4.1.1 Setting the measured fluid

Fluids that can be measured are liquid, gas, water, and steam. When the measured fluid is water and the Fluid type of this parameter is set to Water, temperature and pressure correction of the mass flow rate and heat are performed based on steam table. Set the measured fluid by the following parameters.

Menu path

HART	Device Settings ► Basic setup ► Fluid type
Display	C15

Selection		Description	
HART	Display	Description	
Liquid	0	Liquid is set as the measured fluid	
Gas	1	Gas is set as the measured fluid	
Water	2	Water is set as the measured fluid	
Steam	3	Steam is set as the measured fluid	

NOTE

When Water is set as the measured fluid, flow rate calculation of water is performed based on the steam table. Just as on the previous product digital YEWFLO series vortex flowmeter, when performing flow rate measurement of water, set Liquid as the measured fluid.

NOTE

Use the Dryness setting fixed at 100 %.

4.1.2 Setting the Measured Flow Rate

As measured flow rate options, volumetric flow rate, mass flow rate, Standard/Normal flow rate, heat, and heat difference can be measured.

Set the measured flow rate by the following parameters.

Menu path

HART	Device Settings ► Basic setup ► Flow select
Display	C16

Selection		Description	
HART	Display	Description	
Volume	0	Volumetric flow rate: This refers to the volume of fluid that flows through the measuring pipe per unit hour.	
Mass	1	Mass flow rate: This refers to the mass of fluid that flows through the measuring pipe per unit hour. Mass is the value obtained by multiplying the volumetric flow rate by the fluid density.	
Standard/Normal	2	Standard/Normal flow rate: This refers to the volume of the fluid in a standard or normal state that flows through the measuring pipe per unit hour.	
Energy	3	Heat: This refers to the heat of the fluid that flows through the measuring pipe per unit hour. When the measured fluid is water or steam, this is the value obtained by multiplying the mass flow rate by the fluid specific enthalpy that is calculated according to IAPWS-IF97: IAPWS Industrial Formulation 1997.	
Energy (Heat difference)	4	Heat difference: This refers to the heat difference of the fluid that flows through the measuring pipe per unit hour, and that uses the temperature difference between the upstream and downstream. When the measured fluid is water or steam, this is the value obtained by multiplying the mass flow rate by the difference in fluid specific enthalpy that is calculated according to IAPWS-IF97: IAPWS Industrial Formulation 1997. When the measured fluid is a liquid, this is the value obtained by multiplying the volumetric flow rate or mass flow rate by heat difference and heat conversion factor.	

4.1.3 Setting the Instantaneous Flow Rate Unit

Set the unit of volumetric flow rate, mass flow rate, Standard/Normal flow rate, heat, and heat difference. The unit of each flow rate can be set as a physical unit and a time unit. Note, however, that the set time unit is common to all flow rates.

Example) When the volumetric flow rate is set to "m³/h" Set the volume unit to "m³" and the time unit to "/h". At this setting, the time unit of mass flow rate, Standard/Normal flow rate, heat, and heat difference also becomes "/h".

This setting can be set by the following parameters.

Physical unit

Volumetric flow rate

Menu path

HART	Device Settings ► Basic setup ► Volume unit
Display	C22

Selection		
HART	Display	
m ³	0	
km ³	1	
1	2	
mcf	3	
cf	4	
kcf	5	
USgal	6	
kUSgal	7	
UKgal	8	
kUKgal	9	
mbbl	10	
bbl	11	
kbbl	12	

NOTE

The unit display will be the same (gal) if either USgal or UKgal is selected for the volumetric flow rate unit, and then the instantaneous flow rate (engineering unit) is displayed on the display.

Mass flow rate

HART	Device Settings ► Basic setup ► Mass unit
Display	C27

Selection		
HART Display		
kg	0	
t	1	
lb	2	
klb	3	

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• Standard/Normal flow rate

Menu path

HART	Device Settings ► Basic setup ► Standard/Normal unit
Display	C37

Selection		
HART	Display	
(N)m ³	0	
k(N)m ³	1	
M(N)m ³	2	
(N)I	3	
(S)m ³	4	
k(S)m ³	5	
M(S)m ³	6	
(S)I	7	
(S)cf	8	
k(S)cf	9	
M(S)cf	10	

• Heat/heat difference

Menu path

HART	Device Settings ► Basic setup ► Energy unit
Display	C38

Selection		
HART	Display	
kJ	0	
MJ	1	
GJ	2	
TJ	3	
BTU	4	
kBTU	5	
MBTU	6	

Time unit

HART	Device Settings ► Basic setup ► Time unit
Display	C40

Sele	ction	Description	
HART Display		Description	
/s	0	The time unit is set to s (seconds)	
/min	1	The time unit is set to min (minutes)	
/h	2	The time unit is set to h (hours)	
/d	3	The time unit is set to d (days)	

• Checking the measurement unit

The preset measurement unit can be checked by the following parameters.

•	
HART	Device Settings ► Basic setup ► Flow unit
Display	C41

HART	Display	HART Display		HART	Display
m³/s	0	bbl/d	47	M(S)m³/h	94
m³/min	1	kbbl/s 48 M(S)m³/d		95	
m³/h	2	kbbl/min	49	(S)l/s	96
m³/d	3	kbbl/h	50	(S)l/min	97
km³/s	4	kbbl/d	51	(S)l/h	98
km³/min	5	kq/s	52	(S)I/d	99
km³/h	6	kg/min	53	(S)cf/s	100
km³/d	7	kg/h	54	(S)cf/min	101
l/s	8	ka/d	55	(S)cf/h	102
l/min	9	t/s	56	(S)cf/d	103
l/h	10	t/min	57	k(S)cf/s	104
l/d	11	t/h	58	k(S)cf/min	105
mcf/s	12	t/d	59	k(S)cf/h	106
mcf/min	13	lb/s	60	k(S)cf/d	107
mcf/h	14	lb/min	61	M(S)cf/s	108
mcf/d	15	lb/h	62	M(S)cf/min	109
cf/s	16	lb/d	63	M(S)cf/h	110
cf/min	17	klb/s	64	M(S)cf/d	111
cf/h	18	klb/min	65	kJ/s	112
cf/d	19	klb/h	66	kJ/min	113
kcf/s	20	klb/d	67	kJ/h	114
kcf/min	21	(N)m ³ /s	68	kJ/d	115
kcf/h	22	(N)m ³ /min	69	MJ/s	116
kcf/d	23	(N)m ³ /h	70	MJ/min	117
USgal/s	24	(N)m ³ /d	71	MJ/h	118
USgal/min	25	k(N)m³/s	72	MJ/d	119
USgal/h	26	k(N)m ³ /min	73	GJ/s	120
USgal/d	27	k(N)m ³ /h	74	GJ/min	121
kUSgal/s	28	k(N)m³/d	75	GJ/h	122
kUSgal/min	29	M(N)m ³ /s	76	GJ/d	123
kUSgal/h	30	M(N)m ³ /min	77	TJ/s	124
kUSgal/d	31	M(N)m ³ /h	78	TJ/min	125
UKgal/s	32	M(N)m ³ /d	79	TJ/h	126
UKgal/min	33	(N)l/s	80	TJ/d	127
UKgal/h	34	(N)l/min	81	BTU/s	128
UKgal/d	35	(N)l/h	82	BTU/min	129
kUKgal/s	36	(N)l/d	83	BTU/h	130
kUKgal/min	37	(S)m³/s	84	BTU/d	131
kUKgal/h	38	(S)m³/min	85	kBTU/s	132
kUKgal/d	39	(S)m³/h	86	kBTU/min	133
mbbl/s	40	(S)m³/d	87	kBTU/h	134
mbbl/min	41	k(S)m³/s	88	kBTU/d	135
mbbl/h	42	k(S)m³/min	89	MBTU/s	136
mbbl/d	43	k(S)m³/h	90	MBTU/min	137
bbl/s	44	k(S)m³/d	91	MBTU/h	138
bbl/min	45	M(S)m ³ /s	92	MBTU/d	139
bbl/h	46	M(S)m³/min	93	SPE.	140

4.1.4 Setting the Span of the Instantaneous Flow Rate

The span of volumetric flow rate, mass flow rate, Standard/Normal flow rate, heat, and heat difference can be set.

Note, however, that the span unit is the unit set in section 4.1.3. When the unit has been changed, the span value is converted interlocked with the newly set unit. This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Basic setup ► Flow span
Display	B10 or C45

• Measurable minimum flow velocity

The minimum flow velocity of each size varies according to the density of the fluid. Table 4.1 shows this relationship. Check the minimum flow velocity by size in the latest version of the sizing program. The volumetric flow rate that calculation is based on is restricted by the values in Table 4.1 when the flow rate is heat and heat difference, too.

Table 4.1Relationship Between Minimum Velocity and Density (when two values are indicated, the
larger one is the minimum velocity)

Model code - Type of body			Liquid		Gas, Steam	
Model code - Type of body			Type of shedder bar			
-0: General	-1: Reduced bore type (1 size reduction) -2: Reduced bo		A, B, N, P: General type E, S: Cryogenic	C, D, Q, R: High	A, B, N, P: General type E, S: Cryogenic	C, D, Q, R: High
type	-4: High pressure reduced bore type (1 size reduction)	type (2 size reduction)	type (*1) G, H, U, V: Long Neck Type	temperature type (*1)	type (*1) G, H, U, V: Long Neck Type	temperature type (*1)
VY015-0	VY025-1	VY040-2	1250/0	_	$\sqrt{80/0}$ or 3	
	VY025-4	V1040 2	1230/p	-	400/p 01 3	-
VY025-0	VY040-1	VY050-2	√122.5/ρ	√490/ρ	√45/ρ or 2	√125/p or 2
1020-0	VY040-4	V1030-2				
VY040-0	VY050-1	VY080-2	√90/ρ	√302.5/0	√31.3/p or 2	√90.3/p or 2
	VY050-4	V1000 2		1002.0/p		
VY050-0	VY080-1	VY100-2	V90/0	<u>√160/o</u>	$\sqrt{31.3/0}$ or 2	$\sqrt{61.3/0}$ or 2
	VY080-4	1100 2	490/p	-100/p	401.5/p 012	401.5/p 012
1/2080-0	VY100-1	VY150-2	V90/0	√ <u>160/o</u>	$\sqrt{31.3/0}$ or 2	$\sqrt{61.3/0}$ or 2
V1000-0	VY100-4	V1130-2	, 90/p	, 100/p	401.5/p 012	401.5/p 012
VY100-0	VY150-1	VY200-2	V90/0	√160/ρ	√31.3/p or 2	√61.3/p or 2
11000	VY150-4	V1200 2	400/p			
VY150-0	VY200-1	-	√90/ρ	√160/ρ	√31.3/ρ or 3	√61.3/ρ or 3
VY200-0	-	-	√122.5/ρ	√202.5/p	√45/ρ or 3	√80/p or 3
VY250-0	-	-	√160/ρ	√ 360/ρ	√61.3/ρ or 3	√125/p or 3
VY300-0	-	-	√160/ρ	√360/ρ	√61.3/ρ or 3	√125/p or 3
VY400-0	-0		√250/p	√490/ρ	√80/p or 4	√125/p or 4

ρ: Density at operating conditions (kg/m³)

For liquid: 400 to 2000 kg/m³

For gas and steam: 0.5 kg/m³ or more

*1: The high pressure reduced bore type body cannot be combined with a high temperature type or cryogenic type shedder bar.

(Unit: m/s)

Measurable flow velocity

Table 4.2 shows the ranges of the measurable flow velocities.

		Model code - Type of			
Fluid	-0: General type-1: Reduced bore typetypetype-6: Dual- Sensor(1 size reduction)General Type-4: High pressure reduced bore type-2: Reduced bore type(2 size reduction)		-2: Reduced	Minimum flow velocity	Maximum
			,	velocity	
Liquid	VY015-0 to VY400-0 VY015-6 to VY200-6	VY025-1 to VY200-1 VY025-4 to VY150-4	VY040-2 to VY200-2	"Flow velocity obtained from Table 4.1" or "flow velocity at Reynolds number of 5000", whichever is greater.	10 m/s (*1)
Gas Steam	VY015-0 to VY400-0 VY015-6 to VY200-6	VY025-1 to VY200-1 VY025-4 to VY150-4	VY040-2 to VY200-2	"Flow velocity obtained from Table 4.1" or "flow velocity at Reynolds number of 5000", whichever is greater.	80m/s (*2)

Table 4.2	Range of Measurable Flow	Velocities
	Italige of measurable i low	Velocities

When the flow velocity is lower than the minimum, both the analog output and the pulse output are displayed as "0".

Maximum possible value for span setting:

For liquid, a flow rate up to the equivalent of a flow velocity of 15 m/s can be set.

For gas or steam, a flow rate up to the equivalent of a flow velocity of 120 m/s can be set.

When density $\rho > 1000 \text{ kg/m}^3$, maximum flow velocity $V = \sqrt{[(1/\rho) * 10^5]}$ When density $\rho > 15.6 \text{ kg/m}^3$, maximum flow velocity $V = \sqrt{[(1/\rho) * 10^5]}$ *1:

*2:

*3: Formula for calculating flow velocity calculated from Reynolds number

$$u = 5 \times \frac{V}{D}$$
(Re=5000)

where

$$Re = \frac{354 \times 10^3 \times Q_f}{v \times D}$$
$$v = \frac{\mu \times 10^3}{\rho_f}$$

Q.: Volumetric flow rate at operating conditions (m³/h)

D: Inner diameter of sensor section (mm)

u: Flow velocity (m/s)

Re: Reynolds number (non unit)

ρ_r: Density at operating conditions (kg/m³)

μ: Viscosity at operating conditions (mPa·s)

v: Kinematic viscosity at operating conditions (10-6 m²/s)

NOTE

Set the flow rate span while paying attention to the following points.

- On lines with large changes in flow rate, set the maximum flow rate as the flow rate span. When a flow rate exceeding the flow rate span flows on the line, the error of flow rate (%) increases.
- On lines with a stable flow rate, as a guideline, set a flow rate approximately 1.5x to 2x the regular flow rate as the flow rate span.

NOTE

When the flow rate unit and span value are changed at the same time, be sure to change the flow rate unit first.

Setting the Damping Time Constant of the 4.1.5 Instantaneous Flow Rate

The damping time constant (63.2% response) of volumetric flow rate, mass flow rate, Standard/ Normal flow rate, heat, and heat difference can be set. Change the damping time constant, for example, to suppress output oscillation or to alter the response speed (default 4.0 seconds).

This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Basic setup ► Flow damping
Display	B15 or C50

NOTE

When using the HART communication in such application that the output varies very quickly, set the damping time constant as 2 sec or greater.

4.1.6 Setting the Lowcut Function of Instantaneous Flow Rate

This function intentionally sets the low-flowrate range to zero based on the setting value of this parameter for the purpose of removing noise. The lowcut value of volumetric flow rate, mass flow rate, Standard/Normal flow rate, heat, and heat difference can be set. Use of the lowcut function can disable output of the flow rate at the setting value or below. The lower limit value that can be set is the flow rate equivalent to the flow velocities in the table below.

This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Flow rate ► Flow lowcut
Display	D10

Model code - Type of body			Liquid	Gas, Steam	
	-1: Reduced bore type (1 size reduction)	-2: Reduced bore type (2 size reduction)	Unit: m/s	Unit: m/s	
-0: General type	-4: High pressure reduced bore type (1 size reduction)				
10015.0	VY025-1	10/040.2	0.47	4.50	
VY015-0	VY025-4	V 1040-2	0.17	1.50	
10025.0	VY040-1		0.10	1.00	
V 1025-0	VY040-4	V 1050-2	0.12	1.00	
10040.0	VY050-1	VY080-2	0.10	1.00	
V1040-0	VY050-4				
VX050-0	VY080-1	VY100-2	0.10	1.00	
V1030-0	VY080-4		0.10	1.00	
1/2080-0	VY100-1	VX150.2 0.10	1.00		
V 1000-0	VY100-4	VT 150-2	0.10	1.00	
10/100.0	VY150-1	10/200.2	0.40	4.00	
V 1100-0	VY150-4	V f 200-2	0.10	1.00	
VY150-0	VY200-1	-	0.10	1.50	
VY200-0	-	-	0.12	1.50	
VY250-0	-	-	0.14	1.50	
VY300-0	-	-	0.14	1.50	
VY400-0	-	-	0.17	2.00	

Table 4.3 Lowcut setting lower limit flow velocity (m/s)

NOTE

Be sure to set the lowcut value (D10) of the instantaneous flow rate after setting the diameter type (E10).

NOTE

To change the lowcut flow rate and adjust items (H item), change all applicable adjust items (H items), and then set the lowcut value (D10).

NOTE

You can check the lower limit of the lowcut flow rate in Device Settings ► Detailed setup ► Flow rate ► Lowcut limit.

4.1.7 Setting the User Unit Conversion of the Instantaneous Flow Rate

The instantaneous flow rate can be converted to an arbitrary unit for use by using an arbitrary conversion factor. Any character string up to eight characters long can be set for the user unit. Conversion to a user unit is performed by multiplying the instantaneous volumetric flow rate by the conversion factor.

This setting can be set by the following parameters or execute User unit.

Selection of whether or not to convert to user units

Menu path

HART	Device Sattings Detailed sature Elow user conversion Elow user conversion
	Device detailings > Detailed setup > 1 low dset conversion > 1 low dset conversion
Display	D40

Sele	ction	Description
HART	Display	Description
Off	0	Conversion to user units is not performed.
On	1	Conversion to user units is performed.

Display the flow rate unit used for the conversion reference

Display the flow rate unit (Flow user base unit) that is used for the conversion reference when Flow user conversion (D40) is "On".

HART	Device Settings ► Detailed setup ► Flow user conversion ► Flow user base unit
Display	D41

Selection									
HART	Display	HART	Display	HART	Display	HART	Display	HART	Display
m³/s	0	kUSgal/s	28	t/s	56	(S)m³/s	84	kJ/s	112
m³/min	1	kUSgal/min	29	t/min	57	(S)m³/min	85	kJ/min	113
m³/h	2	kUSgal/h	30	t/h	58	(S)m³/h	86	kJ/h	114
m³/d	3	kUSgal/d	31	t/d	59	(S)m³/d	87	kJ/d	115
km ³ /s	4	UKgal/s	32	lb/s	60	k(S)m³/s	88	MJ/s	116
km³/min	5	UKgal/min	33	lb/min	61	k(S)m³/min	89	MJ/min	117
km³/h	6	UKgal/h	34	lb/h	62	k(S)m³/h	90	MJ/h	118
km³/d	7	UKgal/d	35	lb/d	63	k(S)m³/d	91	MJ/d	119
l/s	8	kUKgal/s	36	klb/s	64	M(S)m ³ /s	92	GJ/s	120
l/min	9	kUKgal/min	37	klb/min	65	M(S)m ³ /min	93	GJ/min	121
l/h	10	kUKgal/h	38	klb/h	66	M(S)m ³ /h	94	GJ/h	122
l/d	11	kUKgal/d	39	klb/d	67	M(S)m ³ /d	95	GJ/d	123
mcf/s	12	mbbl/s	40	(N)m ³ /s	68	(S)l/s	96	TJ/s	124
mcf/min	13	mbbl/min	41	(N)m ³ /min	69	(S)l/min	97	TJ/min	125
mcf/h	14	mbbl/h	42	(N)m ³ /h	70	(S)l/h	98	TJ/h	126
mcf/d	15	mbbl/d	43	(N)m³/d	71	(S)l/d	99	TJ/d	127
cf/s	16	bbl/s	44	k(N)m³/s	72	(S)cf/s	100	BTU/s	128
cf/min	17	bbl/min	45	k(N)m ³ /min	73	(S)cf/min	101	BTU/min	129
cf/h	18	bbl/h	46	k(N)m³/h	74	(S)cf/h	102	BTU/h	130
cf/d	19	bbl/d	47	k(N)m³/d	75	(S)cf/d	103	BTU/d	131
kcf/s	20	kbbl/s	48	M(N)m³/s	76	k(S)cf/s	104	kBTU/s	132
kcf/min	21	kbbl/min	49	M(N)m ³ /min	77	k(S)cf/min	105	kBTU/min	133
kcf/h	22	kbbl/h	50	M(N)m ³ /h	78	k(S)cf/h	106	kBTU/h	134
kcf/d	23	kbbl/d	51	M(N)m³/d	79	k(S)cf/d	107	kBTU/d	135
USgal/s	24	kg/s	52	(N)l/s	80	M(S)cf/s	108	MBTU/s	136
USgal/min	25	kg/min	53	(N)l/min	81	M(S)cf/min	109	MBTU/min	137
USgal/h	26	kg/h	54	(N)l/h	82	M(S)cf/h	110	MBTU/h	138
USgal/d	27	kg/d	55	(N)l/d	83	M(S)cf/d	111	MBTU/d	139

Setting the name of the user-specified unit

Set the name of the user-specified unit using eight characters and symbols when Flow user conversion (D40) is "On".

The same characters and symbols as in Section 3.3 Basic settings can be set.

Menu path

HART	Device Settings ► Detailed setup ► Flow user conversion ► Flow user unit
Display	-

Setting the user conversion factor

Set the conversion factor to user units when Flow user conversion (D40) is "On". The conversion factor is calculated/multiplicated to the parameters such as the instantaneous flow rate as follows:

Flow user unit = Flow user base unit × Flow conversion factor

Menu path

HART	Device Settings ► Detailed setup ► Flow user conversion ► Flow conversion factor
Display	D43

Example:

To convert the unit of instantaneous volumetric flow rate from I (liters)/s to dI (deciliters)/s, set the parameters as follows:

Flow user conversion = "On" Flow user base unit = "I/s" Flow user unit = "dI/s" Flow conversion factor = "10"

Applicable parameters for instantaneous flow rate user unit conversion

Applicable parameters for instantaneous flow rate user unit conversion are listed below.

Flow rate	Totalizer preset value
Flow span	Totalizer rate
Flow lowcut	Pulse output rate ^{*1}
Lowcut limit	Limit switch level ^{*2}
Total	Limit switch hysteresis ^{*2}

*1: This parameter will be applicable only when Pulse/Status output mode = "Scaled pulse".

*2: These parameters will be applicable only when Limit switch select = "Flow rate" or "Total".

NOTE

If the software revision is R1.01.01, the pulse rate (Pulse output rate) is not multiplied by the user conversion factor, and user unit conversion is not applied.

Example:

With Flow user base unit = "l/s" and Pulse output rate = "5[l/p]", if Flow user conversion = "On", Flow user unit = "dl/s", and Flow conversion factor = "10", the pulse output rate will not be displayed/operated at $5[l/p] \times 10 = 50[SPE./p]$. Instead, the pulse output rate will be displayed as 5[SPE./p], and pulse output will operate with a weight of 5[l/p].

The user conversion factor (Flow conversion factor) will not be applied to the pulse output rate, and only the display unit will change. Therefore, replace "SPE." from the pulse output rate display unit ("SPE./p") with the unit from the flow user base unit (with the time unit removed).

4.1.8 Basic Settings of Compensation in the Flow Rate Measurement Function

Mass flow rate refers to the mass of fluid that flows through the measuring pipe per unit hour, and is the value obtained by multiplying the volumetric flow rate by the fluid density.

Standard/Normal flow rate refers to the volume of the fluid in a standard or normal state that flows through the measuring pipe per unit hour when the measured fluid is a gas, and is the value obtained by multiplying the volumetric flow rate by the gas density ratio. Gas density ratio is the value obtained by dividing the fluid density calculated based on the temperature and pressure presently being measured by density in a standard or normal state.

Heat is the heat of fluid that flows through the measuring pipe per unit hour, and, when the measured fluid is water or steam, this is the value obtained by multiplying the mass flow rate by the fluid specific enthalpy that is calculated according to IAPWS-IF97: IAPWS Industrial Formulation 1997.

Heat difference refers to the heat of the fluid that flows through the measuring pipe per unit hour, and that uses the temperature difference between the upstream and downstream, and, when the measured fluid is water or steam, this is the value obtained by multiplying the mass flow rate by the difference in fluid specific enthalpy that is calculated according to IAPWS-IF97: IAPWS Industrial Formulation 1997. When the measured fluid is a liquid, this is the value obtained by multiplying the volumetric flow rate or mass flow rate by heat difference and heat conversion factor.

The density, pressure and temperature parameters must be set to these flow rate measurements.

Density basic setting

Density unit

Set the density unit by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Density unit
Display	C25 or F11

Selection			
HART	Display		
kg/m ³	0		
lb/cf	1		
lb/USgal	2		
lb/UKgal	3		

Fixed density

The setting value of this parameter is used when calculating the mass flow rate, heat and heat difference by fixed density. Set the fixed density by the following parameters.

HART	Device Settings ► Detailed setup ► Compensation setup ► Fixed Density
Display	C26 or F12 or H26

Density of normal condition

The density of normal condition is set by the following parameters when the measured fluid (Fluid type) is a liquid other than water and mass flow rate and heat difference are selected for the measured flow rate (Flow select), and when the measured fluid (Fluid type) is gas and mass flow rate and Standard/Normal flow rate are selected for the measured flow rate (Flow select). Furthermore, when Standard/Normal flow rate is selected, density is set as the density value of a normal condition (1 atm, 0°C) or the density value of a standard condition (1 atm, 15°C, etc.) according to that selected unit.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Base density
Display	F13

Temperature basic setting

Temperature unit

Set the temperature unit by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Temperature unit
Display	C30 or F14

Selection			
Display			
0			
1			
2			

Fixed temperature

The setting value of this parameter is used when calculating the mass flow rate, Standard/Normal flow rate and heat by fixed density. Set the fixed temperature by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Fixed temperature
Display	C31 or F15

Temperature of normal/standard condition

The temperature of normal condition is set by the following parameters when the measured fluid (Fluid type) is a liquid other than water and mass flow rate and heat difference are selected for the measured flow rate (Flow select), and when the measured fluid (Fluid type) is gas and mass flow rate and Standard/Normal flow rate are selected for the measured flow rate (Flow select). Furthermore, when Standard/Normal flow rate is selected, temperature is set as the temperature value of a normal condition (1 atm, 0°C) or the temperature value of a standard condition (1 atm, 15° C, etc.) according to that selected unit.

HART	Device Settings ► Detailed setup ► Compensation setup ► Base temperature
Display	C32 or F16

Pressure basic setting

Pressure unit

Set the pressure unit by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Pressure unit
Display	C33 or F17

Selection		Description
HART	Display	Description
kPa A	0	The unit is set to absolute pressure kPa
MPa A	1	The unit is set to absolute pressure MPa
bar A	2	The unit is set to absolute pressure bar
psi A	3	The unit is set to absolute pressure psi
kPa G	4	The unit is set to gauge pressure kPa
MPa G	5	The unit is set to gauge pressure MPa
bar G	6	The unit is set to gauge pressure bar
psi G	7	The unit is set to gauge pressure psi

Fixed pressure

The setting value of this parameter is used when the measured fluid (Fluid type) is gas or steam, and when calculating the mass flow rate, Standard/Normal flow rate and heat by fixed density. Set the fixed pressure by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Fixed Pressure
Display	C34 or F18

Pressure of normal/standard condition

The pressure of normal condition is set by the following parameters when the measured fluid (Fluid type) is gas and mass flow rate and Standard/Normal flow rate are selected for the measured flow rate (Flow select). Furthermore, when Standard/Normal flow rate is selected, pressure is set as the pressure value of a normal condition (1 atm, 0°C) or the pressure value of a standard condition (1 atm, 15°C, etc.) according to that selected unit.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Base Pressure
Display	C35 or F19

NOTE

If the software revision is R1.01.01 or R1.01.02, Fixed pressure and Base Pressure cannot be set to minus gauge pressure value, when Pressure unit is set to gauge pressure unit. Follow the steps below to set to minus gauge pressure value.

For Device revision 1 and DD revision 1 or 2

Please set each parameter in the following steps.

- (1) Set absolute pressure unit(kPa A, MPa A, bar A, psi A) to Pressure unit
- (2) Set the value coverted to absolute pressure to Fixed pressure or Base pressure
- (3) Set gauge pressure unit(kPa G, MPa G, bar G, psi G) to Pressure unit
- For Device revision 1 and DD revision 3 or more

Please use Flow rate config method or Pressure detailed config method to set each parameter. The method processing automatically performs the above steps.

Basic settings of specific enthalpy

• Specific enthalpy unit

Set the specific enthalpy unit by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Enthalpy unit
Display	F35

Selection		
HART	Display	
kJ/kg	0	
MJ/kg	1	
GJ/kg	2	
TJ/kg	3	
BTU/lb	4	

Fixed specific enthalpy

The setting value of this parameter is used when calculating the heat by fixed specific enthalpy. Set the fixed specific enthalpy by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Fixed enthalpy
Display	F36

Setting the temperature correction and pressure correction of fluid density and the specific enthalpy

Temperature correction and pressure correction can be performed on fluid density and specific enthalpy by using the temperature measurement function in Section 4.3 and the pressure measurement function in Section 4.4.

Selection of steam type

Select the steam type when the measured fluid is steam. Perform mass flow rate calculation or heat flow rate calculation while referring to the steam table.

HART	Device Settings ► Detailed setup ► Compensation setup ► Steam type
Display	F01

Selection		Description
HART	Display	Description
Saturated steam	0	Saturated steam
Superheated steam	1	Superheated steam

• Selection of compensation type

Set the measurement value to be used when performing temperature correction and pressure correction. For details on the temperature measurement function, see Section 4.3, for the pressure measurement function, see Section 4.4, and for the density measurement function, see Section 4.5.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Compensation type
Display	F03

Selection		Description
HART	Display	Description
Not used	0	Flow rate calculation based on fixed temperature, fixed pressure and fixed specific enthalpy is performed. Temperature correction and pressure correction are not performed.
Built-in temp.	1	Temperature correction based on the built-in temperature gauge is performed.
Built-in temp. & A-in press.	2	Temperature correction based on the built-in temperature gauge and pressure correction based on pressure measured by analog input are performed.
A-in temp	4	Temperature correction based on temperature measured by analog input is performed.
A-in press.	5	Pressure correction based on pressure measured by analog input is performed.
A-in density	6	Density correction based on density measured by analog input is performed.

• Checking the compensation method of density and specific enthalpy

The compensation method of density and enthalpy can be checked.

HART	Device Settings ► Detailed setup ► Compensation setup ► Calculation type
Display	-

Selection		Description	
HART	Display	Description	
Fixed	-	Flow rate calculation based on fixed temperature, fixed pressure, fixed density, and fixed specific enthalpy is performed. Temperature correction and pressure correction are not performed.	
Analog input	-	The density measured value of analog input is used when the measured fluid is liquid or gas, and the measured flow rate is mass flow rate or Standard/Normal flow rate.	
Compensation T	-	Temperature correction of density is performed according to measured temperature when the measured fluid is liquid and the measured flow rate is mass flow rate and heat difference or when the measured fluid is water and the measured flow rate is mass flow rate, heat and heat difference.	
Compensation T/P	-	Temperature correction and pressure correction of density are performed according to measured temperature and measured pressure when the measured fluid is gas, and the measured flow rate is mass flow rate or Standard/ Normal flow rate.	
Saturated steam T -		When the measured fluid is saturated steam and water, density and specific enthalpy are calculated based on the measured temperature by using the built-in saturated steam table to calculate the mass flow rate and heat flow rate.	

Selection		Description	
HART	Display	Description	
Saturated steam P	-	When the measured fluid is saturated steam, density and specific enthalpy are calculated based on the measured pressure by using the built-in saturated steam table to calculate the mass flow rate and heat flow rate.	
Superheated steam T/P	-	When the measured fluid is superheated steam, density and specific enthalpy are calculated based on the measured temperature and measured pressure by using the built-in superheated saturated steam table to calculate the mass flow rate and heat flow rate.	

Setting the deviation factor when the measured fluid is a gas and the measured flow rate is mass flow rate or Standard/Normal flow rate

Set the deviation factor (ratio) for the density of the normal/standard condition. Set that ratio when the density of the normal/standard condition is different.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Deviation
Display	C36 or F23

Basic settings when the measured flow rate is the heat difference

When the measured flow rate is heat difference, the fluid temperature at two measurement points is required. Set the measurement points. When the measured fluid is liquid, set the heat conversion factor.

Selection of method of use of the temperature

Select the method of use of the fluid temperature at two measurement points.

Menu path

 HART
 Device Settings ► Detailed setup ► Compensation setup ► Heat difference select

 Display
 F37

Selection		Description
HART	Display	Description
Built-in(H)/Analog input(L)	0	The built-in temperature gauge is used as the fluid temperature value on the high-temperature side and analog input is used as the fluid temperature value on the low-temperature side.
Analog input(H)/Built-in(L)	1	Analog input is used as the fluid temperature value on the high-temperature side and the built-in temperature gauge is used as the fluid temperature value on the low-temperature side.
Analog input(delta T)	2	When the measured fluid is liquid, analog input is used as the temperature difference value.

NOTE

A value smaller than "0" cannot be output as the heat difference. When the output value will be smaller than "0", change the method of use of the temperature.

• Selection of the unit of heat conversion factor

Select the unit of heat conversion factor when the measured fluid is liquid.

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► Heat difference conv unit
Display	F38

Selection		
HART	Display	
(kJ/kg)/K	0	
(MJ/m ³)/K	1	
(BTU/cf)/degF	2	
(BTU/USgal)/degF	3	
(BTU/UKgal)/degF	4	
(BTU/lb)/degF	5	

• Setting the heat conversion factor

Set the heat conversion factor when the measured fluid is liquid.

HART	Device Settings ► Detailed setup ► Compensation setup ► Heat difference conv factor
Display	F39

4.1.9 Checking the Density and Specific Enthalpy Used for Flow Rate Measurement

The result of measurement and density, specific enthalpy and other data used for flow rate measurement can be checked by the following parameters.

Menu path

HART	Process Variables ► Device variable ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Flow rate(%)	A10	The instantaneous flow rate (value converted to %) is displayed
Flow rate	A20	The instantaneous flow rate is displayed at the preset unit
Total	A30	The totalized flow rate is displayed For details on the totalization function, see Section 4.2
Temperature(%)	A40	The temperature (value converted to %) is displayed
Temperature	A41	The temperature is displayed at the preset unit
Loop current	-	The Loop current(mA) is displayed

Menu path

HART	Device Settings ► Detailed setup ► Compensation setup ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Density	F40 or K38	The density is displayed at the preset unit
Density ratio	F41	The density ratio used for Standard/Normal flow rate measurement is displayed
Enthalpy	F42	The specific enthalpy used for heat measurement is displayed at the set unit
Delta temperature	F43	The temperature difference used for heat difference measurement is displayed at the set unit when the measured fluid is liquid
Delta enthalpy	F44	The specific enthalpy difference used for heat difference measurement is displayed at the set unit when the measured fluid is steam or water

NOTE

Use the Dryness setting fixed at 100 %.

4.2 Totalization Function

With this function, instantaneous flow rate values can be totaled. Totalization of the instantaneous flow rate is performed by the unit set for the flow rate that is specified for the measured flow rate (Flow select). The product has a totalization switch function that compares the preset target value with the totalized value to output the result in the form of the status output. The product also has a function for resetting the totalized value and a totalization preset function for starting totalization from a preset value.

4.2.1 Checking the Totalization Unit

The preset unit can be checked by the following parameters. The measurement unit corresponding to the flow rate specified for the measured flow rate is displayed.

Menu path

HART	Device Settings ► Easy setup ► Totalizer unit
Display	B41

Selection							
HART	Display	HART	Display	HART	Display	HART	Display
m ³	0	kUKgal	9	k(N)m ³	18	M(S)cf	27
km ³	1	mbbl	10	M(N)m ³	19	kJ	28
1	2	bbl	11	(N)I	20	MJ	29
mcf	3	kbbl	12	(S)m ³	21	GJ	30
cf	4	kg	13	k(S)m ³	22	TJ	31
kcf	5	t	14	M(S)m ³	23	BTU	32
USgal	6	lb	15	(S)I	24	kBTU	33
kUSgal	7	klb	16	(S)cf	25	MBTU	34
UKgal	8	(N)m ³	17	k(S)cf	26	SPE.	35

4.2.2 Setting Start/Stop of the Totalization Function

Set start/stop of the totalization function by the following parameters.

Menu path

```
      HART
      Device Settings ► Easy setup ► Totalizer start/stop

      Display
      B40
```

Selection		Description	
HART	Display	Description	
Stop	0	The totalization function is stopped	
Start	1	The totalization function is started	

4.2.3 Reset/Preset Function for Totalized Values

Set the reset/preset function for totalized values by the following parameters. When reset is set, the totalized value is reset to "0". When preset is set, the preset value (Totalizer preset value) is set to the totalized value.

Setting reset/preset

Menu path

HART	Device Settings ► Easy setup ► Totalizer reset/preset(method)
Display	B47

Selection		Description
HART Display		
Not execute	0	The totalized value reset/preset function is not executed.
Reset	1	The totalized value is reset and "0" is set.
Preset	2	The totalized value is preset, and the preset value (Totalizer preset value) is set.

NOTE

Parameters are returned to "Not execute" after the totalized value reset/preset function is used.

NOTE

When totalized value preset is used, be sure to set both Totalizer rate (B45) and Totalizer preset value (B48) first.

Setting the preset value

The preset value for the totalized value of the instantaneous flow rate can be set by the following parameters.

Menu path

HART	Device Settings ► Easy setup ► Totalizer preset value
Display	B48

4.2.4 Setting the Total Rate of the Totalization Function

An arbitrary factor can be set to the totalized value of the instantaneous flow rate by the following parameters.

HART	Device Settings ► Easy setup ► Totalizer rate
Display	B45

NOTE

The totalized value that is displayed on the display acts differently according to the preset value. • When the Totalizer rate value is one of 0.00001, 0.0001, 0.001, 0.01, 0.1, 1, 10, 100, or 1000 The totalized value with unit appended is displayed.

• Other than the above

The totalized value is displayed as the count value of the preset Totalizer rate.

4.2.5 Setting the Totalization Operation of the Totalization Function

Set operation when the totalized value on the display exceeds 999999 by the following parameters.

Menu path

HART	Device Settings ► Easy setup ► Totalizer reset mode
Display	B49

Selection		Description
HART Display		
Reset	0	Divide the totalized value by 1000000 and use the remainder for the new totalized value. ^{*1} Totalization is continued.
Hold only display	1	Only the totalized value on the display is fixed (held). Totalization of A30: Total is continued.
Hold	2	The totalized value is is fixed (held).

*1: This operation is performed even when the Totalization function is stopped.

4.3 Temperature Measurement Function

4.3.1 Checking the Temperature Measurement Method

On a type with built-in temperature gauge, temperature can be measured by the built-in temperature gauge. On an analog input type, the measured temperature value is acquired from the temperature transmitter connected to the analog input.

The temperature measurement method can be checked by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature select
Display	F04 or G10

Sele	ction	Description
HART	Display	Description
Fixed	0	The fixed temperature set at Fixed Temperature is used
Built-in	1	The measured value of the built-in temperature gauge on the type with a temperature sensor is used
Analog input	2	The measured temperature value is acquired from the temperature transmitter connected to the analog input on the analog input type

4.3.2 Setting Scaling of Temperature Measurement

Setting the lower limit value (0%)

Set the temperature to be taken as 0% for when analog output is performed after scaling the measured temperature value of the built-in temperature gauge.

Menu path

HART	Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature LRV
Display	B51 or G11

Setting the upper limit value (100%)

Set the temperature to be taken as 100% for when analog output is performed after scaling the measured temperature value of the built-in temperature gauge.

Menu path

HART	Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature URV
Display	B52 or G12

4.3.3 Setting the Damping Time Constant of the Temperature Measurement

Set the damping time constant (63.2% response) for the temperature measurement of the built-in temperature gauge by the following parameters. Change the damping time constant, for example, to suppress output oscillation or to alter the response speed (default 4.0 seconds).

HART	Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature damping
Display	G13

NOTE

When using HART communication in a situation where the output signal changes instantly, set the damping time constant to 2 seconds or more.

4.3.4 Compensating Temperature Measurement

The measured temperature value of the built-in temperature gauge can be compensated. The calculation formula for temperature correction is as follows.

 $T_r = T_n \times a + b$

- T_r: Temperature after compensation based on measured temperature [unit selected at C30 or F14: Temperature unit]
- T_n: Measured temperature [unit selected at C30 or F14: Temperature unit]
- a: Compensation factor (gain)
- B: Compensation value (offset)

Compensation factor (gain) and compensation value (offset) can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► T/P setup ► Temperature ► (see table below)
Display	(See table below)

Para	meter	Description	
HART	Display	Description	
Temperature gain	G15	The compensation factor (gain) is set	
Temperature offset	G16	The compensation value (offset) is set	

4.4 Pressure Measurement Function

On an analog input type, the measured pressure value can be acquired from the pressure transmitter connected to the analog input. At 4.1.8 Selection of compensation type (F03: Compensation type), select pressure correction based on the pressure measured by analog input, and set the analog input range in 4.7.4.

4.4.1 Checking the Pressure Measurement Method

The pressure measurement method can be checked by the following parameters.

HART	Device Settings ► Detailed setup ► T/P setup ► Pressure ► Pressure select
Display	F05 or G20

Selection		Description	
HART	Display	Description	
Fixed	0	The fixed pressure set at Fixed Pressure is used	
Analog input	2	The measured pressure value is acquired from the pressure transmitter connected to the analog input on the analog input type	

4.5 Density Measurement Function

On the analog input type, the measured density value can be acquired from the density transmitter connected to the analog input. At 4.1.8 Selection of compensation type (F03: Compensation type), select correction based on the density measured by analog input, and set the analog input range in 4.7.4.

NOTE

When acquiring the density by current input, set the density of 4.1.8 correctly and then set 4.7 as well.

4.6 Analog Output Function

4.6.1 Analog Output Selection

Set the process value to assign to analog output. This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Analog output ► Analog output select
Display	B50

Selection		Description	
HART	Display	Description	
Flow rate	0	The instantaneous flow rate is set to analog output	
Temperature	1	The fluid temperature is set to analog output (When equipped with built-in temperature sensor)	

4.6.2 Displaying Analog Output

This current value of the analog output can be checked by the following parameters.

HART	Process Variables ► Device variable ► Loop current		
Display	-		

4.6.3 Upper Limit Value/Lower Limit Value of Analog Output

The upper limit value/lower limit value of analog output can be set.

The upper limit value can be restricted between 4.0 and 21.6 mA, and the lower limit value can be restricted between 3.6 to 20.0 mA.

These settings can be set and checked by the following parameters.

On the HART configuration tool, set this manually according to the interactive Operation Guide called "DD Method".

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Analog output ► Analog output limit
Display	(See table below)

Parameter		Description
HART Display		
-	D31	The lower limit value of analog output is set
-	D30	The upper limit value of analog output is set
Analog output limit	-	The upper limit value/lower limit value of analog output are set
Analog output low limit	-	The lower limit value of analog output is displayed
Analog output high limit	-	The upper limit value of analog output is displayed

Example:

The result of setting the upper limit value to 16 mA and the lower limit value to 8 mA is as follows. Current [mA]



NOTE

When the NE43 option (Option NE43) is enabled, the Analog output high limit (upper limit value) becomes 20.5 mA and the Analog output low limit (lower limit value) becomes 3.8 mA. For details about how to check the NE43 option, refer to Section 4.14.1.

4.6.4 Adjusting the Analog Output Value

Analog output values can be adjusted by conditions of use. To adjust analog output values, execute adjustment value output (output of 4 mA and 20 mA current) from the product, then connect the ammeter for calibration, and measure the current value.

Set the measured current value to parameters, and adjust the analog output value. This setting can be set by the following parameters.

On the HART configuration tool, set this manually according to the interactive Operation Guide called "DD Method".

Menu path

HART	Maintenance ► Adjustment ► Analog output trim ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Analog output trim	H05	Adjustment value output is executed ^{*1}
Reference meter(4mA)	H07	The measured value at 4mA adjustment is set
Reference meter(20mA)	H08	The measured value at 20mA adjustment is set
Analog output trim(4mA)	H10	The adjustment value when analog input is 4 mA Value is displayed (Unit:%)
Analog output trim(20mA)	H11	The adjustment value when analog input is 20 mA Value is displayed (Unit:%)
Analog output trim clear	H06	The adjustment value when analog output is used is cleared*2

*1: Select execution of adjustment value output from the table below

Selection		Description
HART Display		
Not execute	0	Not execute
4 mA	1	4 mA is output
20 mA	2	20 mA is output

*2: Select execution of clearing of the adjustment value of analog output from the table below

Sele	ction	Description
HART	Display	Description
Not execute	0	Not execute
Execute	1	Clearing of the adjustment value of analog output is executed

IMPORTANT

When the adjustment function for the current value is used and the indicated output and current value do not match, re-adjust the current value.

NOTE

When the Reference meter (4mA) and Reference meter (20mA) are set, adjustments are made and the initial value (4mA/20mA) is displayed.

4.6.5 **Priority of Analog Output**

Analog output operates according to the following priority.

Priority	Output Mode
	Output is fixed at 4 mA in the HART multidrop mode
High ♠	Adjustment value output
	HART Loop test
Low	Test mode, analog output test
	Operation when an error occurs ^{*1}
	Normal output

*1: See 4.12.2 Operation when an error occurs

4.7 Analog Input Function

This function is an optional function.

The process value of an external device can be loaded to this product as an analog input. Analog input can be used for the input of external temperature, external pressure, external density, and external temperature difference to perform various correction calculations. For details on correction calculation, see 4.1.8.

4.7.1 Analog Input Selection

The process value assigned to analog output is displayed. This setting can be checked by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input select
Display	F06

Selection		Description
HART Display		
Off	0	Analog input is unused or cannot be used
Temperature	1	External temperature is currently used as the input
Pressure	2	External pressure is currently used as the input
Density	3	External density is currently used as the input
Delta temperature	4	External temperature difference is currently used as the input

NOTE

- The analog input function can be used when an analog input type (communication and I/O code JB) is selected.
- To assign a process value to analog input, select analog input as the target process value at Compensation Type. (See Section 4.1.8)
- Two or more process values cannot be used as analog inputs at the same time.

4.7.2 Displaying Analog Input

This current value of the analog input can be checked by the following parameters.

HART	Maintenance ► Signal controls ► (see table below)
Display	(See table below)

Parameter		Description	
HART	Display	Description	
Analog input(mA)	K57	The current value of the external input is displayed	
Analog input	K58	The process value of the external input is displayed	

4.7.3 Setting the Analog Input Unit

Display the unit when analog input is used.

This setting can be checked by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input unit
Display	D52

4.7.4 Setting the Analog Input Range

The range of the process value used for analog input can be set by settings 0% and 100% of the process value used for analog input.

This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Analog input ► (see table below)
Display	(See table below)

Parameter		Description
HART Display		
Analog input LRV	D53	The value when the process value used for analog input is 0% is set
Analog input URV	D54	The value when the process value used for analog input is 100% is set

4.7.5 Upper Limit Value/Lower Limit Value of Analog Input

The upper and lower limit values of current that are input as analog input can be set. The upper limit value can be set between 4.0 and 21.6 mA, and the lower limit value can be restricted between 3.6 to 20.0 mA.

This setting can be set by the following parameters.

HART	Device Settings ► Detailed setup ► I/O ► Analog input ► (see table below)
Display	(See table below)

Para	meter	Description
HART	Display	Description
Analog input low limit	D55	The lower limit value of the analog input value is set
Analog input high limit	D56	The upper limit value of the analog input value is set

4.7.6 Adjusting the analog input value

Analog input values can be adjusted by conditions of use. To adjust analog input values, input 4 mA and 20 mA currents from external devices, and check the analog input values on the display of this device or by HART communication. Set the checked current value to parameters, and adjust the analog input values.

This setting can be set by the following parameters.

On the HART configuration tool, set this manually according to the interactive Operation Guide called "DD Method".

Menu path

HART	Maintenance ► Adjustment ► Analog input trim ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
-	H14	The measured value at 4 mA adjustment is displayed
-	H15	The measured value at 8 mA adjustment is displayed
-	H16	The measured value at 12 mA adjustment is displayed
-	H17	The measured value at 16 mA adjustment is displayed
-	H18	The measured value at 20 mA adjustment is displayed
-	H12	Adjustment of analog input is executed ^{*1}
-	H13	The adjustment value when analog input is used is cleared ^{*2}

Parameter		Description	
HART	Display	Description	
Analog input trim	-	The measured value at 4 mA, 8 mA, 12 mA, 16 mA, and 20 mA measurement is set, and adjustment is executed	
Analog input trim (4mA)	-	The measured value at 4 mA adjustment is displayed	
Analog input trim (8mA)	-	The measured value at 8 mA adjustment is displayed	
Analog input trim (12mA)	-	The measured value at 12 mA adjustment is displayed	
Analog input trim (16mA)	-	The measured value at 16 mA adjustment is displayed	
Analog input trim (20mA)	-	The measured value at 20 mA adjustment is displayed	
Analog input trim clear	-	The adjustment value when analog input is used is cleared ^{*2}	

*1: Select execution of adjustment of analog input from the following table

Selection		Description	
HART	Display	Description	
Not execute	0	Not execute	
4 mA	1	Adjustment when analog input is 4 mA is executed	
8 mA	2	Adjustment when analog input is 8 mA is executed	
12 mA	3	Adjustment when analog input is 12 mA is executed	
16 mA	4	Adjustment when analog input is 16 mA is executed	
20 mA	5	Adjustment when analog input is 20 mA is executed	

*2: Select execution of clearing of the adjustment value of analog input from the table below

Selection		Departmen
HART	Display	Description
Not execute	0	Not execute
Execute	1	Clearing of the adjustment value of analog input is executed

IMPORTANT

When the adjustment function for the current value is used and the indicated input and current value do not match, re-adjust the current value.

4.7.7 Priority of Analog Input

Analog input operates according to the following priority.

Priority	Output Mode
High	Test Mode
	Operation when an error occurs ^{*1}
Low	Normal output

*1: See 4.12.2 Operation when an error occurs

4.8 Pulse Output, Frequency Output, and Status Output

4.8.1 Setting the Pulse/Status Output Mode

Select the pulse/status output mode.

This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Pulse/Status output mode
Display	B20

Select the output mode from the table below

Selection		Description
HART	Display	Description
Off	0	Not output
Scaled pulse	1	Set the flow rate to pulse output
Unscaled Pulse	2	Vortex pulse output is set
Frequency	3	Frequency output is set
Alarm switch	4	Alarm contact output is set
Limit switch	5	Limit switch output is set

4.8.2 Setting the Pulse Rate

When pulse output or vortex pulse output is used, the pulse rate value (pulse weighting) can be set.

When pulse output is used, set the flow rate per single pulse output. At this time, the pulse rate unit is the unit of instantaneous flow rate set in section 4.1.2.

When vortex pulse output is used, the result obtained by calculation based on the number of vortexes that occurred from the shedder bar is output as the number of pulses. At this time the formula for the number of output pulses is as follows.

Number of output pulses per second = Vortex frequency / pulse rate setting value This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Pulse output rate
Display	B21

Example: When pulse output is used

If "10" is set as the pulse rate when the flowrate unit is m³, the pulse rate is expressed as 10 m³/ pulse.

Example: When vortex pulse output is used

If "0.1" is set as the pulse rate, the "Vortex frequency x 10 pulses" are output.

NOTE

The lowcut function will be applied if using pulse output, but will not be applied if using vortex pulse output. For details about the lowcut function, see 4.1.6.
4.8.3 Mapping of Frequency Output

When frequency output is used, the process value to be output must be selected. This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Frequency output select
Display	D11

Select the process value to output from the table below

Select	tion	Description
HART Display		Description
Flow rate	0	The instantaneous flow rate is set
Temperature	1	The fluid temperature is set (When equipped with built- in temperature sensor)

4.8.4 Setting the Frequency Output Range

When frequency output is used, frequencies at 0% and 100% for the span of the process value can be set. The range of frequency output can be set by setting the frequency. This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► (see table below)
Display	(See table below)

Para	meter	Description	
HART	Display	Description	
Frequency output zero	D12	The frequency when the process value at which to output frequency is 0% is set	
Frequency output span	B22	The frequency when the process value at which to output frequency is 100% is set	

The supported span is determined as follows according to the selection of Frequency output select.

Frequency output select	Process value 100%	Process value 0%
Flow rate	Flow span	0.0
Temperature	Temperature URV	Temperature LRV

4.8.5 Pulse Output/Frequency Output Priority

Pulse output/frequency output operates according to the following priority.

Priority	Output Mode		
High	Pulse Test Mode		
	Operation when an error occurs ^{*1}		
Low	Normal output		

*1: See 4.12.2 Operation when an error occurs

4.8.6 Setting Status Output Functions

When a status output (alarm contact output or limit switch output) is used, the product status can be output as a contact output.

Alarm contact output

This function turns status output on or off when an alarm or warning occurs. When status output is used as alarm contact output, the alarm to be output can be selected. When the target alarm occurs, status output becomes active.

Target alarms can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Alarm switch select
Display	D15

Select the alarms to output from the table below

Selec	tion	Description
HART	Display	
All alarm/warning	0	All alarms/warnings are set to output
All alarm	1	All alarms are set to output
System/Process alarm	2	System alarms/process warnings are set to output
System alarm	3	System alarms are set to output
Process alarm	4	Process alarms are set to output
Setting alarm	5	Setting alarms are set to output
Warning	6	Warnings are set to output

Alarms targeted with each setting are displayed as follows.

	Alarm Category			
Alarm switch select	System alarm	Process alarm	Setting alarm	Warning
All alarm/warning	✓	\checkmark	\checkmark	\checkmark
All alarm	\checkmark	\checkmark	\checkmark	-
System/Process alarm	√	✓	-	-
System alarm	✓	-	-	-
Process alarm	-	\checkmark	-	-
Setting alarm	-	-	\checkmark	-
Warning	-	-	-	\checkmark

The following shows an example of operation.

Device alarm states

	Alarm canceled	Alarm occurring	Alarm canceled
Status outpu (Active direc	ut tion: short circuit (closed))		
Status outpu	t		
(Active direc	tion: release (open))		F0450.ai

Limit switch output

This function turns status output on and off when a target selected from one of instantaneous flow rate, fluid temperature, fluid pressure, or totalization exceeds (High limit) or falls below (Low limit) a certain threshold value.

When status output is used as limit switch output, the process value to assign to output can be selected. Also, selection of the H limit (upper limit value)/L limit (lower limit value), threshold value and hysteresis can be set.

This setting can be set by the following parameters.

Menu path

HART	Device Settings \blacktriangleright Detailed setup \blacktriangleright I/O \blacktriangleright Pulse/Status output \blacktriangleright (see table below)
T DAIXT	
Display	(See table below)

Para	meter	Description	
HART Display		Description	
Limit switch select	D16	The process value targeted in limit switch output is set ^{*1}	
Limit switch mode	D17	The H side/L side of limit switch output is set ^{*2}	
Limit switch level	B23	The threshold value is set	
Limit switch hysteresis	D18	The hysteresis width of the limit switch output switching is set ^{*3}	
Limit switch unit	D19	The unit of the threshold value and hysteresis value are displayed	

*1: Select the process value targeted in limit switch output from the table below

Selection		Description	
HART	Display	Description	
Flow rate	0	The instantaneous flow rate is set to the limit switch target	
Temperature	1	The fluid temperature is set to the limit switch target (When equipped with built-in temperature sensor)	
Totalizer	3	The totalized flow rate value is set to the limit switch target	

*2: Select the H limit (upper limit value)/L limit (lower limit value) of limit switch output from the table below

Selection		Description
HART	Display	Description
Low limit	0	The L limit (lower limit value) is set. Limit switch output becomes active when the process value to output falls below the threshold value.
High limit	1	The H limit (upper limit value) is set. Status output becomes active when the process value to output exceeds the threshold value.

NOTE

If the software revision is R1.01.01, the limit switch level and limit switch hysteresis unit (Limit switch unit) will not be displayed properly if the limit switch output target was set to the heat difference instantaneous flow rate, in DTM or another configuration tool.

When Limit switch select = "Flow rate" and Flow select = "Energy (Heat difference)", the limit switch unit will not be displayed in the heat difference unit (kJ/s, MJ/h, etc.). Instead, it will be displayed in the volumetric flow rate unit (m3/s, l/h, etc.).

The limit switch output will operate normally in the heat difference unit.

When using the conditions described above, read the limit switch level and limit switch hysteresis unit as the energy unit, instead of the limit switch unit.

*3: The value of limit switch switching is calculated as follows.

(1) Value at which the limit switch (when H limit is selected) switches from an active to a non-active state = Set limit threshold value - Hysteresis value

(2) Value at which the limit switch (when L limit is selected) switches from an active to a non-active state = Set limit threshold value + Hysteresis value

The following shows an example of operation. **Example of H limit:** Limit switch output = instantaneous flow rate Measured flow rate selection = volumetric flow rate Span of volumetric flow rate = $300 \text{ m}^3/\text{h}$, H /L selection of limit switch is set = H limit Limit threshold value = $300 \text{ m}^3/\text{h}$ When hysteresis width = $15 \text{ [m}^3/\text{h]}$ is set

Value at which the limit switch switches from an active to a non-active state = $285 \text{ [m}^3/\text{h]}$ = $300 \text{ [m}^3/\text{h]} - 15 \text{ [m}^3/\text{h]}$

Example of L limit:

Limit switch output = instantaneous flow rate Measured flow rate selection = volumetric flow rate Span of volumetric flow rate = $300 \text{ m}^3/\text{h}$, H /L selection of limit switch is set = L limit Limit threshold value = $0 \text{ m}^3/\text{h}$ When hysteresis width = $15 \text{ [m}^3/\text{h]}$ is set

Value at which the limit switch switches from an active to a non-active state = $15 [m^3/h]$ = $0 [m^3/h] + 15 [m^3/h]$

= 0 [m³/h] + 15 [m³/h]

When H limit is selected Flow rate (m³/h) Threshold value 300 285 When L limit is selected Flow rate (m³/h) 15 Threshold value 0 Status output (Active direction: release (open)) F043.ai

NOTE

When the physical quantity to be output is changed, the alarm judgment value must be set again.

4.8.7 Displaying the State of Status Output

Display the state of status output.

This setting can be checked by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Status output condition
Display	D13

Value		Description
HART	Display	Description
Not active	0	Non-actitve state
Active	1	Active state

4.8.8 Setting the Active Direction of Status Output

When status output is used, which of open/close is set to active can be set. This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Status output direction
Display	D14

Select the active direction of status output from the table below

Selection		Description
HART	Display	Description
On active	0	When status output is short circuit (closed) is set to active
Off active	1	When status output is release (open) is set to active

4.9 Sensor Information

4.9.1 Setting Sensor Information

Sensor-related settings are set before shipment from the factory as specified at the time of ordering.

This setting can be set by the following parameters. Note, however, that normally there is no need to change this setting.

Menu path

HART	Device Settings ► Detailed setup ► Sensor Information ► (see table below)
Display	(See table below)

Parameter		Departmention
HART	Display	Description
Nominal size	E10	The nominal size is set ^{*1}
Body type	E20	The body type is set ^{*2}
Sensor type	E30	The sensor type is set ^{*3}
Connection type	E22	The integral/remote sensor is set ^{*4}
K factor unit	E40	The K factor unit is set ^{*5}
K factor	E41	The K factor 15 degC value is set
Process temperature	E44	The allowable temperature is displayed ^{*6} /set ^{*7}
Max pressure	E45	The maximum allowable pressure is displayed ^{*6} / set ^{*7}
Sensor S/N	-	The sensor serial No. is displayed ^{*6} /set ^{*7}

*1: Select the nominal size

Selection		Description
HART	Display	Description
15 mm	1	The diameter is set to 15 mm
25 mm	2	The diameter is set to 25 mm
40 mm	3	The diameter is set to 40 mm
50 mm	4	The diameter is set to 50 mm
80 mm	5	The diameter is set to 80 mm
100 mm	6	The diameter is set to 100 mm
150 mm	7	The diameter is set to 150 mm
200 mm	8	The diameter is set to 200 mm
250 mm	9	The diameter is set to 250 mm
300 mm	10	The diameter is set to 300 mm
400 mm	11	The diameter is set to 400 mm

*2: Select the body type

Selection		Description
HART	Display	Description
General	0	General type
One size down	1	Reduced bore type: 1 size reduction
Two size down	2	Reduced bore type: 2 size reduction
High pressure	4	High pressure reduced bore type: 1 size reduction
Dual sensor	6	Dual sensor type

*3: Select the sensor type		
Selection		Description
HART	Display	Description
Standard	0	General type
Standard w/ temp sensor	1	General type with temperature sensor
High temperature	2	High temperature type
High temperature w/ temp sensor	3	High temperature type with temperature sensor
Cryogenic	4	Cryogenic type
Long neck	6	Long neck type
Long neck w/ temp sensor	7	Long neck type with temperature sensor

*4: Select the transmitter connection method

Selection		Description
HART	Display	Description
Integral	0	The integral sensor is set
Remote	1	The remote sensor is set

*5: The K factor unit is selected

Selection		Description
HART	Display	Description
p/l	0	P/l is set
p/USgal	1	p/USgal is set
p/UKgal	2	p/UKgal is set

*6: *7: For R1.01.01 or R1.01.02

For R1.01.03 or more

IMPORTANT

The K factor is a value unique to each individual device. Be sure to use the value set before shipment from the factory that is stamped on the nameplate, and do not rewrite this value. (Except when the sensor has been replaced on the remote type)

4.9.2 Backup/Restore of Sensor Information

These functions back up and restore sensor related setting information to facilitate changes to settings that occur due to replacement of the transmitter and sensor. This product has memory for both the transmitter and sensor.

- Backup: Data is copied from transmitter memory to sensor memory
- Restore: Data is copied from sensor memory to transmitter memory





Replacement of sensor



Data to be backed up and restored are the sensor adjustment values, management information and inspection information.

The following table shows the actual data that is backed up and restored.

Fluctuating level	Prediction start date	Sensor MS code 2
Transient noise count	Prediction stop date	Sensor MS code 3
High vibration action	Flow lowcut	Sensor MS code 4
High vibration time	Nominal size	Sensor MS code 5
Critical vibration action	Body type	Sensor MS code 6
Critical vibration level	Sensor type	Sensor style code
Critical vibration time	Connection type	Sensor S/N
Clogging time	K factor unit	Signal level
Sensor circuit threshold	K factor	Trigger level mode
Sensor capacitance threshold	Process temperature	Trigger level(TLA)
Sensor resistance threshold	Max pressure	Noise balance mode
Prediction period	Sensor MS code 1	Noise ratio(manual)

Backup and restore can be executed and checked by the following parameters. **Menu path**

HART	Device Settings ► Detailed setup ► Sensor Information ► (see table below)
Display	-

Parameter		Description
HART	Display	Description
Sensor backup/restore	E46	Backup/restore of sensor information is executed*1
Sensor backup/restore result	E47	The backup/restore result of sensor information is displayed ^{*2}

*1: Select execution of backup/restore from the table below

Selection		Description
HART	Display	Description
Not execute	-	Initial state after a power on
Backup parameter	-	Targeted parameters are copied from the transmitter to the sensor
Restore parameter	-	Targeted parameters are copied from the sensor to the transmitter
Restore parameter(factory)	-	Targeted parameters are copied from the sensor to the transmitter (parameter area for factory use)

*2: The result of backup/restore operation is shown as follows.

Selection		Departmen
HART	Display	Description
Unknown	-	Initial state after a power on
Pass	-	Backup/restore was successful
Failure	-	Backup/restore failed
Running	-	Backup/restore execution in progress

NOTE

Only transmitter side memory is used for the flow calculation. Sensor side memory is only kept saving data as the backup function.

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4.10 Auxiliary Calculation Function

4.10.1 Compensation (Gain)

A user-specified arbitrary compensation factor (gain) can be set. This compensation factor (gain) is applied by multiplication on the measured value.

This setting can be set by the following parameters.

Menu path

HART	Maintenance ► Adjustment ► Flow rate gain
Display	H20

4.10.2 Reynolds Number Correction

On a vortex flowmeter, error increases at low Reynolds numbers. Output error at Reynolds numbers 20000 or less can be corrected by segment approximations.

The Reynolds number correction factor corresponding to the Reynolds number found based on the present flow velocity is calculated by linear approximation of five pairs of [Reynolds number - correction factor setting parameter]. This correction factor is applied by multiplication on the measured value.

The correction factor is calculated by the following formula.

Correction factor ε_r =

1 + ((Reynolds number – Adjust Reynolds number[x]) / (Adjust Reynolds number [x+1]– Adjust Reynolds number [x]) × (Re adjust value [x+1]– Re adjust value [x]) + Re adjust value [x]) / 100

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This setting can be set by the following parameters.

NOTE

On the display, you can change the selection of Reynolds number correction, but you cannot change Adjust Reynolds number 1 to 5 and Re adjust value 1 to 5.

Menu path

HART	Maintenance ► Adjustment ► Reynolds adjust ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Reynolds adjust	H25	Execution of Reynolds number correction is selected*1
Viscosity unit	H28	Unit of viscosity ^{*2}
Viscosity	H27	Viscosity ^{*3}
Reynolds number	H24	Reynolds number
Adjust Reynolds number 1	-	Reynolds number of the No.1 break point of Reynolds number correction ^{*4}
Re adjust value 1	-	Correction value of the No.1 break point of Reynolds number correction ^{*4}
Adjust Reynolds number 2	-	Reynolds number of the No.2 break point of Reynolds number correction ^{*4}
Re adjust value 2	-	Correction value of the No.2 break point of Reynolds number correction ^{*4}
Adjust Reynolds number 3	-	Reynolds number of the No.3 break point of Reynolds number correction ^{*4}
Re adjust value 3	-	Correction value of the No.3 break point of Reynolds number correction ^{*4}
Adjust Reynolds number 4	-	Reynolds number of the No.4 break point of Reynolds number correction ^{*4}
Re adjust value 4	-	Correction value of the No.4 break point of Reynolds number correction ^{*4}
Adjust Reynolds number 5	-	Reynolds number of the No.5 break point of Reynolds number correction ^{*4}
Re adjust value 5	-	Correction value of the No.5 break point of Reynolds number correction ^{*4}

*1: Execution of Reynolds number correction is selected

Selection		Description
HART	Display	Description
Off	0	Correction calculation is not performed.
On	1	Correction calculation is performed.

*2: Select the viscosity unit

Selection		
HART	Display	
mPa·s	0	
Pa·s	1	
cP	2	
Р	3	
m2/s	4	
cSt	5	
St	6	

*3: Viscosity setting The viscosity (mPa·s(cP)) is set to perform Reynolds number correction. The Reynolds number (Re) is calculated by the following formula: Reynolds number (Re) = (velocity x diameter x density * 10^3) / viscosity velocity: Flow velocity (m/s) diameter: Sensor inner diameter (m) density: Fluid density (kg/m³) viscosity: Viscosity parameter setting value (mPa·s)

*4: Reynolds adjust

In a 3-dimensional flow inside a pipeline, as Reynolds number (<20000) decreases, the Strouhal number (K factor) gradually increases. The curve of this K factor is corrected using a 5-point line segment approximation.



NOTE

When Reynolds number correction is used, be sure to set both H26:Fixed density and H27:Viscosity. Note, however, that when the Viscosity unit is a kinematic viscosity unit (m2/s, cSt, St), H26:Fixed density is not affected.

4.10.3 Instrument Error Correction

The instrument error correction factor corresponding to the present vortex frequency is calculated by linear approximation of five pairs of [vortex frequency - correction factor setting parameter]. This correction factor is applied by multiplication on the measured value. The correction factor is calculated by the following formula.

Correction factor ε_{f} =

1 + ((Vortex frequency – Adjust vortex frequency [x]) / (Adjust vortex frequency [x+1] – Adjust vortex frequency [x]) × (Adjust value 1 [x+1] – Adjust value 1 [x]) + Adjust value 1 [x]) / 100

This setting can be set by the following parameters.

Menu path

HART	Maintenance ► Adjustment ► Instrument error adjust ► (see table below)
Display	(See table below)

Parameter		
HART	Display	Description
Instrument error adjust	H40	Whether or not to use instrument error correction is selected ^{*1}
Adjust vortex frequency 1	H41	Vortex frequency of No.1 break point of instrument error correction*2
Adjust value 1	H42	Correction value of No.1 break point of instrument error correction*2
Adjust vortex frequency 2	H43	Vortex frequency of No.2 break point of instrument error correction* ²
Adjust value 2	H44	Correction value of No.2 break point of instrument error correction* ²
Adjust vortex frequency 3	H45	Vortex frequency of No.3 break point of instrument error correction*2
Adjust value 3	H46	Correction value of No.3 break point of instrument error correction*2
Adjust vortex frequency 4	H47	Vortex frequency of No.4 break point of instrument error correction* ²
Adjust value 4	H48	Correction value of No.4 break point of instrument error correction*2
Adjust vortex frequency 5	H49	Vortex frequency of No.5 break point of instrument error correction*2
Adjust value 5	H50	Correction value of No.5 break point of instrument error correction*2

*1: Whether or not to use instrument error correction is selected

Selection		Description
HART	Display	Description
Off	0	Correction calculation is not performed.
On	1	Correction calculation is performed.

*2: As shown in the figure, flow rate error based on the reference flow rate value is corrected by segment approximations by setting the correction data corresponding to the frequency of any five points.



 (1) Set the break point frequency as f1 ≤ f2 ≤ f3 ≤ f4 ≤ f5. When there are 4 points, set f4 = f5. When there are 3 points, set f3 = f4 = f5.

(2) When there is a flow rate input of f1 or less, instrument error correction is performed with the correction value taken to be d1.

(3) When there is a flow rate input of f5 or more, instrument error correction is performed with the correction value taken to be d5.

(4) Horizontal axis (f1 - f5): Set the break point frequency as the parameter.
(5) Vertical axis (d1 - d5): Set the correction value (%) of each break point as the parameter.

Expansion Correction 4.10.4

Error caused by pressure loss occurs in proportion to the increase in flow speed of a fluid. Expansion correction is used to correct this error.

This setting can be set by the following parameters.

HART	Maintenance ► Adjustment ► Expansion factor adjust
Display	H30

Selection		Description
HART	Display	Description
Off	0	Correction calculation is not performed.
On	1	Correction calculation is performed.

4.11 Maintenance/Adjustment Functions

4.11.1 Noise Balance

Normally, use noise balance in the Auto mode. Note, however, that when there is considerable vibration on the piping line and measurement is not succeeding in the Auto mode, adjust this by entering setting values in the Manual mode.

For details on adjustment method, see Sections 4.11.3 Zero Tuning and 4.1.6 Setting the Lowcut Function of Instantaneous Flow Rate.

Menu path

HART	Maintenance ► Signal controls ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Signal band	-	The signal band is displayed.
Signal level	K20	Adjustment scale factor of signal judgment level
Noise balance mode	K25	Selection of noise balance mode
Noise ratio(auto)	K26	Noise balance value when the noise balance mode is Auto
Noise ratio(manual)	K27	Noise balance value when the noise balance mode is Manual

4.11.2 TLA

The trigger level (TLA) has already been set to the optimum value. Accordingly, there is no need to set this during regular measurement. However, the trigger level needs to be adjusted in the following cases:

- To perform measurement at a flow rate lower than the default flow rate
- When there is considerable vibration on the piping line, and the flow rate is zero even after manually adjusting noise balance, or when output indicates a value higher than the actual value during a low flow rate

Note, however, that the measurable lower limit flow velocity increases when the adjustment value has been set higher than the optimum value (default value).

For details on adjustment method, see Sections 4.11.3 Zero Tuning and 4.1.6 Setting the Lowcut Function of Instantaneous Flow Rate.

HART	Maintenance ► Signal controls ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Trigger level mode	-	Selection of TLA mode
Trigger level(TLA)	К10	User setting scale factor of trigger level judgment threshold value

4.11.3 Zero Tuning

Perform zero tuning manually when there is flow rate output despite the fact that fluid has been stopped even though the device has been automatically adjusted to cancel out external noise (e.g vibration on piping) at all times. Perform zero tuning by the procedure below.



HART	Maintenance ► Signal controls ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Tuning at zero	K51	Select whether to execute tuning of noise balance is executed
Tuning status	K52	Noise balance tuning state

4.11.4 Other Maintenance Information

The following parameters can be checked.

HART	Maintenance ► Signal controls ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Velocity span	K32	The flow velocity span value is displayed
Velocity lowcut	K54	The lowcut flow velocity value is displayed
Vortex frequency span	K36	The vortex frequency span is displayed
Vortex frequency lowcut	K55	The lowcut vortex frequency is displayed

4.12 Alarms

4.12.1 Errors and Countermeasures

Explanation of NE107 status:

	NE107 status	Status of the device
F	Failure	Parts failure, device failure, overall failure
С	Function Check	The output signal is temporarily abnormal as a local operation or value has been input manually.
S	Out of specification	The device is operating outside of the specification. The output signal is uncertain for the process or the environment.
М	Maintenance required	Maintenance is required in the near future.
Ν	No Effect	State other than mentioned above.

The following table shows possible countermeasures.

System alarm

The device has malfunctioned and normal measurement is not possible. The product might need to be replaced.

NE107	Error message		Dotails of orror	Countormossuro
status	HART	Display	Details of error	Countermeasure
-	-	-	Operation stop of the transmitter CPU is detected	Contact your nearest Yokogawa service center.
F	010:CPU failure	AL-010	A failure in the program memory of the transmitter CPU is detected	Contact your nearest Yokogawa service center.
F	011:CPU failure	AL-011	A failure in the I/O calculation memory of the transmitter CPU is detected	Contact your nearest Yokogawa service center.
F	012:Main storage failure	AL-012	Physical/logical failure of the transmitter EEPROM is detected	Contact your nearest Yokogawa service center.
F	013:Sub storage failure	AL-013	Physical/logical failure of the sensor EEPROM is detected	Contact your nearest Yokogawa service center.
F	014:Main ASIC failure	AL-014	Operation stop of the main control IC is detected	Contact your nearest Yokogawa service center.
F	015:Sub ASIC failure	AL-015	Operation stop of the sub control IC is detected	In the case of the remote type, refer to Section 8.7 "Remote Type" in the Vortex Flowmeter VY Series Installation Manual. In the case of the integral flowmeter, contact your nearest Yokogawa service center.
F	016:ADC circuit failure	AL-016	Failure of the sensor ADC circuit is detected	Contact your nearest Yokogawa service center.
F	017:Signal circuit failure	AL-017	Failure of the sensor signal circuit is detected	Contact your nearest Yokogawa service center.
F	018:Power circuit failure	AL-018	Failure of the sensor power circuit is detected	Contact your nearest Yokogawa service center.
F	020:Flow sensor failure	AL-020	Failure of the flow sensors (A or B) is detected	Contact your nearest Yokogawa service center.

NE107	Error message		Details of arror	Countormocouro	
status	HART	T Display Details of error		Countermeasure	
F	021:Temperature sensor failure	AL-021	Failure of the temperature sensor is detected	Contact your nearest Yokogawa service center.	
F	023:Analog input failure	AL-023	Failure of analog input device is detected	Check the connections to the analog input device	

Process alarm

The device is normal but normal measurement is not possible due to process-related problems. Consider maintenance.

NE107	Error message		Details of arror	Countormocouro
status	HART	Display	Details of error	Countermeasure
S	030:Fluctuation	AL-030	Fluctuation of the flow rate signal is detected	Check the process or installation status.
S	031:Transient noise	AL-031	Transient noise on the flow rate signal is detected	Check the process or installation status.
S	032:High vibration	AL-032	Abnormal vibration of the piping is detected	Check the process or installation status.
S	033:Critical vibration	AL-033	Abnormal resonance of the piping is detected	Check the process or installation status.
S	040:Temperature out of range	AL-040	The fluid temperature is out of the specification temperature range	Check the process.
S	042:Analog output out of range	AL-042	Analog output is out of the upper/lower limit value range	Check the parameter settings or the process values assigned to analog output.
S	043:Pulse output out of range	AL-043	Pulse output/frequency output are out of the specification range	Check the parameter settings or the process values assigned to pulse output.
S	044:Analog input out of range	AL-044	Analog input is out of the upper/lower limit value range	Check the device connected to analog input
S	045:T/P compensation out of range	AL-045	The fluid temperature and fluid pressure is out of the compensation range	Check the fluid temperature and fluid pressure values.

Setting alarm

The device is operating normally, however, a parameter setting error has occurred. Check the parameter settings.

NE107	Error message		Dotails of orror	Countormossuro	
status	HART	Display	Details of error	Countermeasure	
С	050:Flow span set error	AL-050	The flow rate span setting is out of the specification range	Correct the flow rate span value. Or, check the flow rate calculation setting parameter.	
С	051:Temperature span set error	AL-051	The temperature span setting is inconsistent or out of the specification range	Correct the temperature span value.	

NE107	Error message		Dotails of orror	Countermocouro	
status	HART	Display	Details of error	Countermeasure	
С	053:Flow calculation set error	AL-053	Setting inconsistency in flow rate calculation (including calculation tool)	Check the flow rate setting, flow rate selection and flow rate calculation setting parameter.	
С	054:Analog output set error	AL-054	Analog output upper/ lower limit value setting inconsistency	Check the analog output parameter setting.	
С	055:Pulse output set error	AL-055	Pulse output setting inconsistency	Check the pulse output rate, frequency of processing values 0% and 100%, and flow rate span value.	
С	056:Analog input set error	AL-056	Analog input upper/ lower limit value setting inconsistency	Check the analog input parameter and flow rate calculation settings.	
С	060:Sensor backup error	AL-060	Transmitter/sensor backup setting inconsistency	Check the data to be backed up.	

Warnings

The device and measurement are operating normally, however, a warning has occurred.

NE107	Error message		Deteile of error	Countormocouro
status	HART	Display	Details of error	Countermeasure
М	070:Sensor communication error	AL-070	Control IC communication error is detected	In the case of a remote type, check the remote cable. In the case of an integral flowmeter, contact a Yokogawa service center.
М	071:Flow sensor error	AL-071	Abnormal sensor sensitivity is detected	Check the state of the flow sensors by using Built-in Verification.
М	072:Clogging	AL-072	Clogging of a flow sensor is detected	Remove foreign matter by following the instructions in the device manual.
М	073:Degradation	AL-073	Degradation of a flow sensor is detected	Consider the timing for removing foreign matter.
S	074:Board temperature out of range	AL-074	A device internal temperature out of the specification range is detected	Review the installation environment.
С	080:Simulation running	AL-080	Test/simulation is running	When restoring to normal operation, cancel simulation or the output test.
С	081:Verification running	AL-081	Verification is currently executing	Wait for diagnostic processing to complete.
-	082:Incorrect PIN	AL-082	Entry of wrong user levels PIN	Enter the correct PIN. If you have forgotten your password, contact your nearest sales office or Service Center.

4.12.2 Operation When an Error Occurs

Description of Term

Term	Description
Operation	Operation state in which output is being correctly output
Interlocked to input	Operation state in which the same processing as when there is no alarm is performed

Example 1) The volumetric flow rate also is held if the vortex frequency to be input is held when the volumetric flow rate is in use.

Example 2) When a temperature sensor failure occurs

When the flow rate is used as the volumetric flow rate, the vortex frequency to be input becomes normal action and the volumetric flow rate also becomes normal action.

When the flow rate is used as the mass flow rate, temperature and pressure can be input in addition to the vortex frequency. Accordingly, the combination becomes vortex frequency (normal), temperature (error) and pressure (normal). Output becomes the mass flow rate calculated according to the temperature error as a result of specifying handling of the temperature error by setting in Temp sensor alarm action.

The following table summarizes output and display behavior when an error occurs.

System alarm

			Output						Fluid temperature	
NE 107	Error message	Current	pulse/ frequency	Status	Vortex frequency	Built-in temperature	Analog input	Instantaneous flow rate	Fluid pressure Fluid density Fluid density ratio Specific enthalpy	Flow rate total
-	-	Burnout (HW)	Stop	Open (HW)		-	-	-	-	-
F	010:CPU failure	Burnout	Stop	Operation	Fixed	at 0%	Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	011:CPU failure	Burnout	Stop	Operation	Fixed	at 0%	Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	012:Main storage failure	Burnout	Stop	Operation	Fixed	at 0%	Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	013:Sub storage failure	Burnout	Stop	Operation	Fixed	at 0%	Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	014:Main ASIC failure	Burnout	Stop	Operation	Fixed	at 0%	Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	015:Sub ASIC failure	Burnout	Stop	Operation	Fixed at 0%		Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	016:ADC circuit failure	Burnout	Stop	Operation	Fixed at 0%		Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	017:Signal circuit failure	Burnout	Stop	Operation	Fixed	Fixed at 0%		Interlocked to input	Interlocked to input	Stop
F	018:Power circuit failure	Burnout (L)	Stop	Operation	Fixed	at 0%	Fixed at 0%	Interlocked to input	Interlocked to input	Stop
F	020:Flow sensor failure	User setting Flow sensor alarm action	Stop	Operation	User setting Flow sensor alarm action	Operation	Operation	Interlocked to input	Interlocked to input	Stop
F	021:Temperature sensor failure	User setting Temp sensor alarm action	Stop	Operation	Operation	User setting Temp sensor alarm action	Operation	Interlocked to input	Interlocked to input	Stop
F	023:Analog input failure	User setting Aux input alarm action	Stop	Operation	Oper	ation	User setting Aux input alarm action	Interlocked to input	Interlocked to input	Stop

Process alarm

			Output						Fluid temperature	
NE 107	Error message	Current	pulse/ frequency	Status	Vortex frequency	Built-in temperature	Analog input	Instantaneous flow rate	Fluid pressure Fluid density Fluid density ratio Specific enthalpy	Flow rate total
s	030:Fluctuation	Operation	Operation	Operation	Oper	ration	Operation	Interlocked to input	Interlocked to input	Operation
s	031:Transient noise	Operation	Operation	Operation	Oper	ration	Operation	Interlocked to input	Interlocked to input	Operation
S	032:High vibration	Operation	Operation Stop (*)	Operation	User setting High vibration action	Operation	Operation	Interlocked to input	Interlocked to input	Operation
S	033:Critical vibration	Operation	Operation Stop (*)	Operation	User setting Critical vibration action	Operation	Operation	Interlocked to input	Interlocked to input	Operation
s	040:Temperature out of range	Operation	Operation	Operation	Oper	ration	Operation	Interlocked to input	Interlocked to input	Operation
S	042:Analog output out of range	Limit	Operation	Operation	Ope	Operation		Interlocked to input	Interlocked to input	Operation
s	043:Pulse output out of range	Operation	Limit	Operation	Oper	ration	Operation	Interlocked to input	Interlocked to input	Operation
s	044:Analog input out of range	Operation	Operation	Operation	Ope	ration	Limit	Interlocked to input	Interlocked to input	Operation
s	045:T/P compensation out of range	Operation	Operation	Operation	Oper	ration	Operation	Interlocked to input	Interlocked to input	Operation

*: If the software revision is R1.01.01, the pulse/frequency output operation when AL-032:High vibration and AL-033:Critical vibration occur will be "Stop".

Setting alarm

			Output						Fluid temperature	
NE 107	Error message	Current	pulse/ frequency	Status	Vortex frequency	Built-in temperature	Analog input	Instantaneous flow rate	Fluid pressure Fluid density Fluid density ratio Specific enthalpy	Flow rate total
С	050:Flow span set error	Operation	Operation	Operation	Oper	Operation		Interlocked to input	Interlocked to input	Operation
С	051:Temperature span set error	Operation	Operation	Operation	Operation		Operation	Interlocked to input	Interlocked to input	Operation
С	053:Flow calculation set error	Operation	Operation	Operation	Oper	Operation		Hold	Interlocked to input ^{*1}	Hold
С	054:Analog output set error	Hold	Operation	Operation	Oper	ration	Operation	Interlocked to input	Interlocked to input	Operation
С	055:Pulse output set error	Operation	Hold	Operation	Oper	Operation		Interlocked to input	Interlocked to input	Operation
С	056:Analog input set error	Operation	Operation	Operation	Oper	ration	Hold	Interlocked to input	Interlocked to input	Operation
С	060:Sensor backup error	Operation	Operation	Operation	Oper	ration	Operation	Interlocked to input	Interlocked to input	Operation

*1: Fluid density, Fluid density ratio and Specific enthalpy are held.

Warnings

			Output						Fluid temperature	
NE 107	Error message	Current	pulse/ frequency	Status	Vortex frequency	Built-in temperature	Analog input	Instantaneous flow rate	Fluid pressure Fluid density Fluid density ratio Specific enthalpy	Flow rate total
М	070: Sensor Communication error	Operation	Operation	Operation	Oper	ation	Operation	Interlocked to input	Interlocked to input	Operation
М	071: Flow sensor error	Operation	Operation	Operation	Operation		Operation	Interlocked to input	Interlocked to input	Operation
М	072: Clogging	Operation	Operation	Operation	Operation		Operation	Interlocked to input	Interlocked to input	Operation
М	073: Degradation	Operation	Operation	Operation	Oper	ation	Operation	Interlocked to input	Interlocked to input	Operation
S	074: Board temperature out of range	Operation	Operation	Operation	Oper	ation	Operation	Interlocked to input	Interlocked to input	Operation
С	080: Simulation running	Operation	Operation	Operation	Oper	ation	Operation	Interlocked to input	Interlocked to input	Operation
С	081: Verification running	Operation	Operation	Operation	Но	old	Hold	Interlocked to input	Interlocked to input	Operation
-	082: Incorrect PIN	Operation	Operation	Operation	Oper	ation	Operation	Interlocked to input	Interlocked to input	Operation

4.12.3 Alarm Display Setting

Alarms are displayed on the lower display when an error occurs on this product. When two or more alarms occur on this product, alarms are displayed in sequence. Also, the names of alarms are displayed prefixed in accordance with the NAMUR NE107 standard.

This setting can be set by the following parameters.

HART	Device Settings ► Detailed setup ► Display ► Display NE107
Display	D22

Para	neter	Description
HART	Display	Description
Off	0	The NAMUR NE107 category is not displayed.
On	1	The NAMUR NE107 category is displayed.

Alarm History Function 4.12.4

This function allows alarms that occurred in the past to be stored as an alarm history. This function supports the following two types of functions:

- Alarm record: Five records are stored in sequence from the first alarm that occurs •
- Recent alarm: The latest five alarms are stored

The features of these two functions are as follows.

Item	Alarm record	Recent alarm
Number of storage alarms	The first five alarms are stored in the order that they occurred	The latest five alarms that occurred are stored
6th alarm onwards	Not stored	Stored after the oldest alarm is cleared
Support for duplicate alarms	Not stored	Duplicate alarms are moved to the latest occurring alarm
Automatic deletion of alarms	After the specified number of days (default value: 60 days) has elapsed since the last alarm was stored, alarms [0] to [4] are cleared, and the alarm remaining in Recent alarm is stored (Even if the history is not filled with 5 alarms, alarms are cleared when the specified limit is reached)	Clearing is executed at the same timing as automatic deletion of Alarm record

When alarms A to C occurred in sequence

	1	A(1)		1	C(1)
	2	B(1)		2	B(1)
Alarm	3	C(1)	Recent alarm	3	A(1)
	4	Empty		4	Empty
	5	Empty		5	Empty

When alarms A to G occurred in sequence

	1	A(1)		1	G(1)		
	2	B(1)			F(1)		
record	3	C(1)	Recent	ent 3 m	E(1)	AITI	
	4	D(1)		4	D(1)		
	5	E(1)		5	C(1)	B(1)	

When alarms A, C and E occurred from the above state

	1	A(1)			1	E(2)	
	2	B(1)			2	C(2)	
Alarm	3	C(1)	1	Recent	3	A(2)	1
	4	D(1)	1		4	G(1)	
	5	E(1)	1		5	F(1)	ľ.

When alarm A occurred from the above state

	1	A(1)		1	A(3)
	2	B(1)		2	E(2)
record	3	C(1)	Recent alarm	3	C(2)
	4	D(1)		4	G(1)
	5	E(1)		5	F(1)

Wh	en the recent a	larm	was not	upd	lated for a fixed	peri	od of tim	e (e.g. 60 days)
					r			1
66 days ago		1	A(1)			1	E(2)	30 days ago
65 days ago		2	B(1)			2	C(2)	40 days ago
64 days ago	Alarm	3	C(1)		Recent	3	A(2)	59 days ago
63 days ago		4	D(1)			4	G(1)	60 days ago
62 days ago		5	E(1)			5	F(1)	61 days ago
			The Alar occu	alar ms e irrer	m record is cle exceeding 60 d nce are cleared	areo lays I fror	l since the n the rec	eir cent alarm
		1	Empty			1	E(2)	30 days ago
		2	Empty			2	C(2)	40 days ago

		1	Empty			1	E(2)	30 days ago
	Alarm record	2	Empty			2	C(2)	40 days ago
		3	Empty		Recent alarm	3	A(2)	59 days ago
		4	Empty			4	G(1)	60 days ago
		5	Empty			5	Empty	
			The	rem	aining records	are	copied to	o the alarm

history as there are still records remaining in the recent alarms

60 days ago 59 days ago 40 days ago 30 days ago	Alarm record	1 2 3 4	G(1) A(2) C(2) E(2)	X + + >	Recent alarm	1 2 3 4 5	E(2) C(2) A(2) G(1)	30 days ago 40 days ago 59 days ago 60 days ago
		5	Empty			5	Empty	

When the alarm record is cleared manually

	1	A(1)			1	E(2)
	2	B(1)			2	C(2)
record	3	C(1)		Recent	3	A(2)
	4	D(1)			4	G(1)
	5	E(1)			5	F(1)

All alarms both in the record and the recent are cleared

	1	Empty			1	Empty
	2	Empty		2	Empty	
Alarm	3	Empty		Recent alarm	3	Empty
	4	Empty			4	Empty
	5	Empty			5	Empty
	-					

A (x) to G (x): The number in parentheses indicates the number of occurrences of the alarm type.

These settings can be set and checked by the following parameters. Menu path

HART	Diagnostics ► Alarm ► Alarm record ► (see table below)
Display	-

Parameter		a 1.4	
HART	Display	Description	
Alarm record clear	-	Selection for forcibly clearing the alarm history and latest alarm	
Auto delete time	-	Specified limit (number of days) for automatically clearing the alarm history and latest alarm	
Alarm record 1-5	-	Alarms recorded in Alarm record are displayed 5: Latest $\leftarrow \rightarrow$ 1: Oldest	
Alarm record date 1-5	-	The date of alarms recorded in Alarm record are displayed (yyyy/mm/dd)	
Alarm record time 1-5	-	The time of alarms recorded in Alarm record are displayed (hh:mm:ss)	
Alarm record operation time 1-5	-	The operation time when an alarm recorded in Alarm record is displayed in the format "ddddD hh:mm" ^{*1}	
Recent alarm 1-5	-	Alarms recorded in Recent alarm are displayed 1: Latest $\leftarrow \rightarrow 5$: Oldest	
Recent alarm date 1-5	-	The date of alarms recorded in Recent alarm are displayed (yyyy/mm/dd)	
Recent alarm time 1-5	-	The time of alarms recorded in Recent alarm are displayed (hh:mm:ss)	
Recent alarm operation time 1-5	-	The operation time when an alarm recorded in Recent alarm is displayed in the format "ddddD hh:mm" ¹	

The operation time when an alarm occurred is displayed in the format "ddddD hh:mm". "dddddD" indicates the day, "hh" indicates the hour, and "mm" indicates the minute. *1:

Example:

"0031D 12:34" is displayed This example shows that the alarm occurred when the product had been operated for 31 days, 12 hours, and 34 minutes.

4.12.5 Alarm Mask Function

This function masks a preset alarm group to hide alarm notification and prevents an alarm history from being left behind.

This setting can be set by the following parameters.

Menu path

HART	Diagnostics ► Alarm ► (see table below)
Display	-

Parameter		Description
HART	Display	Description
Alarm status select	-	Selection of alarm to be notified (HART/display)*1
Alarm record select	-	Selection of alarm to be stored in history ^{*1}

*1: Alarm status select / Alarm record select list

Selection		Description
HART Display		
All alarm/warning	-	All alarms and warnings are notified/stored in history
All alarm	-	Only alarms are displayed/stored in history (excluding warnings)
System/Process alarm	-	All System/Process alarms are notified and stored in history (excluding Setting Alarms, Warnings)

4.12.6 Output Operation When Alarm Occurs

Burnout

For the burnout function, set the direction of analog output when a CPU failure occurs. The direction of analog output when a burnout occurs can be checked by the following parameters.

Menu path

HART	Diagnostics ► Signal controls ► (see table below)
Display	(See table below)

Parameter		Description
HART Display		
Burnout	D35	The direction of analog output when a burnout occurs is displayed
Burnout recover	-	The restore operation when a burnout occurs is set (Normally, this parameter is used set to On)*1

*1: Burnout Recover select list

Selection		Description
HART	Display	Description
Off	-	Restore is not performed when a burnout occurs (To perform a restore, the device must be turned on again)
On	-	Restore is attempted when a burnout occurs (Normally, this parameter is used set to On)

Setting output operation when a specific alarm occurs

Analog output operation when a specific alarm occurs can be set. This setting can be set by the following parameters.

Menu path

HART	Diagnostics ► Signal controls ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
Flow sensor alarm action	-	Output operation when AL-020:Flow sensor failure occurs is set^{*1}
Temperature sensor alarm action	-	Output operation when AL-021: Temperature sensor failure occurs is set*2
Analog input alarm action	-	Output operation when AL-023: Analog input failure occurs is set ^{*2}
High vibration action	K45	Output operation when AL-032:High vibration occurs is set*3
Critical vibration action	K46	Output operation when AL-033:Critical vibration occurs is set*3

*1: Select output operation when AL-020 occurs

Selection		Description
HART Display		
Burnout	-	Burnout
Hold	-	Output is held at the value immediately before the alarm occurred
Zero	-	Flow rate zero
Measured value	-	Measurement is continued

*2: Select output operation when AL-021 and AL-023 occurs			
Selection		Description	
HART	Display	Description	
Burnout	-	Burn out	
Hold	-	Output is held at the value immediately before the alarm occurred	
Zero	-	Flow rate zero	
Fixed value	-	The analog input value is fixed and subsequently normal calculation is performed*2-1	

*2-1: The fixed current value can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input fix value
Display	D57

*3: Select output operation when AL-032 and AL-033 occurs

Selection		Description
HART	Display	
Zero	0	Flow rate zero
Hold	1	Output is held at the value immediately before the alarm occurred
Measured value	2	Measurement is continued

4.13 Display

4.13.1 Setting Display Items

The content to display in the lower and upper displays can be set. This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Display ► (see table below)
Display	(See table below)

Para	meter	Description
HART	Display	Description
Display line upper	B30	The content to display in the upper display is set ^{*1}
Display line lower	B31	The content to display in the lower display is set ^{*2}

*1: Select the content to display in the upper display from the table below

Sele	ction	Description
HART	Display	Description
Flow rate(%)	0	The instantaneous flow rate (%) is displayed
Flow rate	1	The instantaneous flow rate (engineering unit) is displayed
Temperature(%)	2	The fluid temperature (%) is displayed

*2: Select the content to display in the lower display from the table below

Sele	ction	Description
HART Display		Description
Off	0	No display in lower display
Totalizer	1	The totalized flow rate value is displayed
Temperature	2	The fluid temperature (engineering unit) is displayed
Analog input	4	The process value assigned to analog input (engineering unit) is displayed

NOTE

The units of the external temperature, external pressure and external temperature difference can be displayed when analog input is selected on the lower display. The unit is not displayed on the display when external density is selected for analog input.

4.13.2 Setting the Decimal Point Position

The number of digits past the decimal point can be automatically adjusted or set to fixed when instantaneous flow rate (engineering unit), fluid temperature (engineering unit) or analog input has been set to a display item in 4.13.1.

NOTE

There are some restrictions of this decimal point settings to give priority to show the value without over digit, cause of the 6 digit in lower line of this segment type LCD and it is restricted to 5 digit in case of numerical value with sign.

For example, the case of the value of -100 and decimal point setting is 4 digit, is NOT expressed like "-100.0000", so that, it is changed like "-100.00" with 2 digit of decimal point.

This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Display ► (see table below)
Display	(See table below)

Para	meter	Departmention
HART	Display	Description
Display format flow	D23	The decimal point position of the instantaneous flow rate value is set
Display format temperature	D24	The decimal point position of fluid temperature or external temperature from analog input, included external temperature difference in case of heat difference application
Display format pressure	D25	The decimal point position of external pressure from analog input

D23: Select the decimal point position of display format flow from the table below

Selection		Description
HART	Display	Description
Auto	0	The number of digits past the decimal point is automatically adjusted ^{*1}
0 digit	1	The number of digits past the decimal point is fixed to 0
1 digit	2	The number of digits past the decimal point is fixed to 1
2 digit	3	The number of digits past the decimal point is fixed to 2
3 digit	4	The number of digits past the decimal point is fixed to 3
4 digit	5	The number of digits past the decimal point is fixed to 4

*1: When "Auto" is selected, the display format is automatically switched according to the span of the selected process value. The following table summarizes this in detail. This selection can be set only for Display format flow.

	Judgment Range		Corresponding Display Format
700.0	< Flow span		Odigit
70.0	< Flow span ≤	700.0	1digit
7.0	< Flow span ≤	70.0	2digit
0.7	< Flow span ≤	7.0	3digit
	Flow span ≤	0.7	4digit

D24: Select the decimal point position of Display format temperature and D25: Display format pressure from the table below			
Selection		Description	
HART	Display	Description	
0 digit	0	The number of digits past the decimal point is fixed to 0	
1 digit	1	The number of digits past the decimal point is fixed to 1	
2 digit	2	The number of digits past the decimal point is fixed to 2	
3 digit	3	The number of digits past the decimal point is fixed to 3	
4 digit	4	The number of digits past the decimal point is fixed to 4	

NOTE

When % display is selected, the number of digits past the decimal point is fixed to 1 and cannot be changed.

The decimal point position of totalized values is interlocked with the total rate setting. For details, see 4.2 Totalization Function.

4.13.3 Setting the Update Interval

The update interval of the process value for the display can be set.

NOTE

The display is the type of using liquid crystal, it has feature of slow response under lower temperature atmosphere. So, in this case, please set the longer update interval than usual to make sure to discern displaying contents.

Furthermore, pay attention about the following influences after setting the longer update interval. Turning period of exchanging alarm number and process value displaying.

Then, the time to move to the setting mode by pressing the [SET] switch, is needed a little longer cause of avoiding miss touch the switch. It depends on the setting of update interval and it is about 2 times of the interval. Pay attention in case of the long interval setting, especially.

This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Display ► Display period
Display	D20

Select the update internal from the table below

Selection		Description
HART	Display	Description
0.25s	0	The update interval is set to 0.25 seconds
0.5s	1	The update interval is set to 0.5 seconds
1s	2	The update interval is set to 1 second
2s	3	The update interval is set to 2 seconds
4s	4	The update interval is set to 4 seconds
8s	5	The update interval is set to 8 seconds

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4.13.4 Other Settings

(1) Setting the startup screen

The screen display at startup can be selected. This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Display ► Display startup
Display	D21

Select the screen display at startup from the table below

Selection		Description
HART	Display	Description
Off	0	Nothing is displayed when the display is started up
On	1	The software version is displayed when the display is started up ^{*1}

*1: Example of software version display



F0453.ai

(2) Display test function

The test pattern is displayed by execution of the display test. Note that pressing any switch on the display during execution of this function will stop the function and return to the measurement screen.

This setting can be set by the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► Display test
Display	J45

Select the screen display at startup from the table below

Selection		Description
HART	Display	Description
Not execute	0	Not execute
Execute	1	Full segment pattern and the other pattern are displayed in order from pattern 2, 3, 4, 5, 1 to 2, repeated cyclically The display cycle depends on the display period setting. When it is set to less than 4 s, Full segment pattern is displayed 10 seconds, and the other patterns are displayed 4 seconds When it is set to greater than equal 4 s, Full segment pattern is displayed 16 seconds, and the other patterns are displayed 8 seconds
All on	2	All displayed (pattern 2)
All off	3	All hidden (pattern 1)
Only numeric	4	Only the number area is displayed (pattern 3)
Only unit	5	Only the unit area is displayed (pattern 4)
Only icon	6	Only the icon area is displayed (pattern 5)

Example of display during execution of the display test



(3) Squawk function

A display pattern is displayed on the display to identify products that are being communicated with when two or more of the same model of product are installed. The display pattern is switched in sequence every 8 times of the update interval. Note that pressing any switch on the display during execution of this function will stop the function and return to the measurement screen. This setting can be set by the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► Squawk
Display	-

Select the squawk function from the table below

Selection		Description
HART	Display	Description
Off	-	The squawk pattern is not displayed
On	-	The squawk display pattern is displayed (displayed continuously until squawk is turned off)
Once	-	The squawk display pattern is displayed (the measurement screen is returned to after the pattern is displayed for only 1 display cycle)

• Example of display during execution of the squawk function


4.14 Device Information

4.14.1 Order Information

The order information of the product can be set and displayed. If a particular parameter is specified at the time of order, this product is shipped with the parameter specified. For details about the configuration of the model name and specification code, refer to General Specifications GS 01F07A00-01EN.

These settings can be set and checked by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Information ► Order info ► (see table below)
Display	-

Parameter		Description
HART	Display	Description
Sensor ► Sensor MS code 1 - 6	-	The sensor MS code is displayed ^{*1} /set ^{*2}
Sensor ► Sensor style code	-	The sensor style code is displayed ^{*1} /set ^{*2}
Transmitter ► Transmitter MS code 1 - 6	-	The transmitter MS code is displayed ^{*1} /set ^{*2}
Transmitter ► Transmitter style code	-	The transmitter style code is displayed*1/set*2
Special order ► Special order number 1-2	-	The special order No. is displayed*1/set*2
Other ► Sizing number	-	The sizing No. is displayed ^{*1} /set ^{*2}
Other ► Name plate tag number	-	The name plate tag No. is displayed*1/set*2
Other ► Instruction manual number	-	The instruction manual No. is displayed ^{*1} /set ^{*2}
Other ► Communication select	-	The communication option is displayed
Option ► Option analog input	-	The optional analog input is displayed
Option ► Option built-in temperature	-	The optional built-in temperature gauge is displayed
Option ► Option display installation	-	The optional display is displayed
Option ► Option burnout	-	The optional burnout is displayed ^{*1} /set ^{*2}
Option ► Option NE43	-	The optional NE43 is displayed*1/set*2
Option ► Option wireless adapter	-	The usage status of the wireless adapter is set
Option ► Option dual bolt calibration	-	The optional dual sesnor is displayed ^{*1} /set ^{*2}
Option ► Option cryogenic	-	The optional cryogenic is displayed
Option ► Prediction function	-	The predictive diagnosis mode is displayed ^{*1} /set ^{*2}
Option ► Option built-in verification	-	The verification option is displayed ^{*1} /set ^{*2}
Option ► Option SI unit	-	The optional SI unit is displayed
Option ► Option SIL	-	The optional SIL is displayed

*1: For R1.01.01 or R1.01.02

*2: For R1.01.03 or more

NOTE

When Option wireless adapter is set to "Wireless", the function to save parameters and totalized values to EEPROM in case of power failure is disabled.

4.14.2 Device Revision

The revision of the software, etc. currently used on this product can be checked. This information can be checked by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Information ► Device info ► (see table below)
Display	-

Parameter		Description
HART	Display	Description
Model	-	The device model name is displayed
Dev id*1 / Device Identifier*2	-	The device ID is displayed
Тад	-	The tag number is set
Transmitter S/N	-	The transmitter serial No. is displayed*3/set*4
Software revision	-	The revision No. of the software is displayed
Hardware revision	-	The revision No. of the hardware is displayed
Release date	-	The release date is displayed
Distributor name	-	The distributor name is displayed

4.14.3 Memo Function

Three parameters can be used for the memo function. Memos up to 16 characters long can be set.

This setting can be set by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Information ► Device info ► (see table below)
Display	-

Parameter		Description
HART	Display	Description
Memo 1	-	Memo 1 is set
Memo 2	-	Memo 2 is set
Memo 3	-	Memo 3 is set

*1: For Device revision 1 and DD revision 1 or 2

*2: For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

- *3: For R1.01.01 or R1.01.02
- *4: For R1.01.03 or more

4.14.4 Date and Time Information

The present date and time can be set.

This setting can be displayed and set with the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Information ► Date/Time ► (see table below)
Display	-

Parameter		Description
HART	Display	Description
Set current date	-	The date is set
Current date*1 / Current Date*2	-	The present date is displayed
Current time* ¹ / Current Time* ²	-	The present time is displayed
Set Clock Date	-	The date set at Set current date is displayed
Set Clock Time	-	The time set at Set current date is displayed

NOTE

When the product is turned off, the date and time at that time are stored in memory. However, the time that elapses while power is turned off is not added to the date and time. Set to the correct time again when the power is turned on.

4.14.5 Displaying the Operation Time

Display the operation time. Operation time refers to the operation time up to the present from the time when the power was turned on for the first time. However, time is not counted when power is not turned on.

This information can be checked by the following parameters.

Menu path

HART	Device Settings ► Detailed setup ► Information ► Date/Time ► Operation time
Display	-

The operation time is displayed in the format of "dddddD hh:mm". "dddddD" indicates the day, "hh" indicates the hour, and "mm" indicates the minute.

Example: "0031D 12:34"

This example shows that the product has been operated for 31 days, 12 hours, and 34 minutes.

NOTE

When the product has been operated for 10,000 days, the display stops at "9999D 23:59".

*1: For Device revision 1 and DD revision 1 or 2

*2: For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

4.15 Self-diagnostics

4.15.1 Types of Diagnostic Function

The self-diagnostics function of this product can be used to diagnose product failures or process status.

The diagnostic functions of this product are as follows.

Diagnostic Function	Description		
Noise diagnosis	The presence of transient noise on the flow rate signal is diagnosed, and an alarm is notified when a failure is detected.		
Vibration diagnosis	Vibration on the piping is diagnosed, and an alarm is notified when a failure is detected.		
Resonant diagnosis	Resonance on the piping is diagnosed, and an alarm is notified when a failure is detected.		
Clogging diagnosis	Clogging of the flow rate sensor is diagnosed, and a warning is notified when a failure is detected.		
Predictive diagnosis	The time until failure of the piezo electric device is predicted, and a warning is notified before the failure occurs.		
Verification	The health of the device is diagnosed, and the diagnosis result is displayed.		
Signal latch	The state of the vortex signal at an arbitrary timing or when a specific alarm occurs is latched and the result is displayed.		

4.15.2 Noise Diagnosis

Noise diagnosis diagnoses the presence of transient noise on the flow rate signal, and notifies the alarms Fluctuation (AL30) and Transient noise (AL31) when a failure is detected. This setting can be set by the following parameters.

Menu path

HART	Diagnostics ► Signal controls ► (see table below)	
Display	-	

Paramet	er	Description	
HART	Display	Description	
Transient noise count	-	This is the judgment count of Transient noise diagnosis. When this is set to "0", Transient noise diagnosis is disabled.	
Fluctuating level	-	This is the judgment value for the Fluctuation alarm. When this is set to "0.0%", Fluctuation diagnosis is disabled.	
Sensor circuit threshold(*)	-	The judgment value for the input circuit alarm (AL17) is set. When this is set to "0", diagnosis is disabled.	
Sensor capacitance threshold(*)	-	Failure value for the Sensor Failure alarm (AL20) is	
Sensor resistance threshold(*)	-		

NOTE

(*) If these parameters are set to other than 0, the output will be held once every 60 seconds for sensor diagnosis when the flow rate is zero or the sensor fails.

4.15.3 Vibration Diagnosis

With vibration diagnosis, the presence of abnormal vibration on the piping is diagnosed, and a High vibration alarm is notified when a failure is detected. This judgment time for vibration diagnosis can be set by the following parameters.

When this is set to "0", vibration diagnosis is disabled.

Menu path

HART	Diagnostics ► Signal controls ► High vibration time
Display	-

Analog output operation when the High vibration alarm occurs can be set. For details, see 4.12.6.

4.15.4 Resonant Diagnosis

With resonant diagnosis, flow rate signal data is used to diagnose the presence of resonance, and a Critical vibration alarm is notified when resonance is detected. This setting can be set by the following parameters.

Menu path

HART	Diagnostics ► Signal controls ► (see table below)
Display	-

Paramet	er	Description
HART Display		Description
Critical vibration level	-	The judgment level for the Critical vibration alarm is set. When this is set to "0.0%", resonant diagnosis is disabled.
Critical vibration time	-	The judgment time for the Critical vibration alarm is set.

Analog output operation when the Critical vibration alarm occurs can be set. For details, see 4.12.6.

4.15.5 Clogging Diagnosis

With clogging diagnosis, flow rate signal data is used to diagnose the presence of clogging on the piping, and a Clogging warning is notified when clogging is detected.

This judgment the judgment time for clogging diagnosis can be set by the following parameters. When this is set to "0", clogging diagnosis is disabled.

Menu path

HART	Diagnostics ► Signal controls ► Clogging time
Display	-

4.15.6 Predictive Diagnosis

With predictive diagnosis, the time until an abnormal level is reached is predicted based on the trend of the detection signal from the piezo electric device, and a Degradation warning is notified before the failure is predicted to occur.

These settings can be set and checked by the following parameters.

Menu path

HART	Diagnostics ► Predictive diagnosis ► (see table below)
Display	-

Paramet	er	Description
HART	Display	Description
Prediction execution	-	The predictive diagnosis mode is set
Prediction select	-	The data targeted in predictive diagnosis is set
Prediction period	-	The storage interval of predictive diagnosis is set
Prediction start date	-	The start date of predictive diagnosis is displayed
Prediction stop date	-	The stop date of predictive diagnosis is displayed
Prediction level	-	The judgment value of the prediction time is set
Prediction alarm time	-	The specified time of predictive diagnosis is set
Prediction estimate time	-	The prediction time of predictive diagnosis is displayed
Prediction result	-	The result of predictive diagnosis is displayed
Prediction type	-	The type of predictive diagnosis is set
Prediction data clear ^{*1}	-	Clearing of the trend data of predictive diagnosis is executed

*1: For R1.01.03 or more

NOTE

- Refer to Technical Information Vortex Flowmeter VY Series TI01F07A00-01EN for detailed setting method of predictive diagnosis.
- For Prediction execution, use Execute(1) only when fluid is flowing. If fluid is not flowing, the piezo electric device will not detect the signal, which can cause a malfunction.
- Execute Prediction data clear after performing sensor maintenance or changing fluid conditions.
- Trend data cannot be restored if Prediction data clear is executed.

4.15.7 Verification (Device Health Diagnosis) Function

The verification function diagnoses the health of the product and displays the diagnosis result. Each of the states of the detection circuit, signal circuit and calculation circuit are inspected, and device health diagnosis is performed based on the diagnosis results of internal alarm states and alarm history.

It takes approximately four minutes for the verification function to complete. The results of verification can be checked in parameters. "Pass" is displayed if no problem is found or "Failure" is displayed if a problem is found.

These settings can be set and checked by the following parameters.

Menu path

HART	Diagnostics ► Verification ► (see table below)
Display	-

Parameter		Description	
HART Display		Description	
Verification Exe	-	Execution/cancellation of verification*1	
Verification target	-	The verification target is selected ^{*2}	
Verification status	-	The progress of verification is displayed ^{*3}	
Verification select	-	The verification result to be displayed is selected ^{*4}	
Verification date	-	The date of verification execution selected at Verification select is displayed	
Verification time	-	The time of verification execution selected at Verification select is displayed	
Verification operation time	-	The operation time of verification execution selected at Verification select is displayed	
Verification result	-	The overall result of verification at verification execution selected at Verification select is displayed ^{*5}	
Sensor circuit result	-	The detection circuit diagnosis result of verification at verification execution selected at Verification select is displayed ^{*5}	
Signal circuit result	-	The signal circuit diagnosis result of verification at verification execution selected at Verification select is displayed ^{*5}	
Calculation circuit result	-	The calculation circuit diagnosis result of verification at verification execution selected at Verification select is displayed ^{*5}	
Alarm status result	-	The alarm state result of verification at verification execution selected at Verification select is displayed ^{*5}	
Alarm record result	-	The alarm history result of verification at verification execution selected at Verification select is displayed ^{*5}	

*1: Select execution/cancellation of the verification function from the table below

Parameter		Description
HART Display		
Not execute	-	Initial state after a power on. Processing is canceled if this is set during execution.
Execute	-	Verification is executed. The state returns to Not execute if processing is completed or is forcibly ended after verification is executed. During execution, the state is Busy.

*2: Select the verification target from the table below

Parameter		Description
HART	Display	
Sensor circuit	-	The detection circuit is set as the verification target.
Signal processing circuit -		The signal circuit is set as the verification target.
Calculation circuit -		The calculation circuit is set as the verification target.
Alarm status -		The alarm status is set as the verification target.
Alarm record	-	The alarm history is set as the verification target.

*3: The progress of verification is displayed		
Parameter		Description
HART Display		
Not execute	-	Verification is not yet executed. Initial state after a power on.
Execute (1 to 10/10)	-	Verification is currently executing. Progress is displayed in ten steps.
Finish	-	Verification is completed. The result is updated.
Cancel	-	Verification is canceled and forcibly ended. The result is not updated.

*4: Select the verification result to be displayed from the table below

Parameter		Description	
HART	Display	Description	
Latest	-	Displays the result at this time.	
Previous	-	Displays the previous result.	
Factory	-	Displays the result obtained upon shipment from the manufacturing factory.	

*5: From the table below, select the result of the verification function.

Parameter		Description
HART	Display	Description
Unkown	-	Initial state after a power on
Pass	-	There are no problems concerning the diagnosis result.
Failure	-	There is a problem concerning the diagnosis result.
Cancel	-	Diagnosis is canceled/forcibly ended
Skip	-	Out of verification target

IMPORTANT

- Before using the verification function, be sure to disconnect this product from the control loop.
- Note that parameters cannot be changed while the verification function is executed.

NOTE

- When using the verification function, correctly set the fluid status with the parameter.
- If there is a problem with the verification result, refer to the Maintenance Manual.

4.15.8 Signal Latch

The signal latch function enables the vortex signal to be latched at arbitrary timing and the result displayed in accordance with parameters. Also, the status of the vortex signal when a specific alarm occurs is latched and the result is displayed in accordance with parameters. These settings can be set and checked by the following parameters.

Menu path

HART	Diagnostics ► Sensor signal ► (see table below)
Display	-

Parameter		Description
HART	Display	Description
Signal latch execution	-	Signal latch is executed ^{*1}
Signal latch target	-	The signal latch to display is set ^{*2}
Signal latch alarm	-	The alarm at a signal latch is displayed ^{*3}
Signal latch date	-	The date at a signal latch is displayed
Signal latch time	-	The time at a signal latch is displayed
Signal latch operation time	-	The operation time at a signal latch is displayed
Signal latch vortex frequency	-	The vortex frequency at a signal latch is displayed
Signal latch velocity	-	The flow velocity at a signal latch is displayed
Signal latch max band	-	The maximum band at a signal latch is displayed
Signal latch noise ratio	-	The noise ratio at a signal latch is displayed
Signal latch noise band 1-2	-	Noise band 1-2 at a signal latch is displayed
Signal latch TLA	-	The trigger level at a signal latch is displayed
Signal latch basic band	-	The basic band at a signal latch is displayed
Basic+0-8 band A	-	The A signal amplitude at the basic band + (0 to 8) at a signal latch is displayed
Basic+0-8 band B	-	The B signal amplitude at the basic band + (0 to 8) at a signal latch is displayed
Basic+0-8 band C	-	The C signal amplitude at the basic band + (0 to 8) at a signal latch is displayed
Basic+0-8 band NJLS	-	The noise judgment level at the basic band + (0 to 8) at a signal latch is displayed

*1: Select execution of signal latch from the table below

Selection		Description
HART	Display	Description
Not execute	-	Initial state after a power on
Execute	-	Signal latch is executed

*2: Select the signal latch to display from the table below

Selection		Description
HART	Display	Description
Latest	-	The information that was latched at arbitrary timing is displayed
Sensor alarm record 1	-	
Sensor alarm record 2	-	The information that was latched when an alarm
Sensor alarm record 3	-	occurs is displayed
Sensor alarm record 4	-	1 (Latest) $\leftarrow \rightarrow$ 5 (Oldest)
Sensor alarm record 5	-	

*3: The alarm at a signal latch is displayed		
Selection		Description
HART	Display	Description
None	-	There is no information when an alarm occurs
Fluctuating	-	The information when a Fluctuating alarm occurs is displayed
Transient noise	-	The information when a Transient noise alarm occurs is displayed
High vibration	-	The information when a High vibration alarm occurs is displayed
Flow sensor error	-	The information when a Flow sensor error alarm occurs is displayed
Clogging	-	The information when a Clogging alarm occurs is displayed
Degradation	-	The information when a Degradation alarm occurs is displayed

4.16 Test/Simulation Function

IMPORTANT

Before using the test/simulation function, be sure to disconnect this product from the control loop.

4.16.1 Setting the Test Mode

If the test mode is executed, the value to be output from a connection terminal can be arbitrarily set, and a response from the device can be tested. Testing of one of analog output, pulse output and status output can be tested.

A warning is displayed to indicate that the test mode is in use while this test mode is used.

NOTE

The test mode is considered about both path of user I/F via display key switch access and via HART communication access.

The test mode gives priority to consider for procedure via HART communication access. So, the test mode is released from the procedure via display key switch access soon if the HART communication detected in that time.

This setting can be set by the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
-	J05	Setting of test target ^{*1}
-	J10	The test value (%) of analog output is set
-	J20	The test value (Hz) of pulse output is set
-	J30	The test output of status output is set*4

Parameter		Description
HART	Display	Description
Test/Simulation	-	 Selection of test mode^{*2} Setting of test target^{*1} Setting of test value^{*3}

*1: Se	lect the test target from the table b	below
--------	---------------------------------------	-------

Selection		Description
HART	Display	Description
Analog output	1	Testing of analog output is started
Pulse output	2	Testing of pulse output is started
Status output	3	Testing of status output is started
Test mode off	0	The test mode is canceled

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2: Select execution of the test mode from the table below		
Selection		Description
HART	Display	Description
Test mode	-	The test mode is executed
All off	-	The test mode is canceled (simulation also is canceled at the same time when a simulation is currently executing)

*3:	Set test values	according to	the test target
		•	•

Selection		Description
HART	Display	Description
Test analog output	-	The test value (%) of analog output is set
Test pulse output	-	The test value (Hz) of pulse output is set
Test status output	-	The test output of status output is set*4

*4: Select the test value of status output from the table below

Selection		Description
HART	Display	Description
Off(Open)	0	The test value of status output is set to off (open)
On(Close)	1	The test value of status output is set to off (short circuit)

When an analog output test has been performed, the process value currently selected for analog output is interlocked with the current value being output in the test, and also changes.

NOTE

Set pulse/status terminal output in section 4.8.1. If the set output is different from the test starting output, the test mode cannot be used.

For example, if the pulse/status output is set as a frequency output to start the status output test, the test cannot be started.

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4.16.2 Setting the Simulation Mode

In the simulation mode, values relating to vortex flowmeter inputs can be simulated. That is, vortex frequency (Software/Hardware), built-in temperature and analog input can be simulated.

With vortex frequency (Software) simulation, given simulation values are used in place of values resulting from the calculation of the vortex frequency.

With vortex frequency (Hardware) simulation, the health of the vortex signal input circuit can be checked by assigning pseudo vortex signals generated by internal circuits to the vortex signal input circuit in place of vortex signals from the vortex sensor.

Subsequent flow rate calculation and output is affected by setting simulation values.

A warning is displayed to indicate that the simulation mode is in use while this simulation mode is used.

The unit used when simulating built-in temperature is the temperature unit set in section 4.1.8. When the unit has been changed, the built-in temperature also is interlocked with the newly set unit and also changes.

This setting can be set by the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► (see table below)
Display	(See table below)

Parameter		Description
HART	Display	Description
-	J31	Setting of simulation target ^{*1}
-	J32 or K28	The simulation value (Hz) of the vortex frequency (software) is set
-	J33	The simulation value (Hz) of the vortex frequency (hardware) is set
-	J34	The simulation value of the built-in temperature is set
-	J36	The simulation value (mA) of the analog input is set

Parameter		Description
HART	Display	Description
Test/Simulation	-	 Selection of simulation mode^{*2} Setting of simulation target^{*1} Setting of simulation value^{*3}

*1: Select the simulation target from the table below

Selection		Description	
HART	Display	Description	
Vortex frequency	1	Simulation of vortex frequency input (Software) is started	
Vortex frequency(HW)	2	Simulation of vortex frequency input (hardware) is started	
Built-in temperature	3	Simulation of built-in temperature is started	
Analog input	5	Simulation of analog input is started	
Simulation mode off	0	The simulation mode is canceled	

*2: Select execution of the simulation mode from the table below

Selection		Description	
HART	Display	Description	
Simulation mode	-	The simulation mode is executed	
All off	-	The simulation mode is canceled (the test mode also is canceled at the same time when a test is currently executing)	

3: Set test values according to the simulation target			
Selection		Description	
HART Display			
Simulation vortex frequency	-	The simulation value (Hz) of the vortex frequency (Software) is set	
Simulation vortex frequency(HW)	-	The simulation value (Hz) of the vortex frequency (hardware) is set	
Simulation built-in temperature	-	The simulation value of the built-in temperature is set	
Simulation analog input(mA)	-	The simulation value (mA) of the analog input is set	

4.16.3 Automatic Cancellation of the Test/Simulation Mode

The test/simulation mode is automatically canceled when a fixed period of time has elapsed without changing parameters relating to the test/simulation mode after the test/simulation mode has been enabled. When parameters relating to the test/simulation mode are changed, the cancellation time is extended.

The time that the test/simulation mode is automatically canceled can be set by the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► Auto release time
Display	J40

Select the automatic cancellation time from the table below

Selection		Description
HART	Display	Description
10min	0	The cancellation time is set to ten minutes
30min	1	The cancellation time is set to 30 minutes
60min	2	The cancellation time is set to one hour
3h	3	The cancellation time is set to three hours
6h	4	The cancellation time is set to six hours
12h	5	The cancellation time is set to 12 hours

4.16.4 Loop Test

This function is common to HART communication. A constant current (mA) is output to check the control loop. This function can be executed from the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► Loop test ^{*1} / Force Loop Current ^{*2}
Display	-

*1: For Device revision 1 and DD revision 1 or 2

*2: For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

4.16.5 Device Variable Quantity Simulation Function

This function is common to HART communication. An arbitrary value and status can be set one device variable quantity to check output. The simulation value is also reflected in the output. This function can be executed from the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► (see table below)
Display	-

Para	neter	Description
HART	Display	Description
Device variable simulation	-	 Selection of Device variable^{*1} Setting of Value Setting of Data quality^{*2} Setting of Limit status^{*3}

*1: Select Device variable from the table below

Selection		Description	
HART	Display	Description	
Flow rate	-	Simulation of the instantaneous flow rate is started	
Total	-	Simulation of totalized values is started	
Temperature	-	Simulation of fluid temperature is started	
Pressure	-	Simulation of fluid pressure is started	

*2: Select Data quality from the table below

Selection		Description
HART Display		
Bad	-	The Quality of the status of the selected Device variable is set to Bad
Poor accuracy	-	The Quality of the status of the selected Device variable is set to Poor accuracy
Manual/Fixed	-	The Quality of the status of the selected Device variable is set to Manual/Fixed
Good	-	The Quality of the status of the selected Device variable is set to Good

*3: Select the Limit status from the table below

Sele	ction	Description	
HART	Display	Description	
Not limited	-	The Limit status of the status of the selected Device variable is set to Not limited	
Low limited	-	The Limit status of the status of the selected Device variable is set to Low limited	
High limited	-	The Limit status of the status of the selected Device variable is set to High limited	
Constant	-	The Limit status of the status of the selected Device variable is set to Constant	

4.16.6 Other Test Functions

(1) Restarting devices

Reset the device. When the device is restarted, parameters stored on the device are not initialized.

A restart can be executed by the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► Device reset
Display	_

Select execution of a restart from the table below

Sele	ction	Description
HART	Display	Description
Exit	-	The device restart is not executed
Execute	-	The device restart is executed

(2) Restarting the sensor circuit

Restart the device.

A restart can be executed by the following parameters.

Menu path

HART	Maintenance ► Test/Simulation ► Sensor reset
Display	-

Select execution of a restart from the table below

Selection		Description
HART	Display	Description
Exit	-	The sensor circuit restart is not executed
Execute	-	The sensor circuit restart is executed

4.17 Parameter Protection

4.17.1 Write Protect Function

Write protection can be set by two method, the hardware write protection switch and software write protection. Whichever method is used, writing to parameters is no longer possible. For details about the hardware write protection switch, refer to the Installation Manual. To enable the software write protection function, a password (eight alphanumeric characters, uppercase only) must be set to the parameter "New password". Write protection can be disabled for only ten minutes by entering the password to parameter "Enable write 10 min". The write protect function can be completely disabled by entering eight spaces to parameter "New password" with write protect temporarily disabled.

The write protect function can be set by the following parameters.

Menu path

HART	Device Setting ► Detailed setup ► Protect ► Write protect ► (see table below)
Display	-

Para	meter	Description
HART	Display	Description
Write protect	-	Use of the write protect function is displayed ^{*1}
Enable write 10 min	-	The write protect function is disabled for only 10 minutes
New password	-	A new password for the write protect function is set

*1: Use of the write protect function is displayed

Value		Description
HART	Display	Description
No	-	The write protect function is not used (parameters can be changed)
Yes	-	The write protect function is in use (parameters cannot be changed)

NOTE

The use status of the write protect function can be checked in parameters or by the write protect icon displayed on the display.

The following item is displayed.					
lcon	Description				
8	Write protect is in use (parameters cannot be changed)				

NOTE

If the write protect switch is set to "Protect" on the amplifier board, it is not possible to overwrite parameters. Furthermore, this state is maintained until the write protect switch is set to "Disable". To change parameters, disable the write protect function by using the preset password and set a new password.

The user must manage and remember a password that has been set. In the event that the user forgets the password, software write protection can be temporarily disabled by using a joker password.

Use of a joker password can be checked by the following parameters.

Menu path

HART	Device Setting ► Detailed setup ► Protect ► Write protect ► Software seal
Display	-

Check use of the joker password from the following.

Va	lue	Description
HART	Display	Description
Кеер	-	Normal
Break	-	The write protect function is disabled by the joker password

NOTE

When use of a joker password is required, inform the nearest Yokogawa Electric Corporation sales office.

4.17.2 Operation Levels (User Role)

On this product, parameters that can be accessed can be restricted by assigning operation levels (user roles) to parameter settings.

The following table summarizes the operation levels that can be assigned on this product.

Operation Dights	Parameter						
Operation Rights	Read	Write					
Operator	All parameters	Display parameter settings that do not affect processes can be set					
Maintenance	All parameters	Parameters that can be set by Operator levels and test- and adjustment-related parameters can be set.					
Specialist	All parameters	All parameters that can be written can be set					

By default, operation levels are disabled. When operation levels are disabled, the only levels that can be accessed is the Specialist levels.

To enable operation levels, a pass code must be set. Operation levels are enabled by setting a value other than "0" (zero) to the Maintenance or Specialist pass code. Operation levels are changed by this pass code. Different values must be set to the Maintenance and Specialist pass codes.

Operation Rights	Pass Code
Operator	A pass code is not required. From display: When a value other than the pass code set to Maintenance and Specialist is set, Operator levels are enabled. From communication: When "0" (zero) is set, Operator levels are enabled. Entering the incorrect PIN 5 times will cause AL-082: Incorrect PIN.
Maintenance	Maintenance pass code setting conditions • Value other than zero and different from the Specialist pass code • Operation levels are disabled by setting zero
Specialist	Specialist pass code setting conditions • Value other than zero and different from the , Maintenance pass code • Operation levels are disabled by setting zero

HART communication must be used to set and check parameters relating to operation levels. These operations are not possible on the display.

Perform setting and entry of pass codes, and checking of present operation levels by the following parameters.

Menu path

HART Device Setting ► Detailed setup ► Protect ► User role ► (see table below)

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D	IS	n

lay

Parameter		Description				
HART	Display	Description				
Set user role PIN	-	The Maintenance/Specialist pass code is set. Set this manually according to the interactive Operation Guide called "DD Method".				
Change user role	-	Enter the pass code to switch operation levels.				
Current role	-	The present operation levels are displayed. 0: Operator 1: Maintenance 2: Specialist				
Active role	-	The present active operation levels are displayed.				
Maintenance PIN	-	The Maintenance PIN is displayed only when Specialist levels are entered.				
Specialist PIN	-	The Specialist PIN is displayed only when Specialist levels are entered.				

When a pass code is not set to Specialist levels but only to Maintenance levels, the range of parameters that can be written to is the same as for Specialist levels. At this time "Specialist" and not "Maintenance" is displayed for parameter "Current role".

When 30 minutes elapses from the last writing of a parameter with Current role set to either Maintenance or Specialist, Current role automatically returns to Operator. Current role also returns to Operation when a zero is entered to "Change user role".

To disable operation levels, set a zero to the Maintenance and Specialist pass codes with Specialist levels enabled.

For details on access levels for each parameter, see Chapter 5 "Parameter Lists." Operation levels are not applicable to parameters common to HART communication such as Loop Test and Burst Mode.

The user must manage and remember pass codes that have been set. In the event that the user forgets the password, operation levels can be disabled by using a joker password.

NOTE

When use of a joker password is required, inform the nearest Yokogawa Electric Corporation sales office.

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5. Parameter Lists

This chapter shows parameter lists used for HART communication and the display.

Each parameter is set as specified at the time of ordering. Since other parameters are set with default values, be sure to refer to this chapter when changing them.

IMPORTANT

If this product is turned off before 30 seconds after setting the parameters, the settings will not be stored correctly. Keep the product turned on for over 30 seconds after setting the parameters.

NOTE

To obtain correct flow signals, it is necessary to set the nominal size, flow rate span and meter factor of the flow sensor. The nominal size and meter factor of the flow sensor are set on this product when shipped from the manufacturing factory. So, the customer is not required to set them.

If particular parameters are specified at the time of order, this product is shipped with the parameter set as specified. If a parameter is not specified at the time of order, that parameter needs to be set by the customer.

NOTE

The available functions and parameters displayed vary depending on communication and I/O codes specified at the time of ordering.

The parameter lists are configured by the following items.

Parameter Name	HART: Indicates the parameter name. Display: Indicates the parameter No.
Data Range	When data is select type, the selection is indicated. When data is numeric type, the setting range and number of digits past the decimal point are indicated. When data is alphanumeric type, the number of characters limitation is indicated. The parameter data at setting on the display is indicated in parentheses ().
R/W	Indicates parameters that can be displayed and set. When operation levels are enabled, the parameters that can be set vary according to the operation level that is set. R: Display only RW1: Display and setting, settable by all operation levels RW2: Display and setting, setting is limited to Maintenance and Specialist operation levels RW3: Display and setting, setting is limited to Specialist operation levels
Default Value	Indicates the default value that is set before shipment from the factory.
Unit	Indicates the data range unit.
Refer to	Indicates the page to refer to for details on parameter content.

NOTE

The parameter list is listed in the menu order of the display.

5.1 **Process Measurement Values**

Parameter Name	Data Danas	DAA	Default	Linit	Description	Refer	
HART	Display	Data Range	R/W	Value	Unit	Description	to
Process Variables ► Device variable ► Flow rate(%)	A10	-	R	0.0	%	The instantaneous flow rate (%) is displayed	P.57
Process Variables ► Device variable ► Flow rate	A20	-	R	0.0	Flow unit (C41)	The instantaneous flow rate is displayed	P.57
Process Variables ► Device variable ► Temperature(%)	A40	-	R	0.0	%	The measured temperature (%) is displayed	P.57
Process Variables ► Device variable ► Temperature	A41	-	R	0.0	Temperature unit (C30)	The measured temperature is displayed	P.57
Process Variables ► Device variable ► Total	A30	-	R	0.0	Totalizer unit (B41)	The totalized value is displayed	P.57
Process Variables ► Device variable ► Loop current	-	-	R	4.0	mA	The current value of the analog output is displayed	P.63

5.2 Standard Setting Items

Parameter Name	Parameter Name		inde	R/W	Default	Unit	Description	Refer
HART	Display	Data Na		1011	Value	Unit	Description	to
Device Settings ► Easy setup ► Flow span	B10 C45	0.0< to 99999.9		RW3	10.0 *1	Flow unit (C41)	The span of the instantaneous flow rate is set	P.44
Device Settings ► Easy setup ► Flow damping	B15 C50	0.0 to 200.0		RW3	4.0	s	The damping time constant of the instantaneous flow rate is set	P.46
Device Settings ► Easy setup ► Pulse/Status output mode	B20	Off Scaled pulse Unscaled pulse Frequency Alarm switch Limit switch	(0) (1) (2) (3) (4) (5)	RW3	Off (0) *1	-	The pulse/status output function is selected	P.71
Device Settings ► Easy setup ► Pulse output rate	B21	0.0< to 99999.9		RW3	1.0 *1	-	The pulse rate value is set	P.71
Device Settings ► Easy setup ► Frequency output span	B22	0.0 to 10000.0		RW3	10000.0	Hz	The frequency when the process value is 100% is set	P.72
Device Settings ► Easy setup ► Limit switch level	B23	-99999.9 to 99999.9		RW3	0.0	Limit switch unit (D19)	The threshold value of the limit switch is set	P.74
Device Settings ► Easy setup ► Display line upper	B30	Flow rate(%) Flow rate Temperature(%)	(0) (1) (2)	RW1	Flow rate(%) (0) ⁻¹	-	The content to display in the upper display is set	P.101
Device Settings ► Easy setup ► Display line lower	B31	Off Totalizer Temperature Analog input	(0) (1) (2) (4)	RW1	Off (0) *1	-	The content to display in the lower display is set	P.101
Device Settings ► Easy setup ► Totalizer start/stop	B40	Stop Start	(0) (1)	RW3	Stop (0) *1	-	Start/stop of the totalization function is set	P.58
Device Settings ► Easy setup ► Totalizer unit	B41	m³ km³ I mcf cf kcf USgal kUKgal kUKgal bbl kbl kbl kbb kkb (N)m³ k(N)m³ M(N)m³ (N)I (S)m³ k(S)m³ MSTU BTU kBTU MBTU SPE.	$\begin{array}{c} (0) \\ (1) \\ (2) \\ (3) \\ (4) \\ (5) \\ (6) \\ (7) \\ (8) \\ (9) \\ (10) \\ (11) \\ (12) \\ (13) \\ (14) \\ (15) \\ (16) \\ (17) \\ (13) \\ (14) \\ (15) \\ (16) \\ (17) \\ (18) \\ (19) \\ (20) \\ (21) \\ (22) \\ (23) \\ (24) \\ (25) \\ (26) \\ (27) \\ (28) \\ (29) \\ (30) \\ (31) \\ (32) \\ (33) \\ (34) \\ (35) \end{array}$	R	m ³ (0)	-	The totalized value unit is checked	P.58
Device Settings ► Easy setup ► Totalizer rate	B45	0.00001 to 99999.9		RW3	1.0 *1	-	The total rate is set	P.59
Device Settings ► Easy setup ► Totalizer reset/preset	B47	Not execute Reset Preset	(0) (1) (2)	RW3	Not execute (0)	-	Reset/preset of the totalization function is set	P.59
Device Settings ► Easy setup ► Totalizer preset value	B48	0.0 to 99999.9		RW3	0.0	Totalizer unit (B41)	The preset value of the totalization function is set	P.59
Device Settings ► Easy setup ► Totalizer reset mode	B49	Reset Hold only display Hold	(0) (1) (2)	RW3	Reset (0)	-	The totalization operation of the totalization function is set	P.60
Device Settings ► Easy setup ► Analog output select	B50	Flow rate Temperature	(0) (1)	RW3	Flow rate (0)	-	The process value to assign to analog output is set	P.63
Device Settings ► Easy setup ► Temperature LRV	B51 G11	-999.9 to 999.9		RW3	-40.0	Temperature unit (C30)	The scaling lower limit value (0%) of temperature measurement is set	P.61

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

Parameter Name		Data Banna	D/M	Default	Unit	Description	Refer
HART	Display	Data Range		Value			to
Device Settings ► Easy setup ►	B52	-999.9 to 999.9	RW3	250.0	Temperature	The scaling upper limit value	P.61
Temperature URV	G12				unit	(100%) of temperature	
					(C30)	measurement is set	

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

5.3 **Basic Setting Items**

Parameter Name	1	Data Range		R/W	Default	Unit	Description	Refer
HART	Display				Value			to
Device Settings ► Basic setup ► Tag	-	-		RW1	All Space *1	-	The tag is set	P.109
Device Settings ► Basic setup ►	C15	Liquid	(0)	RW3	Liquid (0) *1	-	The measured fluid is set	P.39
Fluid type		Gas	(1)					
		Water	(2)					
Dovice Settings N Pasis actur	C16	Volumo	(3)	D\\/2	Volume (0) *1		The measured flow rate is get	D 40
Flow select	010	Mass	(0)	RVVS	volume (0)	-	The measured now rate is set	P.40
		Standard/Normal	(2)					
		Energy	(3)					
		Energy(Heat difference)	(4)	ļ				
Device Settings ► Basic setup ►	C22	m ³	(0)	RW3	m ³ (0) ^{*1}	-	The physical unit of the	P.41
volume unit		km ³	(1)				volumetric flow rate is set	
		mcf	(3)					
		cf	(4)					
		kcf	(5)					
		USgal	(6) (7)					
		UKgal	(7)					
		kUKgal	(9)					
		mbbl	(10)					
		bbl	(11)					
Device Octions & Device octors &	005	KDDI	(12)	DIA/O	1		The demoit consists and	D.50
Density unit	F11	lb/cf	(0)	RVVS	kg/m² (0)	-	The density unit is set	P.50
		lb/USgal	(2)					
		lb/UKgal	(3)					
Device Settings ► Basic setup ►	C26	0.0< to 99999.9		RW3	1000.0 *1	Density unit	The fixed density is set	P.50
Fixed density	F12					(C25)		
	H26			DIAKO	1 (0) **			
Device Settings ► Basic setup ►	C27	kg t	(0)	RW3	kg (0) 1	-	The physical unit of the mass	P.41
Mass unit		lb	(1)				now rate is set	
		klb	(3)					
Device Settings ► Basic setup ►	F14	degC	(0)	RW3	degC (0) *1	-	The temperature unit is set	P.51
Temperature unit	C30	degF	(1)					
	545	K	(2)	DIAKO	45.0 %	-	T I C 11	
Eived temperature	F15	-999.9 to 999.9		RVV3	15.0	Iemperature	i ne fixed temperature is set	P.51
	001					(C30)		
Device Settings ► Basic setup ►	F16	-999.9 to 999.9		RW3	15.0 *1	Temperature	The temperature of the normal/	P.51
Base temperature	C32					unit	standard condition is set	
						(C30)		
Device Settings ► Basic setup ►	F17	kPa A	(0)	RW3	MPa A (1) *1	-	The pressure unit is set	P.52
	033	bar A	(1)					
		psi A	(3)					
		kPa G	(4)					
		MPa G	(5)					
		par G	(0)					
Device Settings Basic setup	F18	abs:0.0< to 99999.9	(1)	RW3	0 10133 *1	Pressure	The fixed pressure is set	P.52
Fixed pressure ¹²	C34	guage:-999999.9 *3 to				unit		
		99999.9				(C33)		
Device Settings ► Basic setup ►	F19	abs:0.0< to 99999.9		RW3	0.10133 *1	Pressure	The pressure of the normal/	P.52
Base pressure ¹²	C35	guage:-99999.9 ⁻³ to				unit	standard condition is set	
Device Settings Basic setup	F23	0.0< to 99999.9		RW/3	1.0.1	(000)	The deviation factor (ratio)	P 55
Device Settings P basic setup P	C36	0.0 < 10 99999.9		11100	1.0	-	for the density of the normal/	F.33
							standard condition is set	
Device Settings ► Basic setup ►	C37	(N)m ³	(0)	RW3	(N)m ³ (0) ^{*1}	-	The physical unit of the	P.42
Standard/Normal unit		k(N)m ³	(1)				Standard/Normal flow rate	
		M(N)m ³	(2)				is set	
		(S)m ³	(4)					
		k(S)m ³	(5)					
		M(S)m ³	(6)					
		(S)I (S)cf	(7)					
		k(S)cf	(o) (9)					
		M(S)cf	(10)					

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

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*2 If the software revision is R1.01.01 or R1.01.02, Fixed pressure and Base Pressure cannot be set to minus gauge pressure value, when Pressure unit is set to gauge pressure unit. Minus gauge pressure value will be obtained, setting the absolute pressure value in absolute pressure unit and returning to gauge pressure unit.

*3 The lower limit of gauge pressure is the value equivalent to 0 when converted to absolute pressure. This value is equal to the negative value of Air pressure setting.

Parameter Name			Data Danca	DAA	Default	Unit	Description	Refer
HART	Display	Data Range		FC/ VV	Value	onit	Description	to
Device Settings ► Basic setup ►	C38	kJ	(0)	RW3	kJ (0) *1	-	The physical unit of the heat/	P.42
Energy unit		MJ	(1)				heat difference is set	
		GJ	(2)					
		TJ	(3)					
		BTU	(4)					
		kBTU	(5)					
		MBTU	(6)					
Device Settings ► Basic setup ►	C40	/s	(0)	RW3	/h (2) *1	-	The time unit is set	P.42
Time unit		/min	(1)					
		/h	(2)					
		/d	(3)					

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.
 *2 If the software revision is R1.01.01 or R1.01.02, Fixed pressure and Base Pressure cannot be set to minus gauge pressure value, when Pressure unit is set to gauge pressure unit. Minus gauge pressure value will be obtained, setting the absolute pressure value in absolute pressure unit and returning to gauge pressure unit.
 *3 The lower limit of gauge pressure is the value equivalent to 0 when converted to absolute pressure. This value is equal to the negative value of Air pressure setting.

Parameter Name			Data Ra	nae		R/W	Default	Unit	Description	Refer
HART	Display		Dutu Hu				Value		2000.19.00.1	to
Device Settings ► Basic setup ►	C41	m³/s	(0)	(N)m³/h	(70)	R	m³/h (2)	-	The measurement unit is	P.43
Flow unit		m³/min	(1)	(N)m ³ /d	(71)				checked	
		m³/h	(2)	k(N)m ³ /s	(72)					
		km ³ /s	(3)	$k(N)m^3/b$	(73)					
		km ³ /min	(4)	k(N)m ³ /d	(75)					
		km ³ /h	(6)	M(N)m ³ /s	(76)					
		km ³ /d	(7)	M(N)m ³ /min	(77)					
		l/s	(8)	M(N)m ³ /h	(78)					
		l/min	(9)	M(N)m ³ /d	(79)					
		l/h	(10)	(N)l/s	(80)					
		I/d	(11)	(N)l/min	(81)					
		mct/s	(12)	(N)I/h	(82)					
		mct/min	(13)	(N)I/d	(83)					
		mcf/d	(14)	(S)m ³ /min	(85)					
		cf/s	(15)	(S)m ³ /h	(86)					
		cf/min	(17)	(S)m ³ /d	(87)					
		cf/h	(18)	k(S)m³/s	(88)					
		cf/d	(19)	k(S)m³/min	(89)					
		kcf/s	(20)	k(S)m³/h	(90)					
		kcf/min	(21)	k(S)m³/d	(91)					
		kcf/h	(22)	M(S)m³/s	(92)					
		kcf/d	(23)	M(S)m ³ /min	(93)					
		USgal/s	(24)	M(S)m ³ /h	(94)					
		USgal/min	(25)	1VI(S)m ³ /d	(95)					
		USgal/d	(20)	(3)//s (S)//min	(90)					
		kUSgal/s	(28)	(S)//h	(98)					
		kUSgal/min	(29)	(S)I/d	(99)					
		kUSgal/h	(30)	(S)cf/s	(100)					
		kUSgal/d	(31)	(S)cf/min	(101)					
		UKgal/s	(32)	(S)cf/h	(102)					
		UKgal/min	(33)	(S)cf/d	(103)					
		UKgal/h	(34)	k(S)cf/s	(104)					
		UKgal/d	(35)	k(S)ct/min	(105)					
		kUKgal/s	(30)	K(S)ct/h	(106)					
		kUKgal/min kUKgal/b	(38)	K(S)CI/U	(107)					
		kl lKgal/d	(39)	M(S)cf/min	(100)					
		mbbl/s	(40)	M(S)cf/h	(110)					
		mbbl/min	(41)	M(S)cf/d	(111)					
		mbbl/h	(42)	kJ/s	(112)					
		mbbl/d	(43)	kJ/min	(113)					
		bbl/s	(44)	kJ/h	(114)					
		bbl/min	(45)	kJ/d	(115)					
		bbl/h	(46)	MJ/s	(116)					
		bbl/d	(47)	MJ/min	(117)					
		KDDI/S	(48)	IVIJ/N	(110)					
		kbbl/h	(49) (50)	G /s	(119)					
		kbbl/d	(50)	G.I/min	(120)					
		ka/s	(52)	GJ/h	(122)					
		kg/min	(53)	GJ/d	(123)					
		kg/h	(54)	TJ/s	(124)					
		kg/d	(55)	TJ/min	(125)					
		t/s	(56)	TJ/h	(126)					
		t/min	(57)	TJ/d	(127)					
		t/h	(58)	BTU/s	(128)					
		lb/c	(59)		(129)					
		ID/S	(60)	BIU/N	(130)					
		lb/h	(62)	kBTU/s	(132)					
		lb/d	(63)	kBTU/min	(133)					
		klb/s	(64)	kBTU/h	(134)					
		klb/min	(65)	kBTU/d	(135)					
		klb/h	(66)	MBTU/s	(136)					
		klb/d	(67)	MBTU/min	(137)					
		(N)m ³ /s	(68)	MBTU/h	(138)					
		(N)m³/min	(69)	MBTU/d	(139)					
				SPE.	(140)					
Device Settings ► Basic setup ►	B10	0.0< to 99999.9				RW3	10.0 *1	Flow unit	The span of the instantaneous	P.44
Flow span	C45							(C41)	flow rate is set	
Device Settings Basic setup	B15	0.0 to 200.0				RW3	4.0	s	The damping time constant	P.46
Flow damping	C50								of the instantaneous flow	-

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors. *2 If the software revision is R1.01.01 or R1.01.02, Fixed pressure and Base Pressure cannot be set to minus gauge pressure value, when Pressure unit is set to gauge pressure unit. Minus gauge pressure value will be obtained, setting the absolute pressure value in absolute pressure unit and returning to gauge pressure unit.

*3 The lower limit of gauge pressure is the value equivalent to 0 when converted to absolute pressure. This value is equal to the negative value of Air pressure setting.

rate is set

5.4 Additional Setup

Parameter Name		Dete D		DAM	Default	11-14	Description	Refer
HART	Display	Data R	ange	R/W	Value	Unit	Description	to
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Frequency output select	D11	Flow rate Temperature	(0) (1)	RW3	Flow rate (0)	-	The process value to assign to frequency output is set	P.72
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Frequency output zero	D12	0.0 to 10000.0		RW3	0.0	Hz	The frequency when the process value is 0% is set	P.72
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Status output condition	D13	Not active Active	(0) (1)	R	Not active (0)	-	The state of status output is displayed	P.76
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Status output direction	D14	On active Off active	(0) (1)	RW3	On active (0)	-	The active direction of status output is selected	P.76
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Alarm switch select	D15	All alarm/warning All alarm System/Process alarm Process alarm Setting alarm Warning	(0) (1) (2) (3) (4) (5) (6)	RW3	All alarm/ warning (0)	-	The alarm to be output is selected	P.73
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Limit switch select	D16	Flow rate Temperature Totalizer	(0) (1) (3)	RW3	Flow rate (0)	-	The process value to assign to limit switch output is set	P.74
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Limit switch mode	D17	Low limit High limit	(0) (1)	RW3	Low limit (0)	-	The H side/L side to assign to limit switch output is set	P.74
Device Settings ► Detailed setup ► I/O ► Pulse/Status output ► Limit switch hysteresis	D18	0.0 to 99999.9		RW3	0.0	Limit switch unit (D19)	The hysteresis width of the limit switch output switching is set	P.74

DemonsternNerre										
	Diaplay		Data Ra	nge		R/W	Default Value	Unit	Description	Refer
	Display	m3/c	(0)	M(S)m3/b	(04)	В	walue		The unit of the threshold value	D74
I/O ► Pulse/Status output ►	019	m³/min	(0)	M(S)m ³ /d	(94)	ĸ	mº/n (2)	-	and hysteresis value for the	P.74
Limit switch unit		m³/h	(2)	(S)l/s	(96)				limit switch are displayed	
		m ³ /d	(3)	(S)I/min	(97)				1 3	
		km ³ /min	(4)	(S)I/d	(98)					
		km³/h	(6)	(S)cf/s	(100)					
		km³/d	(7)	(S)cf/min	(101)					
		l/s l/min	(8)	(S)cf/h (S)cf/d	(102)					
		l/h	(10)	k(S)cf/s	(103)					
		l/d	(11)	k(S)cf/min	(105)					
		mcf/s	(12)	k(S)cf/h	(106)					
		mct/min mcf/h	(13)	K(S)Cf/d M(S)cf/s	(107)					
		mcf/d	(15)	M(S)cf/min	(109)					
		cf/s	(16)	M(S)cf/h	(110)					
		cf/min	(17)	M(S)cf/d	(111)					
		cf/d	(10)	kJ/min	(112)					
		kcf/s	(20)	kJ/h	(114)					
		kcf/min	(21)	kJ/d	(115)					
		kcf/h	(22)	MJ/s MJ/min	(116)					
		USgal/s	(23)	MJ/h	(117)					
		USgal/min	(25)	MJ/d	(119)					
		USgal/h	(26)	GJ/s	(120)					
		USgal/d kl ISgal/s	(27)	GJ/min G I/b	(121)					
		kUSgal/min	(29)	GJ/d	(123)					
		kUSgal/h	(30)	TJ/s	(124)					
		kUSgal/d	(31)	TJ/min	(125)					
		UKgal/s UKgal/min	(32)	T.I/d	(126)					
		UKgal/h	(34)	BTU/s	(128)					
		UKgal/d	(35)	BTU/min	(129)					
		kUKgal/s	(36)	BTU/h	(130)					
		kUKgal/min kLIKgal/h	(37)	kBTU/s	(131)					
		kUKgal/d	(39)	kBTU/min	(133)					
		mbbl/s	(40)	kBTU/h	(134)					
		mbbl/min	(41)	kBTU/d	(135)					
		mbbl/d	(42)	MBTU/min	(136)					
		bbl/s	(44)	MBTU/h	(138)					
		bbl/min	(45)	MBTU/d	(139)					
		bbl/h	(46)	SPE.	(140)					
		kbbl/s	(47)	degF	(141)					
		kbbl/min	(49)	ĸ	(143)					
		kbbl/h	(50)	kPa A	(144)					
		kbbl/d ka/s	(51)	MPa A bar A	(145)					
		kg/min	(53)	psi A	(147)					
		kg/h	(54)	kPa G	(148)					
		kg/d	(55)	MPa G	(149)					
		t/min	(57)	psi G	(150)					
		t/h	(58)	m3	(152)					
		t/d	(59)	km3	(153)					
		lb/s	(60)	mcf	(154)					
		lb/h	(62)	cf	(155)					
		lb/d	(63)	kcf	(157)					
		klb/s	(64)	USgal	(158)					
		klb/h	(66)	UKgal	(159) (160)					
		klb/d	(67)	kUKgal	(161)					
		(N)m³/s	(68)	mbbl	(162)					
		(N)m³/min	(69)	bbl	(163)					
		(N)m ³ /h	(70)	kbbl	(164)					
		(N)m ³ /s	(71)	t	(165)					
		k(N)m ³ /min	(73)	lb	(167)					
		k(N)m³/h	(74)	klb	(168)					
		k(N)m ³ /d	(75)	(N)m ³	(169)					
		M(N)m ³ /min	(70)	M(N)m ³	(170)					
		M(N)m ³ /h	(78)	(N)I	(172)					
		M(N)m ³ /d	(79)	(S)m ³	(173)					
		(N)//s (N)//min	(80) (81)	к(S)m ³ M(S)m ³	(174) (175)					
		(N)l/h	(82)	(S)I	(176)					
		(N)l/d	(83)	(S)cf	(177)					
		(S)m ³ /s	(84)	k(S)cf	(178)					
		(S)m ^{-/} min (S)m ³ /h	(85) (86)	kJ	(179) (180)					
		(S)m³/d	(87)	MJ	(181)					
		k(S)m ³ /s	(88)	GJ	(182)					
		k(S)m ³ /min	(89)	TJ	(183)					
		k(S)m³/d	(90) (91)	KBTU	(164)					
		M(S)m ³ /s	(92)	MBTU	(186)					
		M(S)m ³ /min	(93)	SPE.	(187)					

Parameter Name			-	Default	11-24	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Device Settings ► Detailed setup ► Display ► Display period	D20	0.25s (0) 0.5s (1) 1s (2) 2s (3) 4s (4) 8s (5)	RW1	0.25s (0)	-	The update interval of the process value for the display is set	P.103
Device Settings ► Detailed setup ► Display ► Display startup	D21	Off (0) On (1)	RW1	Off (0)	-	The screen display at startup is selected	P.104
Device Settings ► Detailed setup ► Display ► Display NE107	D22	Off (0) On (1)	RW1	Off (0)	-	Display/hide of the NAMUR NE107 category is selected	P.95
Device Settings ► Detailed setup ► Display ► Display format flow	D23	Auto (0) 0 digit (1) 1 digit (2) 2 digit (3) 3 digit (4) 4 digit (5)	RW1	Auto (0)	-	The decimal point position of the instantaneous flow rate value is set	P.102
Device Settings ► Detailed setup ► Display ► Display format temperature	D24	0 digit (0) 1 digit (1) 2 digit (2) 3 digit (3) 4 digit (4)	RW1	Odigit (0)	-	The decimal point position of the temperature value is set	P.102
Device Settings ► Detailed setup ► Display ► Display format pressure	D25	0 digit (0) 1 digit (1) 2 digit (2) 3 digit (3) 4 digit (4)	RW1	Odigit (0)	-	The decimal point position of the pressure value is set	P.102
Device Settings ► Detailed setup ► I/O ► Analog output ► Analog output high limit	D30	4.0 to 21.6	RW3	21.6 *1	mA	The upper limit value of analog output is set Set from Analog output limit(Method)	P.64
Device Settings ► Detailed setup ► I/O ► Analog output ► Analog output low limit	D31	3.6 to 20.0	RW3	3.6 *1	mA	The lower limit value of analog output is set Set from Analog output limit(Method)	P.64
Diagnostics ► Signal controls ► Burnout	D35	High (0) Low (1)	R	High (0)	-	The direction of analog output when a burnout occurs is displayed	P.99
Diagnostics ► Signal controls ► Burnout recover	-	Off (0) On (1)	RW3	Off (0)	-	The restore operation when a burnout occurs is set	P.99
Device Settings ► Detailed setup ► Flow rate ► Flow lowcut	D10	1/2 or equivalent of minimum flow velocity to 99999.9	RW3	0.47 *1	Flow unit (C41)	The lowcut value of the instantaneous flow rate is set	P.46
Device Settings ► Detailed setup ► Flow user conversion ► Flow user conversion	D40	Off (0) On (1)	RW3	Off (0)	-	Whether or not to convert to user units is selected and displayed Set from User unit (Method)	P.48
Device Settings ► Detailed setup ► Flow user conversion ► Flow user unit	-	-	RW3	All Space	-	The name of the user- specified unit is set Set from User unit (Method)	P.49

Parameter Name					Default			Refer		
HART	Display		Data Ra	inge		R/W	Value	Unit	Description	to
Device Settings ► Detailed setup ►	D41	m³/s	(0)	(N)m³/h	(70)	R	m³/h (2)	-	The flow rate unit used for	P.48
Flow user conversion ►		m³/min	(1)	(N)m³/d	(71)				the conversion reference is	
Flow user base unit		m³/h	(2)	k(N)m³/s	(72)				displayed	
		m³/d	(3)	k(N)m³/min	(73)					
		km³/s	(4)	k(N)m ³ /h	(74)					
		km³/h	(5)	K(IN)ITI%d	(75)					
		km ³ /d	(0)	M(N)m ³ /min	(70)					
		l/s	(8)	M(N)m ³ /h	(78)					
		l/min	(9)	M(N)m ³ /d	(79)					
		l/h	(10)	(N)l/s	(80)					
		l/d	(11)	(N)l/min	(81)					
		mcf/s	(12)	(N)l/h	(82)					
		mcf/min	(13)	(N)I/d	(83)					
		mct/n	(14)	(S)m ³ /s	(84)					
		rnci/d	(15)	(S)m ³ /b	(60)					
		cf/min	(10)	(S)m ³ /d	(87)					
		cf/h	(17)	k(S)m ³ /s	(88)					
		cf/d	(19)	k(S)m³/min	(89)					
		kcf/s	(20)	k(S)m³/h	(90)					
		kcf/min	(21)	k(S)m³/d	(91)					
		kcf/h	(22)	M(S)m³/s	(92)					
		kcf/d	(23)	M(S)m ³ /min	(93)					
		USgal/s	(24)	M(S)m ³ /h	(94)					
		USgal/min	(25)	W(S)m ³ /a	(95)					
		USgal/II USgal/d	(20)	(3)//S	(90)					
		kUSgal/s	(28)	(S)/h	(98)					
		kUSgal/min	(29)	(S)I/d	(99)					
		kUSgal/h	(30)	(S)cf/s	(100)					
		kUSgal/d	(31)	(S)cf/min	(101)					
		UKgal/s	(32)	(S)cf/h	(102)					
		UKgal/min	(33)	(S)cf/d	(103)					
		UKgal/h	(34)	K(S)ct/S	(104)					
		UKgal/a	(35)	k(S)ci/min	(105)					
		kUKgal/min	(37)	k(S)cf/d	(100)					
		kUKgal/h	(38)	M(S)cf/s	(108)					
		kUKgal/d	(39)	M(S)cf/min	(109)					
		mbbl/s	(40)	M(S)cf/h	(110)					
		mbbl/min	(41)	M(S)cf/d	(111)					
		mbbl/h	(42)	kJ/s	(112)					
		mbbl/d	(43)	kJ/min	(113)					
		bbl/s	(44)	kJ/n	(114)					
		bbl/h	(46)	MJ/s	(115)					
		bbl/d	(47)	MJ/min	(117)					
		kbbl/s	(48)	MJ/h	(118)					
		kbbl/min	(49)	MJ/d	(119)					
		kbbl/h	(50)	GJ/s	(120)					
		kbbl/d	(51)	GJ/min	(121)					
		kg/s	(52)	GJ/n	(122)					
		kg/min	(53)	GJ/U T I/e	(123)					
		kg/d	(55)	TJ/min	(12-7)					
		t/s	(56)	TJ/h	(126)					
		t/min	(57)	TJ/d	(127)					
		t/h	(58)	BTU/s	(128)					
		t/d	(59)	BTU/min	(129)					
		lb/s	(60)	BTU/h	(130)					
		lb/h	(62) (62)		(131) (132)					
		lb/d	(63)	kBTU/min	(133)					
		klb/s	(64)	kBTU/h	(134)					
		klb/min	(65)	kBTU/d	(135)					
		klb/h	(66)	MBTU/s	(136)					
		klb/d	(67)	MBTU/min	(137)					
		(N)m ³ /s	(68)	MBTU/h	(138)					
		(N)m³/min	(69)	MR10/q	(139)			ļ		
Device Settings ► Detailed setup ►	D43	0.0< to 99999.9				RW3	1.0	-	The conversion factor to user	P.49
Flow user conversion									Set from Lloor unit (Method)	
	1								Section User unit (wethod)	

Parameter Name		Data Banna	DAA	Default	Unit	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input unit	D52	degC (0) degF (1) K (2) kPa A (3) MPa A (4) bar A (5) psi A (6) kPa G (7) MPa G (8) bar G (9) psi G (10) kg/m ³ (11) lb/USgal (13) lb/UKgal (14)	R	degC (0)	-	The analog input unit is displayed	P.68
Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input LRV	D53	-99999.9 to 99999.9	RW3	0.0 *1	Analog input unit (D52)	The value when the process value used for analog input is 0% is set	P.68
Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input URV	D54	-99999.9 to 99999.9	RW3	100.0 *1	Analog input unit (D52)	The value when the process value used for analog input is 100% is set	P.68
Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input low limit	D55	3.6 to 20.0	RW3	3.6	mA	The lower limit value of analog input is set	P.68
Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input high limit	D56	4.0 to 21.6	RW3	21.6	mA	The upper limit value of analog input is set	P.68
Device Settings ► Detailed setup ► I/O ► Analog input ► Analog input fix value	D57	3.6 to 21.6	RW3	4.0	mA	The fixed value of analog input is set	P.100

5.5 Detector Setup

Parameter Name				-	Default		B 1.4	Refer
HART	Display	Data Range		R/W	Value	Unit	Description	to
Device Settings ► Detailed setup ► Sensor Information ► Nominal size	E10	15mm 25mm 40mm 50mm 80mm 100mm 150mm 200mm 250mm 300mm 400mm	(1) (2) (3) (4) (5) (6) (7) (8) (9) (10) (11)	RW3	25 mm (2) "	-	The diameter is selected	P.77
Device Settings ► Detailed setup ► Sensor Information ► Body type	E20	General One size down Two size down High pressure Dual sensor	(0) (1) (2) (4) (6)	RW3	General (0) *1	-	The body type is selected	P.77
Device Settings ► Detailed setup ► Sensor Information ► Sensor type	E30	Standard Standard w/ temp sensor High temperature High temperature w/ temp sensor Cryogenic Long neck Long neck Long neck w/ temp sensor	(0) (1) (2) (3) (4) (6) (7)	RW3	Standard (0) ⁻¹	-	The sensor type is selected	P.77
Device Settings ► Detailed setup ► Sensor Information ► Connection type	E22	Integral Remote	(0) (1)	RW3	Integral (0) *1	-	Integral/remote sensor is selected	P.77
Device Settings ► Detailed setup ► Sensor Information ► K factor unit	E40	p/l p/USgal p/UKgal	(0) (1) (2)	RW3	p/l (0) ^{*1}	-	The K factor unit is selected	P.77
Device Settings ► Detailed setup ► Sensor Information ► K factor	E41	0.0< to 99999.9		RW3	68.6 ^{*1}	K factor unit (E40)	The K factor is set	P.77
Device Settings ► Detailed setup ► Sensor Information ► Process temperature	E44	-29 to +250 degC -40 to +250 degC -40 to +450 degC -40 to +400 degC -196 to +250 degC	(0) (1) *2*5 (2) *2*6 (3) *2*6 (4)	R '3/ RW3 '4	0.0 *1	degC	The allowable temperature is displayed '3/set '4	P.77
Device Settings ► Detailed setup ► Sensor Information ► Max pressure	E45	0.0 to 99999.9		R *3/ RW3 *4	0.0 *1	MPa at 38 degC	The maximum allowable pressure is displayed ^{*3} /set ^{*4}	P.77
Device Settings ► Detailed setup ► Sensor Information ► Sensor backup/restore	E46	Not execute Backup parameter Restore parameter Restore parameter(factory)	(0) (1) (3) (4)	RW3	Not execute (0)	-	Backup/restore of sensor information	P.79
Device Settings ► Detailed setup ► Sensor Information ► Sensor backup/restore result	E47	Unknown Pass Failure Running	(0) (1) (2) (3)	R	Unknown (0)	-	The backup/restore result of sensor information is displayed	P.79
Device Settings ► Detailed setup ► Sensor Information ► Sensor S/N	-	-		R *3/ RW3 *4	All Space *1	-	Sensor serial No. displayed *3/ set *4	P.77

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

*2 For option code/LAT, the measured lower limit temperature will be -50 degC instead of -40 degC.

*3: For R1.01.01 or R1.01.02

*4: For R1.01.03 or more

*5: For Body & shedder bar material code W \square , the measured temperature range will be -29 to +250 degC.

*6: For Body & shedder bar material code W⁻, the measured temperature range will be -29 to +400 degC.

5.6 Adjust

Parameter Name		Data Barrea			Default	l la it	Description	Refer
HART	Display	Data Range	K/	/ • •	Value	Unit	Description	to
Device Settings ► Detailed setup ►	-	Fixed	F	R	Fixed *1	-	The compensation method of	P.54
Compensation setup ►		Analog input					density and specific enthalpy	
Calculation type		Compensation T					is confirmed	
		Compensation T/P						
		Saturated steam P						
		Superheated steam T/P						
Device Settings ► Detailed setup ►	F01	Saturated steam (0)) RV	W3	Saturated	-	The steam type is selected	P.53
Compensation setup ► Steam type		Superheated steam (1	ı)		steam (0) *1			
Device Settings ► Detailed setup ►	F03	Not used (0)) RV	W3	Not used	-	The compensation type is	P.54
Compensation setup ►		Built-in temp. (1	1)		(0) *1		selected	
Compensation type		Built-in temp. & A-in press. (2	2)					
		A-in temp. (4	4)					
		A-in press. (3	5)					
Dovice Sottings N Detailed actur	E04	Fixed (0			Eived (0)		The temperature	D61
T/P setup Temperature	G10	Built-in (1)) r 1)	n.	Fixed (0)	-	measurement method is	F.01
Temperature select		Analog input (2	2)				checked	
Device Settings Detailed setup	F05	Fixed (0) F	R	Fixed (0)	-	The pressure measurement	P62
T/P setup ► Pressure ► Pressure	G20	Analog input (2	2)				method is checked	1.02
select			<i>`</i>					
Device Settings ► Detailed setup ►	F06	Off (0)) F	R	Off (0) *1	-	The process value assigned to	P.67
I/O ► Analog input ►		Temperature (1	1)				analog output is displayed	
Analog input select		Presseure (2	2)					
		Density (3	3)					
		Delta temperature (4	1)					
Device Settings ► Detailed setup ►	C25	kg/m ³ (0	0) RV	W3	kg/m ³ (0)	-	The density unit is set	P.50
Compensation setup Density unit	F 11	ID/CT (1						
		lb/UKgal (3	3)					
Device Settings Detailed setup	C26	0.0 <to 99999.9<="" td=""><td>-/ R\</td><td>N3</td><td>1000.0 *1</td><td>Density unit</td><td>The fixed density is set</td><td>P 50</td></to>	-/ R\	N3	1000.0 *1	Density unit	The fixed density is set	P 50
Compensation setup ► Fixed density	F12		1		1000.0	(C25)		1.00
	H26					()		
Device Settings ► Detailed setup ►	F13	0.0< to 99999.9	RV	W3	1000.0 *1	Density unit	The density of the normal	P.51
Compensation setup ► Base density						(C25)	condition is set	
Device Settings ► Detailed setup ►	F14	degC (0)) RV	W3	degC (0) *1	-	The temperature unit is set	P.51
Compensation setup ►	C30	degF (1	1)					
Iemperature unit		K (2	2)					
Device Settings ► Detailed setup ►	F15	-999.9 to 999.9	RV	W3	15.0 *1	Temperature unit	The fixed temperature is set	P.51
Compensation setup ►	C31					(C30)		
	F10	000 0 to 000 0		M2	45.0 *1	Town exeture unit	The temperature of the normal/	DE1
Compensation setup	C32	-999.9 10 999.9		003	15.0	(C30)	standard condition is set	F.51
Base temperature	002					(000)		
Device Settings ► Detailed setup ►	F17	kPaA (0)) RV	W3	MPa A (1) *1	-	The pressure unit is set	P.52
Compensation setup ► Pressure unit	C33	MPaA (1	í)	-				-
		bar A (2	2)					
		psi A (3	3)					
		kPaG (4	4)					
		MPaG (5	<i>)</i>					
		psi G (7	7)					
Device Settings Detailed setup	F18	abs:0.0< to 99999 9	/ R\	N3	0 10133 1	Pressure unit	The fixed pressure is set	P 52
Compensation setup	C34	quage:-99999.9 *4 to 99999.9			0.10100	(C33)		1.02
Fixed pressure *2*3						()		
Device Settings ► Detailed setup ►	F19	abs:0.0< to 99999.9	RV	W3	0.10133 *1	Pressure unit	The pressure of the normal/	P.52
Compensation setup ►	C35	guage:-99999.9 *4 to 99999.9				(C33)	standard condition is set	
Base pressure *2*3								
Device Settings ► Detailed setup ►	-	kPa A (0	D) F	R	MPaA(1)	-	The air pressure unit is	-
Compensation setup ►		MPa A (1	1)				displayed	
Air pressure unit		bar A (2	2)					
Device Cettings & Det " 1 1 1	500		<i>י</i> ו –	A/2	0.40400.**	Ain mag ''	Desseurs is - dd- dd- d	
Device Settings Detailed setup	F20	0.0~ 10 33333.3	R	vv3	0.10133 '	Air pressure unit	Pressure is added to the	-
							pressure is set at calculation of	
							absolute pressure	
Device Settings ► Detailed setup ►	F23	0.0< to 99999.9	RV	W3	1.0 *1	-	The deviation factor (ratio)	P.55
Compensation setup Deviation	C36						for the density of the normal/	

*1 Values are determined accords in formation, sizing sheet or information about the combination of sensors. *2 If the software revision is R1.01.01 or R1.01.02, Fixed pressure and Base Pressure cannot be set to minus gauge pressure value, when Pressure unit is set to gauge pressure unit. Minus gauge pressure value will be obtained, setting the absolute pressure value in absolute pressure unit and returning to gauge pressure unit. *3 Fixed pressure and Base Pressure settings will change to maintain the value converted to absolute pressure in changing Air pressure setting, when

Pressure unit is set to gauge pressure unit.

*4 The lower limit of gauge pressure is the value equivalent to 0 when converted to absolute pressure. This value is equal to the negative value of Air pressure setting.

Parameter Name				Default			Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Device Settings ► Detailed setup ► Compensation setup ► Dryness	F24	90.0 to 100.0	RW3	100.0 *1	%	The dryness level is set	-
Device Settings ► Detailed setup ► Compensation setup ► Temperature coefficient 1	F30	-99999.9 to 99999.9	RW3	0.0	1 / Temperature unit (1/C30)	The primary temperature factor of density calculation is set	-
Device Settings ► Detailed setup ► Compensation setup ► Temperature coefficient 2	F31	-99999.9 to 99999.9	RW3	0.0	1 / Temperature unit ² (1/C30 ²)	The secondary temperature factor of density calculation is set	-
Device Settings ► Detailed setup ► Compensation setup ► Enthalpy unit	F35	kJ/kg (0) MJ/kg (1) GJ/kg (2) TJ/kg (3) BTU/lb (4)	RW3	kJ/kg (0) [⊶]	-	The specific enthalpy unit is set	P.53
Device Settings ► Detailed setup ► Compensation setup ► Fixed enthalpy	F36	0.0< to 99999.9	RW3	1000.0 *1	Enthalpy unit (F35)	The fixed specific enthalpy is set	P.53
Device Settings ► Detailed setup ► Compensation setup ► Heat difference select	F37	Built-in(H)/Analog input(L) (0) Analog input(H)/Built-in(L) (1) Analog input(delta T) (2)	RW3	Built-in(H)/ Analog input(L) (0)	-	The method of use of the fluid temperature is selected	P.55
Device Settings ► Detailed setup ► Compensation setup ► Heat difference conv unit	F38	(kJ/kg)/K (0) (MJ/m³)/K (1) (BTU/LSgal)/degF (2) (BTU/LSgal)/degF (3) (BTU/LKgal)/degF (4) (BTU/LSgal)/degF (5)	RW3	(kJ/kg)/K (0)	-	The unit of heat conversion factor is selected	P.56
Device Settings ► Detailed setup ► Compensation setup ► Heat difference conv factor	F39	0.0< to 99999.9	RW3	1.0	Heat difference conv unit (F38)	The heat conversion factor is set	P.56
Device Settings ► Detailed setup ► Compensation setup ► Density	F40 K38	-99999.9 to 99999.9	R	0.0	Density unit (C25)	The density is displayed	P.57
Device Settings ► Detailed setup ► Compensation setup ► Density ratio	F41	-99999.9 to 99999.9	R	0.0	-	The density ratio used for Standard/Normal flow rate measurement is displayed	P.57
Device Settings ► Detailed setup ► Compensation setup ► Enthalpy	F42	-99999.9 to 99999.9	R	0.0	Enthalpy unit (F35)	The specific enthalpy used for heat measurement is displayed at the set unit	P.57
Device Settings ► Detailed setup ► Compensation setup ► Delta temperature	F43	-99999.9 to 99999.9	R	0.0	Temperature unit (C30)	The temperature difference used for heat difference measurement is displayed	P.57
Device Settings ► Detailed setup ► Compensation setup ► Delta enthalpy	F44	-99999.9 to 99999.9	R	0.0	Enthalpy unit (F35)	The specific enthalpy used for heat measurement is displayed	P.57

*1 Values are determined according information, sizing sheet or information about the combination of sensors.

*2 If the software revision is R1.01.01 or R1.01.02, Fixed pressure and Base Pressure cannot be set to minus gauge pressure value, when Pressure unit is set to gauge pressure unit. Minus gauge pressure value will be obtained, setting the absolute pressure value in absolute pressure unit and returning to gauge pressure unit.

*3 Fixed pressure and Base Pressure settings will change to maintain the value converted to absolute pressure in changing Air pressure setting, when Pressure unit is set to gauge pressure unit.

*4 The lower limit of gauge pressure is the value equivalent to 0 when converted to absolute pressure. This value is equal to the negative value of Air pressure setting.

5.7 Temperature/Pressure Measurement Setup

Parameter Name		Data Panga	DAM	Default	Unit	Description	Refer
HART	Display	Data Range	FK/W	Value	Unit	Description	to
Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature select	F04 G10	Fixed (0) Built-in (1) Analog input (2)	R	Fixed (0)	-	The temperature measurement method is checked	P.61
Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature LRV	B51 G11	-999.9 to 999.9	RW3	-40.0	Temperature unit (C30)	The scaling lower limit value (0%) of temperature measurement is set	P.61
Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature URV	B52 G12	-999.9 to 999.9	RW3	250.0	Temperature unit (C30)	The scaling upper limit value (100%) of temperature measurement is set	P.61
Device Settings ▶ Detailed setup T/P setup ▶ Temperature Temperature damping	G13	0.0 to 200.0	RW3	4.0	s	The damping time constant of the temperature measurement is set	P.61
Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature gain	G15	0.0< to 99999.9	RW3	1.0	-	The compensation factor (gain) of temperature measurement is set	P.62
Device Settings ► Detailed setup ► T/P setup ► Temperature ► Temperature offset	G16	-999.9 to 999.9	RW3	0.0	Temperature unit (C30)	The compensation value (offset) of temperature measurement is set	P.62
Device Settings ► Detailed setup ► T/P setup ► Temperature ► Selected temperature	-	-9999.9 to 9999.9	R	0.0	Temperature unit (C30)	The fluid temperature is displayed	-
Device Settings ► Detailed setup ► T/P setup ► Pressure ► Selected pressure	-	-9999.9 to 9999.9	R	0.0	Pressure unit (C33)	The fluid pressure is displayed	-

5.8 Adjustment Functions

Parameter Name		Data Banga		D/M	Default	Unit	Description	Refer
HART	Display	Data Kange		K/ W	Value		Description	to
Maintenance ► Adjustment ►	H05	Not execute	(0)	RW2	Not execute	-	Adjustment of analog output is	P.65
Analog output trim Analog output trim mode		4mA 20mA	(1)		(0)		executed, executed from Analog output	
		2010 1	(-)				trim(Method)	
Maintenance ► Adjustment ►	H06	Not execute	(0)	RW2	Not execute	-	The adjustment value of analog	P.65
Analog output trim		Execute	(1)		(0)		output is cleared	
Maintenance ► Adjustment ►	H07	3.6 to 20.0		RW2	40	mA	The measured value at 4 mA	P 65
Analog output trim ►							adjustment is set,	
Reference meter(4mA)							set from Analog output	
	100	4.0 to 21.6			20.0	mA	The measured value at 20 mA	Des
Analog output trim	1100	4.0 10 2 1.0		11112	20.0		adjustment is set,	F.05
Reference meter(20mA)							set from Analog output	
							trim(Method)	
Analog output trim	HIU	-1.0 to 1.0		R	0.0	[%]	l ne 4 mA adjustment value is displayed	P.65
Analog output trim(4mA)								
Maintenance ► Adjustment ►	H11	-1.0 to 1.0		R	0.0	%	The 20 mA adjustment value is	P.65
Analog output trim ► Analog output trim(20mA)							displayed	
Maintenance ► Adjustment ►	H12	Not execute	(0)	RW2	Not execute	-	Adjustment of analog input is	P.69
Analog input trim ►		4mA	(1)		(0)		executed,	
Analog input trim mode		8mA	(2)				Execute from Analog input	
		16mA	(3)					
		20mA	(5)					
Maintenance ► Adjustment ►	H13	Not execute	(0)	RW2	Not execute	-	The adjustment value of analog	P.69
Analog input trim clear		Execute	(1)		(0)		output is cleared	
Maintenance ► Adjustment ►	H14	-10.0 to 10.0		R	0.0	%	The 4 mA adjustment value is	P.69
Analog input trim							displayed	
Analog Input trim(4mA)	LI15	10.0 to 10.0			0.0	0/.	The 9 mA adjustment value is	Deo
Analog input trim		-10.0 10 10.0			0.0	70	displayed	F.05
Analog input trim(8mA)								
Maintenance ► Adjustment ►	H16	-10.0 to 10.0		R	0.0	%	The 12 mA adjustment value is	P.69
Analog input trim(12mA)							displayed	
Maintenance ► Adjustment ►	H17	-10.0 to 10.0		R	0.0	%	The 16 mA adjustment value is	P.69
Analog input trim (16mA)							displayed	
Maintenance ► Adjustment ►	H18	-10.0 to 10.0		R	0.0	%	The 20 mA adjustment value is	P.69
Analog input trim							displayed	
Analog input trim(20mA)								
Maintenance ► Adjustment ► Flow rate gain	H20	0.0< to 99999.9		RW2	1.0	-	An arbitrary compensation factor (gain) is set	P.81
Maintenance ► Adjustment ►	H40	Off	(0)	RW2	Off (0)	-	Whether or not to use instrument	P.84
Instrument error adjust ► Instrument		On	(1)				error correction is selected	
error adjust		0.0 to 10000.0			0.0		Vertex frequency (f1) of No. 1	D 94
Instrument error adjust ► Adjust	-	0.01010000.0		11112	0.0	112	break point	F.04
vortex frequency 1								
Maintenance ► Adjustment ►	-	-50.0 to 50.0		RW2	0.0	%	Compensation value (d1) of No.1	P.84
value 1							broak point	
Maintenance ► Adjustment ►	-	0.0 to 10000.0		RW2	0.0	Hz	Vortex frequency (f2) of No.2	P.84
Instrument error adjust ► Adjust							break point	
Maintenance Adjustment	-	-50.0 to 50.0		RW2	0.0	%	Compensation value (d2) of No.2	P.84
Instrument error adjust Adjust							break point	
value 2				DIAG				5.01
Instrument error adjust ► Adjust	-	0.0 to 10000.0		KW2	0.0	HZ	vortex frequency (f3) of No.3 break point	P.84
vortex frequency 3								
Maintenance ► Adjustment ►	-	-50.0 to 50.0		RW2	0.0	%	Compensation value (d3) of No.3	P.84
Instrument error adjust ► Adjust value 3							break point	
Maintenance Adjustment	-	0.0 to 10000.0		RW2	0.0	Hz	Vortex frequency (f4) of No.4	P.84
Instrument error adjust Adjust							break point	
Vortex trequency 4		50.0 to 50.0		D\A/2		0/	Companyation value (d4) of No.4	
Instrument error adjust Adjust		-50.0 10 50.0			0.0	10	break point	F.04
value 4								

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

IM 01F07A02-01EN
Parameter Name		Data Damas		DAM	Default	Unit	Description	Refer
HART	Display	Data Range		R/W	Value	Unit	Description	to
Maintenance ► Adjustment ► Instrument error adjust ► Adjust vortex frequency 5	-	0.0 to 10000.0		RW2	0.0	Hz	Vortex frequency (f5) of No.5 break point	P.84
Maintenance ► Adjustment ► Instrument error adjust ► Adjust value 5	-	-50.0 to 50.0		RW2	0.0	%	Compensation value (d5) of No.5 break point	P.84
Maintenance ► Adjustment ► Reynolds adjust ► Reynolds adjust	H25	Off On	(0) (1)	RW2	Off (0)	-	Execution of Reynolds number correction is selected	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Viscosity unit	H28	mPa·s Pa·s cP P m2/s cSt St	(0) (1) (2) (3) (4) (5) (6)	RW2	mPa·s (0) *1	-	The viscosity factor unit is selected	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Viscosity	H27	0.0< to 99999.9		RW2	1.0 *1	Viscosity unit (H28)	The viscosity factor is set	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Reynolds number	H24	-99999.9 to 99999.9		R	0.0	-	The Reynolds number is displayed	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Adjust Reynolds number 1	-	0.0 to 99999.9		RW2	5500.0	-	Reynolds number of No.1 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Re adjust value 1	-	-50.0 to 50.0		RW2	-11.4	%	Compensation value of No.1 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Adjust Reynolds number 2	-	0.0 to 99999.9		RW2	8000.0	-	Reynolds number of No.2 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Re adjust value 2	-	-50.0 to 50.0		RW2	-6.5	%	Compensation value of No.2 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Adjust Reynolds number 3	-	0.0 to 99999.9		RW2	12000.0	-	Reynolds number of No.3 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Re adjust value 3	-	-50.0 to 50.0		RW2	-3.6	%	Compensation value of No.3 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Adjust Reynolds number 4	-	0.0 to 99999.9		RW2	20000.0	-	Reynolds number of No.4 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Re adjust value 4	-	-50.0 to 50.0		RW2	-1.0	%	Compensation value of No.4 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Adjust Reynolds number 5	-	0.0 to 99999.9		RW2	40000.0	-	Reynolds number of No.5 break point	P.81
Maintenance ► Adjustment ► Reynolds adjust ► Re adjust value 5	-	-50.0 to 50.0		RW2	0.0	%	Compensation value of No.5 break point	P.81
Maintenance ► Adjustment ► Expansion factor adjust	H30	Off	(0)	RW2	Off (0)	-	Whether or not to use expansion factor is selected	P.85

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

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5.9 Test/Simulation

Parameter Name		Data Panga	DAM	Default	Unit	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Maintenance ► Test/Simulation ► Test/Simulation ► Test mode	J05	Off(0)Analog output(1)Pulse output(2)Status output(3)	RW2	Off (0)	-	Test mode and target are selected	P.118
Maintenance ► Test/Simulation ► Test/Simulation ► Test mode ► Test analog output	J10	-2.5 to 110.0	RW2	0.0	%	The test value (%) of analog output is set, Set from Test/ Simulation(method)	P.118
Maintenance ► Test/Simulation ► Test/Simulation ► Test mode ► Test pulse output	J20	0.0 to 10000.0	RW2	0.0	Hz	The test value (Hz) of pulse output is set, Set from Test/ Simulation(method)	P.118
Maintenance ► Test/Simulation ► Test/Simulation ► Test mode ► Test status output	J30	Off(Open) (0) On(Close) (1)	RW2	Off(Open) (0)	-	Test output of status output is set, Set from Test/ Simulation(method)	P.118
Maintenance ► Test/Simulation ► Test/Simulation ► Simulation mode	J31	All Off(0)Vortex frequency(1)Vortex frequency(HW)(2)Built-in temperature(3)Analog input(5)	RW2	All Off (0)	-	Simulation mode and target are selected	P.120
Maintenance ► Test/Simulation ► Test/Simulation ► Simulation mode ► Simulation vortex frequency	J32 K28	0.0 to 10000.0	RW2	0.0	Hz	The simulation value (Hz) of the vortex frequency is set, Set from Test/Simulation(method)	P.120
Maintenance ► Test/Simulation ► Test/Simulation ► Simulation mode ► Simulation vortex frequency(HW)	J33	0.0 to 10000.0	RW2	0.0	Hz	The simulation value (Hz) of the vortex frequency (hardware) is set, Set from Test/Simulation(method)	P.120
Maintenance ► Test/Simulation ► Test/Simulation ► Simulation mode ► Simulation built-in temperature	J34	-999.9 to 999.9	RW2	0.0	Temperature unit (C30)	The simulation value of the built-in temperature is set, Set from Test/Simulation(method)	P.120
Maintenance ► Test/Simulation ► Test/Simulation ► Simulation mode ► Simulation analog input(mA)	J36	3.6 to 21.6	RW2	4.0	mA	The simulation value (mA) of the analog input is set, Set from Verification Exe(method)	P.120
Maintenance ► Test/Simulation ► Auto release time	J40	10min (0) 30min (1) 60min (2) 3h (3) 6h (4) 12h (5)	RW2	30min (1)	-	The time up to automatic cancellation of the test mode and simulation mode is set	P.121
Maintenance ► Test/Simulation ► Display test	J45	Not execute (0) Execute (1) All on (2) All off (3) Only numeric (4) Only unit (5) Only icon (6)	RW1	Not execute (0)	-	The test pattern and whether or not to execute the display test are selected	P.105
Maintenance ► Test/Simulation ► Squawk	-	Off On Once	RW1	Off	-	Whether or not to execute the display's squawk function is selected	P.106
Maintenance ► Test/Simulation ► Device reset	-	Not execute Execute	RW2	Not execute	-	Whether or not to execute a device restart is selected	P.123
Maintenance ► Test/Simulation ► Sensor reset	-	Not execute Execute	RW2	Not execute	-	Whether or not to execute a sensor circuit restart is selected	P.123

5.10 Maintenance

Name Name <th< th=""><th>Parameter Name</th><th>Diamlari</th><th>Data Range</th><th>R/W</th><th>Default</th><th>Unit</th><th>Description</th><th>Refer</th></th<>	Parameter Name	Diamlari	Data Range	R/W	Default	Unit	Description	Refer
Name Participation Cols B0001 /L (b) B0000 /L (b) B0001 /L (b) B0000 /L (b) B0000 /L (b) B0000 /L (b) B0000 /L (c) B00000 /L (c) B00000 /L (c) B0000 /L (c) B0000 /L (c) B0000 /L (c)	TAKI	Display			value			10
agenational by advanced by ad	Maintenance ► Signal controls ►	-	Up to 19200 Hz	R	Up to 19200	-	The signal band is displayed.	P.86
Image income in the second income i	Signal band		Up to 9600 Hz		Hz			
upper location upper			Up to 4800 Hz					
Lipe isolo investige Lipe isolo investige <th< td=""><td></td><td></td><td>Up to 2400 Hz</td><td></td><td></td><td></td><td></td><td></td></th<>			Up to 2400 Hz					
Image intermedee Image intermedee<			Up to 600 Hz					
Image: Instance Image: Ima			Up to 300 Hz					
Image: Solution of the second seco			Up to 150 Hz					
Image:			Up to 75.0 Hz					
Lub is 18 Hr Up is 38 Hr Up is 32 Hr Up is 32 Hr Lub is 18 Hr Up is 32 Hr Lub is 18 Hr Hr Lub is 18 Hr Hr Lub is 18 Hr Lub is 18 Hr <td></td> <td></td> <td>Up to 37.5 Hz</td> <td></td> <td></td> <td></td> <td></td> <td></td>			Up to 37.5 Hz					
Lip bit 30 HP Up bit 30 HP P36 Maintenance > Signal controls > K0 C10 2.00 FN0 1.00 - The tigger level is set P36 Maintenance > Signal controls > K0 C10 2.00 FN0 1.00 - The tigger level is set P36 Maintenance > Signal controls > K0 C20 Advo(montor) FN0 Note information and particle information and particle is set P36 Maintenance > Signal controls > K0 C20 2.01 L2 0 R0 R0 - The none balance mode is elevel information and particle is set P36 Maintenance > Signal controls > K12 201 L2 0 R0 R0 R0 R0 The none balance wake weter P36 Maintenance > Signal controls > K12 200909.0 R R0			Up to 18.8 Hz					
Image: Interpretation in the second interpretation interpretation in the second interpretation in the second interpretation interpretation in the second interpretation in the second interpretation interp			Up to 9.38 Hz					
Line Line <thlin< th=""> Line Line L</thlin<>								
Line Line <thline< th=""> Line Line <thl< td=""><td></td><td></td><td>Up to 2.34 Hz</td><td></td><td></td><td></td><td></td><td></td></thl<></thline<>			Up to 2.34 Hz					
Image in the set of t			Up to 0.59 Hz					
L Up to 0.15 Hz Up to 0.07 Hz NM NM <th< td=""><td></td><td></td><td>Up to 0.29 Hz</td><td></td><td></td><td></td><td></td><td></td></th<>			Up to 0.29 Hz					
Image in the large in			Up to 0.15 Hz					
Maintenance > Signal controls K10 0.12 0.0 KN3 1.0 - The trigger level is est PRB Maintenance > Signal controls K20 0.12 0.0 KN3 1.0 - The signal level is est PRB Maintenance > Signal controls K2 Auto (0) KN3 Auto - The object halone mode is ested. PRB Maintenance > Signal controls K2 Auto (0) KN3 Auto - The noise balance mode is Auto PRB Maintenance > Signal controls K2 Colo 2.0 RN3 0.0 rss The noise balance mode is Auto PRB Maintenance > Signal controls K2 Colo 2.0 R 0.0 rss The flow velocity is display - Maintenance > Signal controls K2 Colo 2.0 R 0.0 RS The flow velocity is display - Maintenance > Signal controls K2 Colo 2.0 R 0.0 FeG The orise balance mode is Autor RS Maintenance > Signal controls K2			Up to 0.07 Hz					
Jagenerace > Signal controls → K20 0.110 20.0 RN3 1.0 - The signal kerel is set P.86 Maintenance > Signal controls → CP Fix Tracking - The signal kerel is set P.86 Maintenance > Signal controls → CP Ado (0) Fix The signal kerel is set P.86 Maintenance > Signal controls → CP CP The older balance mode is isolected The older balance mode is isolected The noise balance mode is isolected The older balance mode is isoleced The older balance mode is isolected	Maintenance ► Signal controls ► Trigger level(TLA)	K10	0.1 to 20.0	RW3	1.0	-	The trigger level is set	P.86
Signal controls Fix	Maintenance ► Signal controls ►	K20	0.1 to 20.0	RW3	1.0	-	The signal level is set	P.86
Tingger level mode Image level mod	Maintenance ► Signal controls ►	-	Fix	RW3	Tracking	-	The trigger level mode is	P.86
Maintenace > Signal controls > K2o Auto (0) KV3 Auto (1) - Ine noise balance mode is allow and the mode is allow and the mode balance mode is allow and themode mode is allow and themode mode is allow and the	Trigger level mode		Tracking				selected	
Maintenance > Signal controls > K28 0.0 to 2.0 R 0.0 - The noise balance value when the noise balance mode is Auto is displayed P88 Maintenance > Signal controls > K27 2.0 to 2.0 RV3 0.0 - The noise balance value when the noise balance mode is Auto is displayed P88 Maintenance > Signal controls > K30 9999.9 to 9999.9. R 0.0 m/s The flow velocity is displayed - Maintenance > Signal controls > K32 9999.9 to 9999.9. R 0.0 m/s The flow velocity is displayed - Maintenance > Signal controls > K34 -9999.9 to 9999.9. R 0.0 M/z The flow velocity is displayed - Maintenance > Signal controls > K3 -9999.9 to 9999.9. R 0.0 H2 The roles balance walue when the vortex frequency span is displayed P88 Maintenance > Signal controls > K3 -9999.9 to 9999.9 R 0.0 Flow unit The flow vortex frequency span is displayed P88 Dagnotics > Marm > Al alarm/warming Alarm status select Al alarm/warming Alarm record select </td <td>Noise balance mode</td> <td>K25</td> <td>Auto(0)Manual(1)</td> <td>RW3</td> <td>Auto (0)</td> <td>-</td> <td>selected</td> <td>P.86</td>	Noise balance mode	K25	Auto(0)Manual(1)	RW3	Auto (0)	-	selected	P.86
Noise ratio(auto) Image: Controls in the noise balance mode is displayed the noise balance mode is displayed Maintenance > Signal controls in Mission > K27 2.0 to 2.0 RV3 0.0	Maintenance ► Signal controls ►	K26	0.0 to 2.0	R	0.0	-	The noise balance value when	P.86
Auto is displayedAuto is displayedAuto is displayedAuto is displayedAuto is displayedNoise raid/cmanual) $k27$ $-2.0 \ b 2.0$ $RW3$ 0.0 $-$ The noise balance value when the noise balance mode is displayed $-$ Maintenance \models Signal controls \models $k30$ $-96999.9 \ b 0 9999.9 \ 0 9 9999.9 \ 0 9 9999.9 \ 0 0 \ 0 0 \ 0 100 \ 0$	Noise ratio(auto)						the noise balance mode is	
Maintenance ► Signal controls ► K27 -2.0 to 2.0 RW3 0.0 - The noise balance value whole Manual is set Manual is set R86 Noise raid(manual) K30 -09999.9 to 9999.9 0 R 0.0 m/s The flow velocity is displayed - Maintenance ► Signal controls ► K32 -99999.9 to 9999.9 0 R 0.0 m/s The flow velocity span is displayed 7-8 Maintenance ► Signal controls ► K34 -99999.9 to 9999.9 0 R 0.0 Hz The volocity span is displayed 7-8 Velocity span K36 -99999.9 to 9999.9 R 0.0 Hz The volocity flow process is displayed 7-8 Velocity span K33 -9999.9 to 9999.9 R 0.0 Hz The volocity flow process is displayed 7-8 Device Signal controls ► K33 -9999.9 R 0.0 Flow unit The instant to be notified is span starts starts 7-8 Rest 0.0 Flow unit process is atm 7-8 Dagnostics ► Alam ► Al alarm/warning Alarm tatus selecit Al alarm/warning Alarm tatus selecit							Auto is displayed	
Noise radio(manual) K30 -99990.9 to 99999.9 R 0.0 m/s The flow velocity is displayed Maintenance > Signal controls > K32 -99990.9 to 99999.9 R 0.0 m/s The flow velocity span is displayed P88 Maintenance > Signal controls > K32 -99999.9 to 99999.9 R 0.0 Hz The vortex frequency is displayed Maintenance > Signal controls > K34 -99999.9 to 9999.9 R 0.0 Hz The vortex frequency is displayed Maintenance > Signal controls > K36 -9999.9 0.9999.9 R 0.0 Hz The vortex frequency is displayed Device Settings > Atam > .0 0.99999.0 R 0.0 Hz The input Nover Init Value of Lowert Ini	Maintenance ► Signal controls ►	K27	-2.0 to 2.0	RW3	0.0	-	The noise balance value when	P.86
Maintenace ► Signal controls ► K30 -09999.9 to 99999.9 R 0.0 m/s The flow velocity span is displayed - Velocity K32 -99999.9 to 99999.9 R 0.0 m/s The flow velocity span is displayed - Maintenace ► Signal controls ► K32 -99999.9 to 9999.9 R 0.0 H2 The vortex frequency is displayed - Maintenace ► Signal controls ► K34 -99999.9 to 9999.9 R 0.0 H2 The vortex frequency span is displayed - Vortex frequency span C 0 0.9999.0 R 0.0 H2 The vortex frequency span is displayed P88 Device Settings ► Detailed setup ► - 0 0.9999.0 R 0.0 H2 The vortex frequency span is displayed P88 Diagnostics ► Alam ► - All alarm/warning All alarm RV3 All alarm/warning Variant setup - The alarm to be stored in variang P88 Diagnostics ► Alam ► - All alarm/warning All alarm RV3 Burnout - Output operation when alarm 020 Flo	Noise ratio(manual)						the noise balance mode is	
Maintenance & Signal controls & Kol 400 R 0.0 Hz The vortex frequency span is displayed P38 Maintenance & Signal controls & Kol 400 - 0 to 99999.9 to 99999.9 R 0.0 Flow unit Mither & Maintenance & Signal controls & Kol - 0 to 99999.0 R 0.0 Flow unit Mither & Maintenance & Signal controls & Kol - 0 to 99999.0 R 0.0 Flow unit Mither & Maintenance & Signal controls & Hold - All alarm/Warning All alarm / Signal controls & Hold RW3 Burnout - Output operation when alarm 202 Flow sensor failure cours is set P39 P39 Dispo		1/00						
Valuation Signal controls K32 -99999.9 to 99999.9 R 0.0 m/s The flow velocity span is displayed P88 Velocity span K34 -99999.9 to 9999.9 R 0.0 Hz The vortex frequency is displayed - Maintenance > Signal controls > K36 -99999.9 to 9999.9 R 0.0 Hz The vortex frequency and signalyed - Maintenance > Signal controls > K36 -99999.0 R 0.0 Hz The vortex frequency span is displayed P88 Device Settings > Detailed setue > - 0 to 9999.0 R 0.0 Flow unit The input tower limit value of lowcut limit va	Maintenance ► Signal controls ►	K30	-99999.9 to 99999.9	R	0.0	m/s	I he flow velocity is displayed	-
Maintenance Signal controls K32 -39999 10 to 9999 9. R U.U mis Intentow Velocity span is displayed Pass Maintenance Signal controls K34 -99999.9 to 9999.9. R 0.0 Hz The vortex frequency is displayed - Maintenance Signal controls K36 -99999.9 to 9999.9. R 0.0 Hz The vortex frequency is displayed - Maintenance Signal controls K36 -99999.9 to 9999.9. R 0.0 Hz The vortex frequency is displayed - Diagnostics Name - At alarn/vaming Alarm status select - 0 to 9999.9. R 0.0 Flow unit (C41) The alarm to be stored in history is selected P38 Diagnostics Name - At alarn/vaming Alarm record select - Burnout Hold - The alarm to be stored in history is selected P38 Diagnostics Signal controls - Burnout Hold RW3 Burnout Hold - Output operation when alarm 022: Temperature sensor failure occurs is set P39 Diagnostics Signal controls - Burnout Hold RW3 Burnout Hold - Output operation when alarm 022: Analog input talure occurs is set P39 Diagnostics <td>Velocity</td> <td>1/00</td> <td></td> <td></td> <td></td> <td></td> <td>T A</td> <td>.</td>	Velocity	1/00					T A	.
Values year Values Values<	Maintenance Signal controls	K32	-99999.9 to 99999.9	R	0.0	m/s	I he flow velocity span is	P.88
Maintenance > Signal controls ► NA Jesses 10 seesses 3 R 0.0 HZ The vortex frequency is a displayed - Maintenance > Signal controls ► K36 99999.10 segses 3 R 0.0 HZ The vortex frequency seps an displayed P88 Device Settings ► Detailed setup ► - 0 to 9999.0 R 0.0 HZ The vortex frequency seps an displayed P88 Diagnostics ► Narm ► All alarm / All alarm RW3 All alarm / warning FW3 All alarm / warning FW3 All alarm / warning - The ialarm to be notified is selected P98 Diagnostics ► Narm ► - All alarm / All alarm / System/Process alarm RW3 All alarm / warning - The alarm to be stored in history is selected P98 Diagnostics ► Signal controls ► - Burnout RW3 Burnout - Output operation when alarm Q2: Flow ensor failure occurs is set P99 Diagnostics ► Signal controls ► - Burnout RW3 Burnout - Output operation when alarm Q2: Flow ensor failure occurs is set P19 Diagnostics ► Signal controls ► - Burnout RW3 Fixed value -		1/04	00000.0.1-00000.0			11-		
Voltex Heighting Comparison Voltex Heighting Comparison Comparison Comparison Comparison Pass Vortex Requency span K36 -99999.9 to 99999.9 R 0.0 Hz The wortex frequency span is displayed Pass Device Settings > Detailed setup > - 0 to 99990.0 R 0.0 Flow unit displayed The input lower limit value of lowcut is displayed Pass Diagnostics > Narm > All alarm varing RW3 All alarm/ warning - The alarn to be notified is selected Pass Diagnostics > Narm > - All alarm/ system/Process alarm RW3 All alarn/ warning - The alarn to be notified is selected Pass Diagnostics > Signal controls > - All alarm RW3 Burnout - Output operation when alarm Q20-Flow ensor failure occurs is set Pass Diagnostics > Signal controls > - Burnout + Hold RW3 Burnout - Output operation when alarm Q20-Flow ensor failure occurs is set Q23-Flow operation when alarm Q23-Flow operation when alar	Waintenance ► Signal controls ►	K34	-99999.9 to 99999.9	R	0.0	HZ	line vortex frequency is	-
Maintendor Stage R O.0 R2 Ite Voltex Inductive year is a dispared Poil Device Settings > Detailed setup > - 0 to 9999.0 R 0.0 Flow unit (C41) The input lower limit value of P88 Diagnostics > Alarm > All alarm/warning Alarm status select - All alarm/warning Allarm RW3 All alarm/warning Allarm - The alarm to be stored in history is selected P.98 Diagnostics > Alarm > All alarm/warning Allarm RW3 All alarm/warning - The alarm to be stored in history is selected P.98 Diagnostics > Signal controls > - Burnout RW3 Burnout - Output operation when alarm 2020 Flow sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout Hold Zero RW3 Burnout - Output operation when alarm 2020 Flow sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout Hold Zero RW3 Burnout - Output operation when alarm 2023 Analog input failure occurs is set P.99 Diagnostics > Signal controls > - 0.0 to 100.0 RW3 I0.0 % The judgment value for the fluctualon alarm is set<		1/26	00000 0 to 00000 0		0.0	LI-7	The vertex frequency open is	D 00
Notes Negative year 0 0 to 99990.0 R 0.0 Flow unit (C41) The input lower limit value of lowcut is displayed P88 Diagnostics > Alarn > All alarm varning Alarm status select - All alarm/varning All alarm RW3 All alarm/ - The alarm to be notified is selected P98 Diagnostics > Alarn > All alarm - All alarm/varning All alarm RW3 All alarm/ - The alarm to be stored in history is selected P98 Diagnostics > Signal controls > Flow sensor alarm action - Burnout Hold Zero Measured value RW3 Burnout - Output operation when alarm 020:Flow sensor failure occurs is set P99 Diagnostics > Signal controls > Temperature sensor alarm action - Burnout Hold Zero Analog input alarm action - Burnout Hold Zero Analog input alarm action - Burnout Hold Zero Prixed value RW3 Is no - Output operation when alarm 023: Analog input failure occurs is set P99 Diagnostics > Signal controls > Fixed value - 0.0 to 100.0 RW3 10.0 % The judgment value for the fluctuation alarm is set P111 Diagnostics > Signal controls > Fixed value - 0.0 to 100.0 RW3 10.0 %		1.30	-99999.9 10 99999.9		0.0	пг	displayed	F.00
Devode Settings → Declared Setings → Declared Setings → Declared Settings → Declared Settings			0 to 00000 0		0.0	Elow upit	The input lower limit value of	D 00
Diagnostics ▶ Alarm ▶ Alar status select - All alarm/warning All alarm RW3 All alarm/ warning - The alarm to be notified is selected P98 Diagnostics ▶ Alarm ▶ Alar mecord select - All alarm/warning All alarm RW3 All alarm/ warning - The alarm to be stored in history is selected P98 Diagnostics ▶ Signal controls ▶ Flow sensor alarm action - Burnout Hold Zero Keaved value RW3 Burnout P99 - Output operation when alarm 020 Flow sensor failure occurs is set P99 Diagnostics ▶ Signal controls ▶ Temperature sensor alarm action - Burnout Hold Zero Fixed value RW3 Burnout P99 - Output operation when alarm 020 Flow sensor failure occurs is set P99 Diagnostics ▶ Signal controls ▶ Temperature sensor alarm action - Burnout Hold Zero Fixed value RW3 Burnout Fixed value - Output operation when alarm 021: Temperature sensor failure occurs is set P99 Diagnostics ▶ Signal controls ▶ Fixed value - 0.0 to 100.0 RW3 10.0 % The judgment value for the fluctuation alarm is set P111 Diagnostics ▶ Signal controls ▶ Fixed value - 0.0	Lowcut limit	-	0 10 99999.0		0.0	(C41)	lowcut is displayed	F.00
Alarm status select All alarm strung No. warning selected No. warning Jagnostics > Alarm > Alar Marwaning All alarm/warning RW3 All alarm/warning P.98 Jagnostics > Signal controls > Flow sensor alarm action Burnout RW3 Burnout - Output operation when alarm 020:Flow sensor failure occurs is set P.99 Diagnostics > Signal controls > Flow sensor alarm action - Burnout Hold Zero RW3 Burnout - Output operation when alarm 020:Flow sensor failure occurs is set P.99 Diagnostics > Signal controls > Flow sensor alarm action - Burnout Hold Zero RW3 Burnout - Output operation when alarm 020:Flow sensor failure occurs is set P.99 Diagnostics > Signal controls > Fixed value - Burnout Hold RW3 Fixed value - Output operation when alarm 023:Analog input failure occurs is set P.99 Diagnostics > Signal controls > Fixed value - 0.0 to 100.0 RW3 10.0 % The judgment value for the fluctuation alarm is set P.111 Diagnostics > Signal controls > Fixed value - 0 to 99 RW3 12 - The judgment value for the fluctuation alarm is set P.111 Diagnostics > Signal controls > Fixed value - 0 to 99 RW3 10 s The j	Diagnostics Alarm	-	All alarm/warning	RW3	All alarm/	-	The alarm to be notified is	P 98
Image: constraint of the system/Process alarmImage: constraint of the system/	Alarm status select		All alarm		warning		selected	
Diagnostics ► Alarm ► - All alarm/Varning RW3 All alarm/Varning - The alarm to be stored in history is selected P.98 Diagnostics ► Signal controls ► - Burnout RW3 Burnout - Output operation when alarm 020.Flow sensor failure occurs is set P.99 Diagnostics ► Signal controls ► - Burnout RW3 Burnout - Output operation when alarm 020.Flow sensor failure occurs is set P.99 Diagnostics ► Signal controls ► - Burnout RW3 Burnout - Output operation when alarm 020.Flow sensor failure occurs is set P.99 Diagnostics ► Signal controls ► - Burnout RW3 Burnout - Output operation when alarm 021: Temperature sensor failure occurs is set P.99 Diagnostics ► Signal controls ► - Burnout RW3 Fixed value - Output operation when alarm 023: Analog input failure occurs is set P.99 Diagnostics ► Signal controls ► - Burnout RW3 10.0 % The judgment value for the filture diagnosis is set P.111 Diagnostics ► Signal controls ► - 0 to 99 RW3 12 - The judgment value for			System/Process alarm					
Alarm record select Allarm System/Process alarm warning history is selected Diagnostics > Signal controls > Burnout Hold Zero Measured value RW3 Burnout - Output operation when alarm 020:Flow sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout Hold Zero Measured value RW3 Burnout - Output operation when alarm 020:Flow sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout Hold Zero Fixed value RW3 Burnout - Output operation when alarm 021:Femperature sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout Hold Zero Fixed value - Output operation when alarm 021:Femperature sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout Hold Zero Fixed value - Output operation when alarm 023: Analog input failure occurs is set P.99 Diagnostics > Signal controls > - 0.0 to 100.0 RW3 10.0 % The judgment count for noise diagnosis is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - Cuput operation when alarm 032: High vibration occurs is set P.111	Diagnostics ► Alarm ►	-	All alarm/warning	RW3	All alarm/	-	The alarm to be stored in	P.98
Image: controls bigs and control	Alarm record select		All alarm		warning		history is selected	
Diagnostics ► Signal controls ►			System/Process alarm					
Flow sensor alarm actionHold Zero Measured valueRW3Burnout020:Flow sensor failure occurs is set020:Flow sensor failure occurs is setDiagnostics > Signal controls > Temperature sensor alarm action-Burnout Hold Zero Fixed valueRW3Burnout Fixed value-Output operation when alarm 021: Temperature sensor failure occurs is setP.99Diagnostics > Signal controls > Analog input alarm action-Burnout Hold Zero Fixed valueRW3Fixed value-Output operation when alarm 023: Analog input failure occurs is setP.99Diagnostics > Signal controls > Analog input failure occurs is set-0.0 to 100.0RW310.0%The judgment value for the fluctuation alarm is setP.111Diagnostics > Signal controls > Transient noise count-0 to 99RW312-The judgment count for noise diagnosis is setP.111Diagnostics > Signal controls > High vibration actionK45Zero (0) HoldRW310sThe judgment term alarm diagnosis is setP.99Diagnostics > Signal controls > High vibration action-0 to 99RW310sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration time-0 to 99RW310sThe judgment value for the diagnosis is setP.112Diagnostics > Signal controls > High vibration time-0 to 99RW310sThe judgment value for the diagnosis is set	Diagnostics ► Signal controls ►	-	Burnout	RW3	Burnout	-	Output operation when alarm	P.99
Zero Measured valueZero Measured valueImage: Set Measured valueImage: Set Measured valueDiagnostics > Signal controls > Fixed valueSumout Hold Zero Fixed valueRW3Burnout PPOutput operation when alarm 021: Temperature sensor failure occurs is setPDiagnostics > Signal controls > Analog input alarm action- Burnout Hold Zero Fixed valueRW3Fixed value- POutput operation when alarm 023: Analog input failure occurs is setPDiagnostics > Signal controls > Fluctuating level-0.0 to 100.0RW310.0%The judgment value for the fluctuation alarm is setP.111Diagnostics > Signal controls > High vibration action-0 to 99RW312-The judgment count for noise diagnosis is setP.111Diagnostics > Signal controls > High vibration actionK46Zero Hold Measured valueRW310sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration actionK46Zero Hold Hold Measured valueRW310sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration actionK46Zero Hold Hold Measured valueRW35.0%The judgment value for the diagnosis alarm is setP.112Diagnostics > Signal controls > Critical vibration level-0.0 to 100.0RW3S.0%The judgment value for the diagnosis alarm is setP.112 <tr< td=""><td>Flow sensor alarm action</td><td></td><td>Hold</td><td></td><td></td><td></td><td>020:Flow sensor failure occurs</td><td></td></tr<>	Flow sensor alarm action		Hold				020:Flow sensor failure occurs	
Measured valueMeasured valueMeasured valueMeasured valueDiagnostics > Signal controls > Analog input alarm action- Hold Zero Fixed value- Hold Zero Fixed valueRW3 RW3Burnout - - - Output operation when alarm occurs is setP.99Diagnostics > Signal controls > Fluctuating level- -Burnout Hold Zero Fixed valueRW3 RW3Fixed value - - Output operation when alarm occurs is setP.99Diagnostics > Signal controls > Fluctuating level-0.0 to 100.0RW3 RW310.0%The judgment value for the fluctuation alarm is setP.111Diagnostics > Signal controls > Fluctuating level-0 to 99RW3 RW312-The judgment count for noise diagnosis is setP.111Diagnostics > Signal controls > Hold Measured value-0 to 99RW3 value (2)10sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > Hold High vibration action-0 to 99RW3 Hold (1) Measured value (2)10sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration action-0 to 99RW3 Hold (1) Measured value (2)RW3 RW310sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration action-0 to 99RW3 Hold (1) Measured value (2)-Output ope			Zero				is set	
Diagnostics > Signal controls > - Burnout RW3 Burnout - Output operation when alarm on 21: Temperature sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout RW3 Burnout - Output operation when alarm on 21: Temperature sensor failure occurs is set P.99 Diagnostics > Signal controls > - Burnout RW3 Fixed value - Output operation when alarm on 23: Analog input failure occurs is set P.99 Diagnostics > Signal controls > - 0.0 to 100.0 RW3 10.0 % The judgment value for the fluctuation alarm is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - The judgment count for noise diagnosis is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - Output operation when alarm diagnosis is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 12 - The judgment count for noise diagnosis is set P.111 Diagnostics > Signal controls > K45 Zero (0) RW3 10 s The judgment time for vibration diagnosis is set <td></td> <td></td> <td>Measured value</td> <td>-</td> <td></td> <td></td> <td></td> <td></td>			Measured value	-				
Interpretature sensor alarm action Proto Diagnostics > Signal controls > - Burnout RW3 Fixed value - Output operation when alarm 023: Analog input failure occurs is set P.99 Diagnostics > Signal controls > - 0.0 to 100.0 RW3 10.0 % The judgment value for the fluctuation alarm is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - The judgment court for noise diagnosis is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - The judgment court for noise diagnosis is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - Output operation when alarm o32: High vibration occurs is set P.99 Diagnostics > Signal controls > K45 Zero (0) RW3 Measured value (2) - Output operation when alarm o32: High vibration occurs is set P.99 Diagnostics > Signal controls > K45 Zero (0) RW3 Measured value (2) - Output operation when alarm diagnosis is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 </td <td>Diagnostics ► Signal controls ►</td> <td>-</td> <td>Burnout</td> <td>RW3</td> <td>Burnout</td> <td>-</td> <td>Output operation when alarm</td> <td>P.99</td>	Diagnostics ► Signal controls ►	-	Burnout	RW3	Burnout	-	Output operation when alarm	P.99
Let of Fixed valueFixed valueInitial e occurs is setDiagnostics > Signal controls > Analog input alarm action-Burnout Hold Zero Fixed valueRW3Fixed value-Output operation when alarm occurs is setP.99Diagnostics > Signal controls > Fluctuating level-0.0 to 100.0RW310.0%The judgment value for the fluctuation alarm is setP.111Diagnostics > Signal controls > Fluctuating level-0.0 to 99RW312-The judgment count for noise diagnosis is setP.111Diagnostics > Signal controls > High vibration actionK45Zero Hold Measured value(1) Measured valueRW310.0sOutput operation when alarm diagnosis is setP.99Diagnostics > Signal controls > High vibration action-0 to 99RW310.0sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration action-0 to 99RW310sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration action-0 to 99RW310sThe judgment walue for the diagnosis is setP.112Diagnostics > Signal controls > High vibration action-0 to 99RW310sThe judgment walue for the diagnosis is setP.99Diagnostics > Signal controls > High vibration action-0 to 99RW310sThe judgment walue for the diagnosis is set <td< td=""><td>remperature sensor alarm action</td><td></td><td>Hold</td><td></td><td></td><td></td><td>021: Temperature sensor</td><td></td></td<>	remperature sensor alarm action		Hold				021: Temperature sensor	
Diagnostics ► Signal controls ► Analog input alarm action-Burnout Hold Zero Fixed valueRW3Fixed value-Output operation when alarm 023: Analog input failure occurs is setP.99Diagnostics ► Signal controls ► Fluctuating level-0.0 to 100.0RW310.0%The judgment value for the fluctuation alarm is setP.111Diagnostics ► Signal controls ► Transient noise count-0 to 99RW312-The judgment count for noise diagnosis is setP.111Diagnostics ► Signal controls ► High vibration actionK45Zero (0) Hold(1) Measured valueRW310sThe judgment time for vibration diagnosis is setP.99Diagnostics ► Signal controls ► Hold-0 to 99RW310sThe judgment time for vibration diagnosis is setP.112Diagnostics ► Signal controls ► High vibration action-0 to 99RW310sThe judgment time for vibration diagnosis is setP.112Diagnostics ► Signal controls ► High vibration action-0 to 99RW310sThe judgment time for vibration diagnosis is setP.112Diagnostics ► Signal controls ► Hold-0 to 100.0RW310sThe judgment value for the diagnosis is setP.99Diagnostics ► Signal controls ► (critical vibration action-0.0 to 100.0RW35.0%The judgment value for the resonant diagnosis alarm is setP.112Diagnostics ► Signal controls ► (critical			Fixed value					
Analog input alarm action Analog input alarm action Filed tarm action Filed tarm action Filed tarm action Filed tarm action C23: Analog input failure occurs is set P.111 Diagnostics > Signal controls > - 0.0 to 100.0 RW3 10.0 % The judgment value for the fluctuation alarm is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - The judgment count for noise diagnosis is set P.111 Diagnostics > Signal controls > K45 Zero (0) RW3 Measured value (2) - Output operation when alarm output operation when alarm is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.99 Diagnostics > Signal	Diagnostics Signal controls		Burpout	RW3	Fixed value	-	Output operation when alarm	Pgg
Zero Fixed valueZero Fixed valueOccurs is setDiagnostics > Signal controls > Fluctuating level-0.0 to 100.0RW310.0%The judgment value for the fluctuation alarm is setP.111Diagnostics > Signal controls > Transient noise count-0 to 99RW312-The judgment count for noise diagnosis is setP.111Diagnostics > Signal controls > High vibration actionK45Zero Hold Measured value(1) Measured valueRW312-Output operation when alarm output operation when alarm is setP.99Diagnostics > Signal controls > High vibration action-0 to 99RW310sThe judgment time for vibration diagnosis is setP.99Diagnostics > Signal controls > High vibration time-0 to 99RW310sThe judgment time for vibration diagnosis is setP.112Diagnostics > Signal controls > High vibration action-0 to 99RW310sThe judgment value for when alarm output operation w	Analog input alarm action		Hold		r stou raido		023: Analog input failure	
Image: constraint of the second sec	0.1		Zero				occurs is set	
Diagnostics > Signal controls > - 0.0 to 100.0 RW3 10.0 % The judgment value for the fluctuation alarm is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - The judgment count for noise diagnosis is set P.111 Diagnostics > Signal controls > - 0 to 99 RW3 12 - The judgment count for noise diagnosis is set P.111 Diagnostics > Signal controls > K45 Zero (0) RW3 Measured value (2) - Output operation when alarm or value for vibration occurs is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.112 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment value for vibration diagnosis is set P.112 Diagnostics > Signal controls > K46 Zero (0) RW3 Hold (1) - Output operation when alarm 033: Critical vibration occurs is set P			Fixed value					
Fluctuating level Image: constraint of the problem of the presonal theanopsis predice of the problem of the presonant diagnos	Diagnostics ► Signal controls ►	-	0.0 to 100.0	RW3	10.0	%	The judgment value for the	P.111
Diagnostics > Signal controls > Transient noise count - 0 to 99 RW3 12 - The judgment count for noise diagnosis is set P.111 Diagnostics > Signal controls > High vibration action K45 Zero (0) Hold RW3 Measured value (2) - Output operation when alarm value (2) P.99 Diagnostics > Signal controls > High vibration time - 0 to 99 RW3 Measured value (2) - Output operation when alarm value (2) P.99 Diagnostics > Signal controls > High vibration time - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.112 Diagnostics > Signal controls > Critical vibration action K46 Zero Hold (1) Measured value RW3 10 s The judgment time for vibration diagnosis is set P.99 Diagnostics > Signal controls > Critical vibration action K46 Zero Hold (2) RW3 Hold (1) - Output operation when alarm diagnosis is set P.99 Diagnostics > Signal controls > Critical vibration level - 0.0 to 100.0 RW3 5.0 % The judgment value for the resonant diagnosis alarm is set P.112	Fluctuating level						fluctuation alarm is set	
Transient noise count Image: Count of the problem	Diagnostics ► Signal controls ►	-	0 to 99	RW3	12	-	The judgment count for noise	P.111
Diagnostics > Signal controls > K45 Zero (0) RW3 Measured value (2) - Output operation when alarm 032: High vibration occurs is set P.99 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.112 Diagnostics > Signal controls > - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.112 Diagnostics > Signal controls > K46 Zero (0) RW3 Hold (1) - Output operation when alarm diagnosis is set P.99 Diagnostics > Signal controls > K46 Zero (0) RW3 Hold (1) - Output operation when alarm diagnosis is set P.99 Diagnostics > Signal controls > N46 Zero (2) RW3 S.0 % The judgment value for the resonant diagnosis alarm is set P.99 Diagnostics > Signal controls > - 0.0 to 100.0 RW3 S.0 % The judgment value for the resonant diagnosis alarm is set P.112	Transient noise count						diagnosis is set	
High vibration action Hold (1) value (2) value (2) 032: High vibration occurs is set Diagnostics ► Signal controls ► - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.112 Diagnostics ► Signal controls ► - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.112 Diagnostics ► Signal controls ► K46 Zero (0) RW3 Hold (1) - Output operation when alarm 033: critical vibration occurs is set P.99 Otignostics ► Signal controls ► K46 Zero (2) RW3 For 000000000000000000000000000000000000	Diagnostics ► Signal controls ►	K45	Zero (0)	RW3	Measured	-	Output operation when alarm	P.99
Image: Measured value (2) (2) (2) (3	High vibration action		Hold (1)		value (2)		032: High vibration occurs	
Diagnostics > Signal controls > High vibration time - 0 to 99 RW3 10 s The judgment time for vibration diagnosis is set P.112 Diagnostics > Signal controls > Critical vibration action K46 Zero (0) Hold RW3 Hold (1) - Output operation when alarm 033: Critical vibration occurs is set P.99 Diagnostics > Signal controls > Critical vibration level - 0.0 to 100.0 RW3 5.0 % The judgment value for the resonant diagnosis alarm is set P.112			Measured value (2)				is set	
High vibration time Measured value Measured value Measured value RW3 Hold (1) - Output operation when alarm 033. Critical vibration occurs is set P.99 Diagnostics > Signal controls > K46 Zero (0) RW3 Hold (1) - Output operation when alarm 033. Critical vibration occurs is set P.99 Diagnostics > Signal controls > - 0.0 to 100.0 RW3 5.0 % The judgment value for the resonant diagnosis alarm is set P.112	Diagnostics ► Signal controls ►	-	0 to 99	RW3	10	s	The judgment time for vibration	P.112
Diagnostics > Signal controls > Critical vibration action K46 Zero (0) RW3 Hold (1) - Output operation when alarm 033: Critical vibration occurs is set P.99 Diagnostics > Signal controls > Critical vibration level - 0.0 to 100.0 RW3 5.0 % The judgment value for the resonant diagnosis alarm is set P.112	High vibration time						diagnosis is set	
Critical vibration action Hold (1) Measured value (2) 033: Critical vibration occurs is set Diagnostics ▶ Signal controls ▶ Critical vibration level - 0.0 to 100.0 RW3 5.0 % The judgment value for the resonant diagnosis alarm is set P.112	Diagnostics ► Signal controls ►	K46	Zero (0)	RW3	Hold (1)	-	Output operation when alarm	P.99
Image:	Critical vibration action		Hold (1)				033: Critical vibration occurs	
Unagnosucs > Signal controls > - 0.0 to 100.0 RW3 5.0 % The judgment value for the resonant diagnosis alarm is set			Ivieasured value (2)	DIATE	50		IS SET	D 1/2
	Critical vibration level	-		KVV3	0.0	70	resonant diagnosis alarm is set	P.112

Parameter Name		Data Damas	DAM	Default	Unit	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Diagnostics ► Signal controls ► Critical vibration time	-	0 to 99	RW3	5	s	The judgment time for resonant diagnosis is set	P.112
Diagnostics ► Signal controls ► Clogging time	-	0 to 99	RW3	30	S	The judgment time for clogging diagnosis is set	P.112
Diagnostics ► Signal controls ► Sensor circuit threshold	-	0 to 65535	RW3	0 *1	-	The judgment value for the input circuit alarm is set	P.111
Diagnostics ► Signal controls ► Sensor capacitance threshold	-	0.0 to 99999.9	RW3	0 *1	pF	The abnormality judgment value of the static capacitance for the piezoelectric element sensor is set	P.111
Diagnostics ► Signal controls ► Sensor resistance threshold	-	0.0 to 99999.9	RW3	0 *1	kohm	The abnormality judgment value of the insulation resistance for the piezoelectric element sensor is set	P.111
Device Settings ► Detailed setup ► Information ► Device info ► Software revision	K50	-	R	"R1.01.01 "	-	The revision No. of the software is displayed	P.109
Maintenance ► Signal controls ► Tuning at zero	K51	Not execute(0)Execute(1)	RW3	Not execute (0)	-	Whether or not to execute tuning of noise balance is selected	P.87
Maintenance ► Signal controls ► Tuning status	K52	Unknown(0)Pass(1)Failure(2)Running(3)	R	Unknown (0)	-	The tuning state of noise balance is displayed	P.87
Maintenance ► Signal controls ► Vortex frequency lowcut	K55	-99999.9 to 99999.9	R	0.0	Hz	The lowcut vortex frequency is displayed	P.88
Maintenance ► Signal controls ► Velocity lowcut	K54	-99999.9 to 99999.9	R	0.0	m/s	The lowcut flow velocity value is displayed	P.88
Maintenance ► Signal controls ► Board temperature	K56	-99999.9 to 99999.9	R	0.0	Temperature unit (C30)	The device internal temperature is displayed	-
Maintenance ► Signal controls ► Analog input(mA)	K57	-99999.9 to 99999.9	R	0.0	mA	The current value of the external input is displayed	P.67
Maintenance ► Signal controls ► Analog input	K58	-99999.9 to 99999.9	R	0.0	Analog input unit (D52)	The process value of the external input is displayed	P.67
Maintenance ► Signal controls ► Built-in temperature	-	-9999.9 to 9999.9	R	0.0	Temperature unit (C30)	The measured value of the internal temperature gauge is displayed	-

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

5.11 Alarm Setting Items

Menu path

HART

Diagnostics ► Alarm ► Alarm record ► (see table below)

Parameter Name		Dete Benne	DAA	Default	Unit	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Alarm record clear	-	Not execute Execute	RW2	Not execute	-	Clearing of the alarm history is executed	P.97
Auto delete time	-	0 to 9999	RW2	60	day	The auto-clear time of the alarm history is set	P.97
Alarm record 1	-	000:None 010:CPU failure 011:CPU failure 012:Main storage failure 013:Sub storage failure 014:Main ASIC failure 015:Sub ASIC failure 016:ADC circuit failure	R	000:None	-	Alarms recorded to the alarm history (Alarm record 1 - 5) are displayed	P.97
Alarm record 2	-	017:Signal circuit failure 017:Signal circuit failure 020:Flow sensor failure 021:Temperature sensor failure 023:Analog input failure 030:Fluctuation 031:Transient noise					
Alarm record 3	-	032:High vibration 033:Critical vibration 040:Temperature out of range 041:Pressure out of range 042:Analog output out of range 044:Analog input out of range 045:T/P compensation out of range 045:T/P compensation out of range 045:T/P compensation out of range					
Alarm record 4		051:Temperature span set error 053:Flow calculation set error 054:Analog output set error 055:Pulse output set error 056:Analog input set error 060:Sensor backup error 070:Sensor communication error 071:Flow sensor error					
Alarm record 5	-	072:Clogging 073:Degradation 074:Board temperature out of range 080:Simulation running 081:Verification running 082:Incorrect PIN					
Alarm record date 1	-	1900/01/01 to 2155/12/31	R	2021/01/01	-	The date that alarms are	P.97
Alarm record date 2	-					recorded to the alarm history	
Alarm record date 3	-					(Alarm record 1 - 5) is	
Alarm record date 4	-					displayed	
Alarm record date 5	-						
Alarm record time 1	-	00:00:00 to 23:59:59	R	00:00:00	-	The time that alarms are	P.97
Alarm record time 2	-					recorded to the alarm history	
Alarm record time 3	-					(Alarm record 1 - 5) is	
Alarm record time 4	-					displayed	
Alarm record time 5	-						
Alarm record operation time 1	-	0000D 00:00 to 9999D 23:59	R	00000 00.00	-	The operation time of	P.97
Alarm record operation time ?	-			00.00		devices up to when alarms	1.51
Alarm record operation time 3	-					are recorded to the alarm	
Alarm record operation time 4	-					history (Alarm record 1 - 5) is	
Alarm record operation time 5	1-					usplayeu	

<5. Parameter Lists>

Parameter Name		212	-	Default	11-14	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Recent alarm 1	-	000:None 010:CPU failure 011:CPU failure 012:Main storage failure 013:Sub storage failure 014:Main ASIC failure 014:Main ASIC failure 016:ADC circuit failure	R	000:None	-	Alarms recorded to the alarm history (Recent alarm 1 - 5) are displayed	P.97
Recent alarm 2	-	1017:Signal circuit failure 018:Power circuit failure 020:Flow sensor failure 021:Temperature sensor failure 023:Analog input failure 030:Fluctuation 031:Finztransient noise 032:High vibration 033:Critical vibration					
Recent alarm 3	-	040:Temperature out of range 041:Pressure out of range 042:Analog output out of range 044:Analog input out of range 045:T/P compensation out of range 050:Flow span set error 051:Temperature span set error 052:Pressure span set error					
Recent alarm 4	-	053:Flow calculation set error 054:Analog output set error 056:Analog input set error 060:Sensor backup error 070:Sensor communication error 071:Flow sensor error 072:Clogging 074:Board temperature out of range					
Recent alarm 5	-	080:Simulation running 081:Verification running 082:Incorrect PIN					
Recent alarm date 1	-	1900/01/01 to 2155/12/31	R	2021/01/01	-	The date that alarms are	P.97
Recent alarm date 2	-					recorded to the alarm history	
Recent alarm date 3	-					(rcecent alarm 1 - 5) is displayed	
Recent alarm date 4	-					displayed	
Recent alarm date 5	-						
Recent alarm time 1	-	00:00:00 to 23:59:59	R	00:00:00	-	The time that alarms are	P.97
Recent alarm time 2	-					recorded to the alarm history	
Recent alarm time 3	-					displayed	
Recent alarm time 4	-					alopiajou	
Recent alarm time 5	-						
Recent alarm operation time 1	-	0000D 00:00 to 9999D 23:59	R	0000D 00:00	-	The operation time of	P.97
Recent alarm operation time 2	-					devices up to when alarms	
Recent alarm operation time 3	-					history (Recent alarm 1 - 5) is	
Recent alarm operation time 4	-					displayed	
Recent alarm operation time 5	-						

5.12 Diagnostic Functions (Verification) Setting Items

Menu path

HART Diagnostics

Diagnostics ► Verification ► (see table below)

Parameter Name		Data Dawa	DAM	Default	11-14	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Verification mode	-	Not execute Execute	RW3	Not execute	-	Execution/cancellation of verification is selected, Set from Test/Simulation(method)	P.114
Verification target	-	Sensor circuit Signal processing circuit Calculation circuit Alarm status Alarm record	RW3	All off	-	The verification target is selected	P.114
Verification status	-	Not execute Execute(1/10) Execute(2/10) Execute(3/10) Execute(5/10) Execute(5/10) Execute(8/10) Execute(8/10) Execute(8/10) Execute(9/10) Execute(10/10) Finish Cancel	R	Not execute	-	The progress of verification is displayed	P.114
Verification select	-	Latest Previous Factory	RW3	Latest	-	The verification result to be displayed is selected	P.114
Verification date	-	1900/01/01 to 2155/12/31	R	2021/01/01	-	The date of verification execution is displayed	P.114
Verification time	-	00:00:00 to 23:59:59	R	00:00:00	-	The time at verification execution is displayed	P.114
Verification operation time	-	0000D 00:00 to 9999D 23:59	R	0000D 00:00	-	The operation time of the device up to verification execution is displayed	P.114
Verification result	-	Unknown Pass Failure Cancel	R	Unknown	-	The overall result of verification is displayed	P.114
Sensor circuit result	-	Unknown Pass Failure Cancel Skip	R	Unknown	-	The diagnosis result of the sensor circuit is displayed	P.114
Signal circuit result	-	Unknown Pass Failure Cancel Skip	R	Unknown	-	The diagnosis result of the signal circuit is displayed	P.114
Calculation circuit result	-	Unknown Pass Failure Cancel Skip	R	Unknown	-	The diagnosis result of the calculation circuit is displayed	P.114
Alarm status result	-	Unknown Pass Failure Cancel Skip	R	Unknown	-	The diagnosis result of the alarm is displayed	P.114
Alarm record result	-	Unknown Pass Failure Cancel Skip	R	Unknown	-	The diagnosis result of the alarm history is displayed	P.114

5.13 Predictive Diagnosis Setting Items

Menu path

HART

Diagnostics ► Predictive diagnosis ► (see table below)

Parameter Name		Data Damas	DAM	Default	11-14	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Prediction execution	-	Not execute Execute	RW3	Not execute	-	Execution/cancellation of predictive diagnosis is selected	P.113
Prediction select	-	A/B ratio Sensor sensitivity Signal A Signal B Signal C	RW3	A/B ratio	-	The target of predictive diagnosis is selected	P.113
Prediction period	-	0 to 65535	RW3	60	min	The storage interval of predictive diagnosis is set	P.113
Prediction start date	-	1900/01/01 to 2155/12/31	R:	2021/01/01	-	The start date of predictive diagnosis is displayed	P.113
Prediction stop date	-	1900/01/01 to 2155/12/31	R	2021/01/01	-	The stop date of predictive diagnosis is displayed	P.113
Prediction level	-	0.0 to 99999.9	RW3	0.0	-	The judgment value of the prediction time is set	P.113
Prediction alarm time	-	0 to 65535	RW3	0	h	The specified time of predictive diagnosis is set	P.113
Prediction estimate time	-	0 to 65535	R	0	h	The prediction time of predictive diagnosis is displayed	P.113
Prediction result	-	Unknown Pass Failure	R	Unknown	-	The result of predictive diagnosis is displayed	P.113
Prediction type	-	Type 1 Type 2 Type 3	RW3	Туре 1	-	The type of predictive diagnosis is set	P.113
Prediction data clear ^{*1}	-	Not execute Execute	RW3	Not execute	-	Clearing of the trend data of predictive diagnosis is executed	P.113

*1 For R1.01.03 or more

IM 01F07A02-01EN

5.14 Signal Latch Setting Items

Menu path

HART Diagnostics ► Sensor signal ► (see table below)

Parameter Name				Default		Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Signal latch execution	-	Not execute Execute	RW3	Not execute	-	Signal latch is executed	P.113
Signal latch target	-	Latest Sensor alarm record 1 Sensor alarm record 2 Sensor alarm record 3 Sensor alarm record 4 Sensor alarm record 5	RW3	Latest	-	The signal latch to display is selected	P.116
Signal latch alarm	-	None Fluctuating Transient noise High vibration Critical vibration Flow sensor error Clogging Degradation	R	None	-	The alarm when a signal latch is executed is displayed	P.116
Signal latch date	-	1900/01/01 to 2155/12/31	R	2021/01/01	-	The date when a signal latch is executed is displayed	P.116
Signal latch time	-	00:00:00 to 23:59:59	R	00:00:00	-	The time when a signal latch is executed is displayed	P.116
Signal latch operation time	-	0000D 00:00 to 9999D 23:59	R	0000D 00:00	-	The operation time of the device up to signal latch execution is displayed	P.116

Menu path

Parameter Name		Dete Demos	Dav	Default		Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Signal latch vortex frequency	-	-99999.9 to 99999.9	R	0.0	Hz	The vortex frequency when a signal latch is executed is displayed	P.116
Signal latch velocity	-	-99999.9 to 99999.9	R	0.0	m/s	The flow velocity when a signal latch is executed is displayed	P.116
Signal latch max band	-	0 to 99	R	0	-	The maximum band when a signal latch is executed is displayed	P.116
Signal latch noise ratio	-	-99999.9 to 99999.9	R	0.0	-	The noise ratio when a signal latch is executed is displayed	P.116
Signal latch noise band 1	-	0 to 99	R	0	-	Noise band 1 when a signal latch is executed is displayed	P.116
Signal latch noise band 2	-	0 to 99	R	0	-	Noise band 2 when a signal latch is executed is displayed	P.116
Signal latch TLA	-	-99999.9 to 99999.9	R	0.0	-	The trigger level when a signal latch is executed is displayed	P.116
Signal latch basic band	-	0 to 99	R	0	-	The basic band when a signal latch is executed is displayed	P.116
Basic+0 band A	-	0 to 65535	R	0	-	The A signal amplitude at the	P.116
Basic+1 band A	-					basic band + (0 to 8) when	
Basic+2 band A	-					a signal latch is executed is	
Basic+3 band A	-					diopidyou	
Basic+4 band A	-						
Basic+5 band A	-						
Basic+6 band A	-						
Basic+7 band A	-						
Basic+8 band A	-						

Parameter Name				Default		D 1.4	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Basic+0 band B	-	0 to 65535	R	0	-	The B signal amplitude at the	P.116
Basic+1 band B	-					basic band + (0 to 8) when	
Basic+2 band B	-					a signal latch is executed is displayed	
Basic+3 band B	-					alsplayed	
Basic+4 band B	-						
Basic+5 band B	-						
Basic+6 band B	-						
Basic+7 band B	-						
Basic+8 band B	-						
Basic+0 band C	-	0 to 65535	R	0	-	The C signal amplitude at the	P.116
Basic+1 band C	-					basic band + (0 to 8) when	
Basic+2 band C	-					a signal latch is executed is displayed	
Basic+3 band C	-					alopiayou	
Basic+4 band C	-						
Basic+5 band C	-						
Basic+6 band C	-						
Basic+7 band C	-						
Basic+8 band C	-						
Basic+0 band NJLS	-	0 to 65535	R	0	-	The noise judgment level at	P.116
Basic+1 band NJLS	-					the basic band + (0 to 8) when	
Basic+2 band NJLS	-					a signal latch is executed is	
Basic+3 band NJLS	-					alopiayou	
Basic+4 band NJLS	-						
Basic+5 band NJLS	-						
Basic+6 band NJLS	-						
Basic+7 band NJLS	-						
Basic+8 band NJLS	-						

5.15 Date/Time Setting Items

Menu path

HART

Device Settings ► Detailed setup ► Information ► Date/Time ► (see table below)

Parameter Name		Data Pango		Default	Unit	Description	Refer
HART	Display	Data Range	PC/ VV	Value	Unit	Description	to
Operation time	-	0000D 00:00 to 9999D 23:59	R	0000D 00:00	-	The operation time of the device is displayed	P.110
Current date ^{*1} / Current Date ^{*2}	-	1900/01/01 to 2155/12/31	R	1900/01/01	-	The present date is displayed	P.110
Current time*1 / Current Time*2	-	00:00:00 to 23:59:59	R	00:00:00	-	The present time is displayed	P.110
Set Clock Date	-	1900/01/01 to 2155/12/31	RW3	1900/01/01	-	The date is set	P.110
Set Clock Time	-	00:00:00 to 23:59:59	RW3	00:00:00	-	The time is set	P.110

*1: For Device revision 1 and DD revision 1 or 2

*2: For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

5.16 Parameter Protection/Operation Rights Setting Items

Parameter Name		Dista Dimini	DAM	Default	Unit	Description	Refer
HART	Display	Data Range	R/W	Value	Unit	Description	to
Device Settings ► Detailed setup ► Protect ► Write protect ► Write protect	-	Off On	-	Off	-	Use of the write protect function is displayed	P.124
Device Settings ► Detailed setup ► Protect ► Write protect ► Software seal	-	Break Keep	-	Break	-	Use of a joker password is checked	P.125
Device Settings ► Detailed setup ► Protect ► Write protect ► New password	-	-	RW3	All Space	-	A new password for the write protect function is set	P.124
Device Settings ► Detailed setup ► Protect ► Write protect ► Enable write 10min	-	-	RW3	All Space	-	The write protect function is canceled for only 10 minutes	P.124
Device Settings ► Detailed setup ► Protect ► User role ► Current role	-	PL1:Operator PL2:Maintenance PL3:Specialist	-	Specialist	-	The present operation levels are displayed.	P.125
Device Settings ► Detailed setup ► Protect ► User role ► Active role	-	0x01:PL1:Operator 0x02:PL2:Maintenance 0x04:PL3:Specialist	-	All off	-	The present active operation levels are displayed	P.125
Device Settings ► Detailed setup ► Protect ► User role ► Set user role PIN	-	-	RW3	0	-	The Maintenance/Specialist pass code is set	P.125
Device Settings ► Detailed setup ► Protect ► User role ► Change user role	-	-	RW1	0	-	Changing of operation levels is implemented	P.125
Device Settings ► Detailed setup ► Protect ► User role ► Maintenance PIN	-	0 to 9999	RW3	0	-	The Maintenance PIN is displayed only when Specialist levels are entered	P.125
Device Settings ► Detailed setup ► Protect ► User role ► Specialist PIN	-	0 to 9999	RW3	0	-	The Specialist PIN is displayed only when Specialist levels are entered	P.125

5.17 Order Information

Menu path

Device Settings ► Detailed setup ► Information ► Order info ► Sensor ► (see table below)

Parameter Name		Doto Bongo	D/M	Dofault Value	Unit	-	Refer
HART	Display	Data Range	R/W	Default value	Unit	Description	to
Sensor MS code 1	-	16 characters	R *2/RW3 *3	All Space *1	-	The sensor model and code are displayed *2/set *3	P.108
Sensor MS code 2	-	16 characters	R *2/RW3 *3	All Space *1	-	The sensor model and code are displayed *2/set *3	P.108
Sensor MS code 3	-	16 characters	R *2/RW3 *3	All Space *1	-	The sensor model and code are displayed *2/set *3	P.108
Sensor MS code 4	-	16 characters	R *2/RW3 *3	All Space *1	-	The sensor model and code are displayed *2/set *3	P.108
Sensor MS code 5	-	16 characters	R *2/RW3 *3	All Space *1	-	The sensor model and code are displayed *2/set *3	P.108
Sensor MS code 6	-	16 characters	R *2/RW3 *3	All Space 1	-	The sensor model and code are displayed *2/set *3	P.108
Sensor style code	-	16 characters	R *2/RW3 *3	All Space	-	The sensor style code is displayed *2/set *3	P.108

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

*2 For R1.01.01 or R1.01.02

*3 For R1.01.03 or more

Menu path

HART	Device Settings ►	Detailed setup	 Information 	Order info ►	Transmitter	(see table below)
	2 c l l c c c c l l l g c r			0.00.000		(000 10.0.0 00.0.0.)

Parameter Name		Data Danga	DAM	Default Value	l lució	Description	Refer
HART	Display	Data Range	FC/ VV	Default value	Unit	Description	to
Transmitter MS code 1	-	16 characters	R *2/RW3 *3	All Space *1	-	The transmitter model and code are displayed $\ensuremath{^2/\text{set}}\ensuremath{^3}$	P.108
Transmitter MS code 2	-	16 characters	R *2/RW3 *3	All Space *1	-	The transmitter model and code are displayed *2/set *3	P.108
Transmitter MS code 3	-	16 characters	R *2/RW3 *3	All Space *1	-	The transmitter model and code are displayed *2/set *3	P.108
Transmitter MS code 4	-	16 characters	R *2/RW3 *3	All Space *1	-	The transmitter model and code are displayed *2/set *3	P.108
Transmitter MS code 5	-	16 characters	R *2/RW3 *3	All Space *1	-	The transmitter model and code are displayed *2/set *3	P.108
Transmitter MS code 6	-	16 characters	R *2/RW3 *3	All Space *1	-	The transmitter model and code are displayed *2/set *3	P.108
Transmitter style code	-	16 characters	R *2/RW3 *3	All Space	-	The transmitter style code is displayed *2/set *3	P.108

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

*2 For R1.01.01 or R1.01.02

*3 For R1.01.03 or more

Menu path

HART Device Settings ► Detailed setup ► Information ► Order info ► Special order ► (see table below)

Parameter Name		Doto Bongo	D/M/		Unit	Description	Refer	
HART	Display	Data Range	R/W Delault Value		Unit	Description		
Special order number 1	-	16 characters	R *1/RW3 *2	All Space	-	The special order No. is displayed *1/set *2	P.108	
Special order number 2	-	16 characters	R *1/RW3 *2	All Space	-	The special order No. is displayed *1/set *2	P.108	
*4 E D1 01 01 D1 01								

*1 For R1.01.01 or R1.01.02

*2 For R1.01.03 or more

Menu path

HART	Device Settings	Detailed setup ►	Information	Order info	Other 🕨	(see table below))
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Parameter Name		Data Banga	DAM	Default Value	Unit	Description	Refer
HART	Display	Data Range	R/W Delauit Val		Unit	Description	to
Sizing number	-	16 characters	R *2/RW3 *3	All Space 1	-	The sizing No. is displayed *2/set *3	P.108
Name plate tag number	-	16 characters	R *2/RW3 *3	All Space *1	-	The name plate tag No. is displayed *2/set *3	P.108
Instruction manual number	-	16 characters	R *2/RW3 *3	All Space *1	-	The instruction manual No. is displayed *2/set *3	P.108
Communication select	-	HART	R	HART	-	The communication type is displayed.	P.108

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

*2 For R1.01.01 or R1.01.02

*3 For R1.01.03 or more

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HART

Menu path		
HART	Device Settings ► Detailed setup ► Information ► Order info ► Option ► (see table below)	

Parameter Name							Pofor
HART	Display	Data Range	R/W	Default Value	Unit	Description	to
Option analog input	-	Off On	R	Off *1	-	The optional analog input is displayed	P.108
Option built-in temperature	-	Off On	R	Off *1	-	The optional built-in temperature gauge is displayed	P.108
Option display installation	-	Off On	R	Off *1	-	The optional display is displayed	P.108
Option burnout	-	High Low	R *2/RW3 *3	High ^{*1}	-	The optional burnout is displayed *2/set *3	P.108
Option NE43	-	Normal NE43	R *2/RW3 *3	Normal *1	-	The optional NE43 is displayed ^{*2} /set ^{*3}	P.108
Option wireless adapter	-	Normal Wireless	RW3	Normal	-	The usage status of the wireless adapter is set	P.108
Option dual bolt calibration	-	Off Upstream Downstream	R *2/RW3 *3	Off ^{*1}	-	The optional dual sesnor is displayed ² /set ³	P.108
Option cryogenic	-	Off On	R	Off *1	-	The optional cryogenic is displayed	P.108
Option built-in verification	-	Off On	R *2/RW3 *3	On	-	The verification option (/VF) is displayed $^{^{\ast}\!2}/\text{set}$ $^{^{\ast}\!3}$	P.108
Prediction function	-	Off On	R *2/RW3 *3	On	-	The predictive diagnosis mode is displayed *2/set *3	P.108
Option SI unit	-	All JP only	R	All *1	-	The optional SI unit is displayed	P.108
Option SIL	-	Off On	R	Off *1	-	The optional SIL is displayed	P.108

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

*2 For R1.01.01 or R1.01.02 *3 For R1.01.03 or more

NOTE

When Option wireless adapter is set to "Wireless", the function to save parameters and totalized values to EEPROM in case of power failure is disabled.

Device Information 5.18

Menu path

HART

Device Settings ► Detailed setup ► Information ► Device info ► (see table below)

Parameter Name		Data Rango	DAA	DefaultValue	l l mit	Description	Refer
HART	Display	Data Range	R/W	Default value	Unit	Description	to
Model	-	-	R	VY Series	-	The device model name is displayed	P.109
Dev id*2 / Device Identifier*3	-	0 to 16777215	R	0 *1	-	The device ID is displayed	P.109
Memo 1	-	-	RW1	All Space	-	Memo 1 is set	P.109
Memo 2	-	-	RW1	All Space	-	Memo 2 is set	P.109
Memo 3	-	-	RW1	All Space	-	Memo 3 is set	P.109
Transmitter S/N	-	-	R *4/RW3 *5	All Space *1	-	The transmitter serial No. is displayed *4/set *5	P.109
Hardware revision	-	-	R	S1.01	-	The hardware software is displayed	P.109
Release date	-	1900/01/01 to 2155/12/31	R	2021/01/01 *1	-	The release date is displayed	P.109
Distributor name	-	-	R	YOKOGAWA	-	The distributor name is displayed	P.109

*1 Values are determined according to ordering information, sizing sheet or information about the combination of sensors.

*2 For Device revision 1 and DD revision 1 or 2 *3 For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more *4 For R1.01.01 or R1.01.02

*5 For R1.01.03 or more

6. Menu Tree (HART communication)

The following shows the hierarchy of the HART communication menu.

NOTE

Online

The available functions and parameters displayed vary depending on communication and I/O code, and option code specified at the time of ordering.

Device Settings	→Page 160
	Easy setup
	Basic setup
	Detailed setup
Diagnostics	→Page 170
	Alarm
	Signal controls
	Condensed status map
	Verification
	Predictive diagnosis
	Sensor signal
Process Variables	→Page 174
	Device variable
	Device variable status
Maintenance	→Page 175
	Test/Simulation
	Adjustment
	Signal controls

(M) Method

Device Settings

Device Settings		_	
	Easy setup		-
		Flow span	4
		Flow damping	-
		Pulse/Status output	_ (M)
		Pulse/Status output mode	4
		Pulse output rate	-
		Frequency output span	-
		Limit switch level	-
		Display line upper	-
		Display line lower	-
		Totalizer start/stop	-
			-
		Totalizer reset/preset	
		Totalizer preset value	-
		Iotalizer reset mode	
		Analog output select	
		Tomporature L PV/	-
			-
	Basic setup	7	
		Тад	7
		Flow rate config	(M)
		Fluid type	1.
		Flow select	1
		Volume unit	7
		Density unit	
		Fixed density	
		Mass unit	
		Temperature unit	
		Fixed temperature	
		Base temperature	
		Pressure unit	
		Fixed pressure	4
		Base pressure	4
		Deviation	_
		Standard/Normal unit	4
		Energy unit	4
			4
			4
		Flow span	4
		Flow damping	
	Detailed setup	→Page 161	_
		Flow rate config	(M)
		Flow rate	_
		1/0	-
		Display	
		Flow user conversion	
		Sensor Information	
		Compensation setup	
		T/P setup	
		Information	
		HART config	
		Protect	
			-

Detailed setup

Detailed setup]	_	
	Flow rate config] (M)	
	Elowroto	1	
	FIOWTALE	Flow lowcut	
		Lowcut limit	
	1/0		I
]	
	Display]	
		Display line upper	
		Display line lower	
		Display period	
		Display startup	
		Display NE107	
		Display format flow	
		Display format temperature	
		Display format pressure	
		1	
	Flow user conversion	Lloorupit	(
			(171)
		Flow user conversion	
		Flow user base unit	
		Flow user unit	
		Flow conversion factor	ļ
	Sensor Information]	
		Nominal size	
		Body type	
		Sensor type	
		Connection type	
		K factor unit	
		K factor	
		Process temperature	
		Max pressure	
		Sensor backup/restore	(M)
		Sensor backup/restore	(101)
		Sensor backup/restore result	
		Sensor S/N	
			I
	Compensation setup]→Page 163	
	T/P setup]→Page 164	
	Information]→Page 165	
	HART config]→Page 166	
	Protect]→Page 169	



I/O

Analog output		
	Analog output select	(
	Analog output limit	(
	Analog output select	
	Analog output low limit	
	Analog output high limit	
Analog input	1	
	Analog input select	
	Analog input unit	
	Analog input LRV	
	Analog input URV	
	Analog input low limit	
	Analog input high limit	
	Analog input fix value	
Pulse/Status output		
	Pulse/Status output	
	Pulse/Status output mode	
	Pulse output rate	
	Frequency output select	
	Frequency output zero	
	Frequency output span	
	Status output condition	
	Status output direction	
	Alarm switch select	
	Limit switch select	
	Limit switch mode	
	Limit switch level	

Limit switch hysteresis Limit switch unit

• Compensation setup

Compensation setup		
	Steam type	
	Heat difference select	
	Compensation type	
	Calculation type	
	Temperature select	
	Pressure select	
	Analog input select	
	Density unit	
	Fixed density	
	Base density	
	Temperature unit	
	Fixed temperature	
	Base temperature	
	Pressure detailed config ^{*1}	(M)
	Pressure unit	
	Fixed pressure	
	Base pressure	
	Air pressure unit	_
	Air pressure	_
	Deviation	_
	Dryness	_
	Temperature coefficient 1	_
	Temperature coefficient 2	_
	Enthalpy unit	_
	Fixed enthalpy	_
	Heat difference conv unit	
	Heat difference conv factor	_
	Density	
	Density ratio	
	Enthalpy	_
	Delta temperature	
	Delta enthalpy	
	Variable status	
		Density data quality
		Density limit status
		Density ratio data quality
		Density ratio limit status
		Enthalpy data quality
		Enthalpy limit status
		Delta temperature data quality
		Delta temperature limit status
		Delta enthalpy data quality

*1 For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

Delta enthalpy limit status

T/P setup T/P setup

Temperature	
	Temperature select
	Temperature unit
	Selected temperature
	Temperature
	Temperature(%)
	Temperature LRV
	Temperature URV
	Temperature damping
	Temperature gain
	Temperature offset
	_
Pressure	
	Pressure select
	Pressure unit
	Selected pressure

Information

Information

	1	
Date/Time		_
	Set current date	(M)
	Operation time	1 1
	Current date ^{*1} / Current Date ^{*2}	1
	Current time ^{*1} / Current Time ^{*2}	1
	Set Clock Date	1
	Set Clock Time	1
Devices info	1]
Device into		1
	IVIOQEI	-
		-
	Momo 1	-
	Momo 2	-
	Memo 3	-
	Transmitter S/N	-
	Software revision	-
	Hardware revision	4
	Release date	-
	Distributor name	-
]
Order info	-	-
	Sensor	
		Sensor MS code 1
		Sensor MS code 2
		Sensor MS code 3
		Sensor MS code 4
		Sensor MS code 5
		Sensor MS code 6
		Sensor siyle code
	Transmitter	
		Transmitter MS code 1
		Transmitter MS code 2
		Transmitter MS code 3
		Transmitter MS code 4
		Transmitter MS code 5
		Transmitter MS code 6
		Transmitter style code
	Special order	1
		Special order number 1
		Special order number 2
	01	
	Other	
		Sizing number
		Name plate tag number
		Instruction manual number
	Option	
		Option analog input
		Option built-in temperature
		Option display installation
		Option burnout
		Option NE43
		Option wireless adapter
		Option dual bolt calibration
		Option cryogenic
		Prediction function
		Option built-in verification
		Option SI unit
		Option SIL

*1 For Device revision 1 and DD revision 1 or 2

*2 For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

• HART config

HART config			
	Loop current mode	(M)	
	Poll addr*1 / Polling Address*2		
	Loop current mode ^{*1} / Loop Current Mode ^{*2}		
	Num reg preams ^{*1} / Number Request Preambles ^{*2}		
	Num resp preams ^{*1} / Number Response Preambles ^{*2}		
	Manufacturer		
	Model ^{*1} / Device Type ^{*2}		
	Тад		
	Long tag		
	Descriptor		
	Message		
	Final asmbly num ⁻¹ / Final Assembly Number ²		
	Max dev vars 1 / Last Device variable 2		
	Software rev ^{*1} / Software Revision* ²		
	Hardware rev ^{*1} / Hardware Revision ^{*2}		
	Cfg chng count ^{*1} / Configuration Change Counter ^{*2}		
	Reset cfg chng flag ¹ / Reset configuration change flag ²	(M)	
	Dynamic variables		
		Dynamic variables assignment	(M)
		PV is ^{*1} / Primary Variable ^{*2}	
		SV is*1 / Secondary Variable*2	ĺ
		TV is ^{*1} / Tertiary Variable ^{*2}	
		QV is ^{*1} / Quaternary Variable ^{*2}	
		PV	
		PV Data quality ^{*1} / PV Process Data Quality ^{*2}	
		PV Limit Status	
		SV Data quality '/ SV Process Data Quality 2	
		TV Data quality '/ IV Process Data Quality 2	
		OV Data quality ^{*1} / OV Process Data Quality ^{*2}	
		QV Limit Status	
			1
	Burst setting	→Page 167 ^{*1} / Page 168 ^{*2}	
	Event notification		
		Set event notification	(M)
		Acknowledge event	(M)
		Stop event notification	(M)
		Mode ' / Event Mode 2	
		Relly Rale 7 Eveni Relly Rale 2	
		Debounce Interval ¹ / Event Debounce Interval ²	
		Status*1 / Event Status*2	
		Time Stamp ^{*1} / Event Time Stamp ^{*2}	
		Device Status Mask ^{*1} / Event Device Status Mask ^{*2}	ĺ
		Device Specific Status 1 Mask*1 / Event Device Specific Status 1 Mask*2	
		Device Specific Status 2 Mask*1 / Event Device Specific Status 2 Mask*2	
		Device Specific Status 3 Mask ^{*1} / Event Device Specific Status 3 Mask ^{*2}	
		Device Specific Status 4 Mask ^{*1} / Event Device Specific Status 4 Mask ^{*2}	
		Device Specific Status 5 Mask ^{*1} / Event Device Specific Status 5 Mask ^{*2}	
		Device Specific Status 6 Mask ¹ / Event Device Specific Status 6 Mask ²	
		Extended Device Status Mask ¹ / Event Extended Device Status Mask ²	
		Standardized Status U Mask '/ EVent Standardized Status U Mask ²	
		Stanuaruized Status T Mask / EVENt Standardized Status 1 Mask /	
		Standardized Status 2 Mask ^{*1} / Event Standardized Status 2 Mask ^{*2}	
		Standardized Status 3 Mask ¹ / Event Standardized Status 3 Mask ²	
		Analog Channel Fixed Mask ^{*1} / Event Analog Channel Fixed Mask ^{*2}	
		Device Specific Status 15 Mask*1 / Event Device Specific Status 15 Mask*2	1
		Device Specific Status 16 Mask*1 / Event Device Specific Status 16 Mask*2	1

*1 For Device revision 1 and DD revision 1 or 2 *2 For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

Burst setting

Burst setting

	Set easy burst	(M)
	Set detailed burst	(M)
ĺ	Stop burst	(M)
ĺ	Stop easy burst	(M)
	Stop detailed burst	(M)
	Burst Message #0	
		Mode
		slot0
		slot1
		slot2
		slot3
		Command
		Update Period
		Irigger Mode
		Classification
	Burst Message #1	
		Mode
		SIOU
		SIUCT
		SIOLZ
		siut3
		SIO(4
		slot6
		slot7
		Command
		Update Period
		Max Update Period
		Trigger Mode
		Classification
		Trigger Units
		Trigger Level
	Burst Message #2	
	Durot moodago #2	Mode
		slot0
		slot1
		slot2
		slot3
		slot4
		slot5
		slot6
		slot7
		Command
		Command Update Period
		Command Update Period Max Update Period
		Command Update Period Max Update Period Trigger Mode
		Command Update Period Max Update Period Trigger Mode Classification
		Command Update Period Max Update Period Trigger Mode Classification Trigger Units
		Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 elot2
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 elot3
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot3 slot4
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot3 slot4 slot5
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot3 slot4 slot5 slot5
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot0 slot1 slot2 slot3 slot4 slot5 slot6 elot7
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot3 slot4 slot5 slot6 slot7 Command
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode Slot0 Slot0 Slot1 Slot2 Slot3 Slot4 Slot5 Slot6 Slot7 Command
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot3 slot4 slot5 slot6 slot7 Command Update Period Max Update Period
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot0 slot1 slot2 slot3 slot4 slot5 slot6 slot7 Command Update Period Max Update Period
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot2 slot3 slot4 slot5 slot6 slot7 Command Update Period Max Update Period Trigger Mode Classification
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot3 slot4 slot5 slot6 slot7 Command Update Period Max Update Period Trigger Mode Classification Trigger Units
	Burst Message #3	Command Update Period Max Update Period Trigger Mode Classification Trigger Units Trigger Level Mode slot0 slot1 slot2 slot3 slot4 slot5 slot6 slot7 Command Update Period Max Update Period Trigger Mode Classification Trigger Level

 * For Device revision 1 and DD revision 1 or 2

Burst setting			
j.	Stop burst	(M)	
	Easy burst setting		1
		Set easy burst	(M)
		Stop easy burst	(M)
		Busrt Message 1 Command	-
		Busrt Message 1 Burst Variable 1	1
		Busrt Message 1 Burst Variable 2	1
		Busrt Message 1 Burst Variable 3	1
		Busrt Message 1 Burst Variable 4]
	Detailed burst setting	Set detailed hurst	
		Stop detailed burst	
		Burst Message 2	()
		Dalot moodago 2	Busrt Message 2 Mode
			Busrt Message 2 Command
			Busrt Message 2 Burst Variable 1
			Busrt Message 2 Burst Variable 2
			Busrt Message 2 Burst Variable 3
			Busrt Message 2 Burst Variable 4
			Busrt Message 2 Burst Variable 5
			Busrt Message 2 Burst Variable 6
			Busrt Message 2 Burst Variable 7
			Busrt Message 2 Burst Variable 8
			Busrt Message 2 Update Rate
			Busrt Message 2 Max Update Rate
			Busit Message 2 Trigger Mode
			Busit Message 2 Trigger Units
			Busit Message 2 Trigger Level
			Basit Meesage 2 mgger 2010
		Burst Message 3	Busrt Message 3 Mode
			Busrt Message 3 Command
			Busrt Message 3 Burst Variable 1
			Busrt Message 3 Burst Variable 2
			Busrt Message 3 Burst Variable 3
			Busrt Message 3 Burst Variable 4
			Busrt Message 3 Burst Variable 5
			Busrt Message 3 Burst Variable 6
			Busit Message 3 Burst Variable 7
			Busit Message 3 Burst Variable 8
			Busit Message 3 Max Lindate Pate
			Busit Message 3 Trigger Mode
			Busrt Message 3 Trigger Class
			Busrt Message 3 Trigger Units
			Busrt Message 3 Trigger Level
		Burst Message 4	Busrt Message 4 Mode
			Busrt Message 4 Command
			Busrt Message 4 Burst Variable 1
			Busrt Message 4 Burst Variable 2
			Busit Message 4 Burst Variable 4
			Busit Message 4 Burst Variable 5
			Bust Message 4 Burst Variable 6
			Busrt Message 4 Burst Variable 7
			Busrt Message 4 Burst Variable 8
			Busrt Message 4 Update Rate
			Busrt Message 4 Max Update Rate
			Busrt Message 4 Trigger Mode
			Busrt Message 4 Trigger Class
			Busrt Message 4 Trigger Units
			Busrt Message 4 Trigger Level

* For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

Protect

Protect

Write protect		
	New password	(N
	Enable write 10min	(N
	Write protect	
	Software seal	
User role		
	Set user role PIN	1)
	Change user role	1)
	Current role	
	Active role	
	Maintenance PIN	
	Specialist PIN	
	Reset PIN code	

Diagnostics

Diagnostics			
	Alarm	→Page 171	
	Signal controls		
	Signal controls	Burpout	
		Burpout recover	-
		Flow sensor alarm action	-
		Temperature sensor alarm action	-
		Analog input alarm action	-
		Fluctuating level	-
			-
		High vibration action	-
			-
			-
			-
		Critical vibration time	-
			-
		Ciogging line Songer girguit threshold	-
		Sensor circuit infeshold	_
		Sensor capacitance infeshold	_
		Sensor resistance threshold	
	Condensed status map	→Page 172	
	Verification		
		Verification Exe	(M)
		Verification target	- ` <i>`</i>
		Verification status	
		Verification select	
		Verification date	
		Verification time	
		Verification operation time	
		Verification result	
		Sensor circuit result	
		Signal circuit result	-
			_
			_
		Alarm record recult	_
		Alamitecold result	
	Predictive diagnosis		
		Prediction execution	
		Prediction select	
		Prediction period	
		Prediction start date	
		Prediction stop date	
		Prediction level	
		Prediction estimate time	
		Prediction alarm time	
		Prediction result	
		Prediction type	
		Prediction data clear ^{*1}	(M)
	Sensor signal	→Page 173	

*1 For Device revision 2 and DD revision 1 or more

Alarm			
	Alarm status select		
	Alarm record select		
	Alarm status		
		System alarm 1	
		System alarm 2	
		Process alarm 1	
		Process alarm 2	
		Setting alarm 1	
		Setting alarm 2	
		Warning 1	
		Warning 2	
	Alarm record		
		Alarm record clear	
		Auto delete time	
		Alarm record 1	
		Alarm record date 1	
		Alarm record time 1	
		Alarm record 2	
		Alarm record date 2	
		Alarm record time 2	
		Alarm record operation time 2	
		Alarm record 3	
		Alarm record date 3	
		Alarm record time 3	
		Alarm record operation time 3	
		Alarm record 4	
		Alarm record date 4	
		Alarm record time 4	
		Alarm record operation time 4	
		Alarm record 5	
		Alarm record date 5	
		Alarm record time 5	
		Alarm record operation time 5	
		Recent alarm 1	
		Recent alarm date 1	
		Recent alarm time 1	
		Recent alarm operation time 1	
		Recent alarm 2	
		Recent alarm date 2	
		Recent alarm operation time 2	
		Recent alarm 3	
		Recent alarm date 3	
		Recent alarm time 3	
		Recent alarm operation time 3	
		Recent alarm 4	
		Recent alarm date 4	
		Recent alarm time 4	
		Recent alarm operation time 4	
		Recent alarm 5	
		Recent alarm date 5	
		Recent alarm time 5	
		Recent alarm operation time 5	
	Additional device status		
		Device status ^{*1} / Device Status ^{*2}	
		Status group 0 ^{°1} / Device Specific Status 1 ^{°2}	
		Status group 1 ^{*1} / Device Specific Status 2 ^{*2}	
		Status group 2 ^{*1} / Device Specific Status 3 ^{*2}	_

Device status ¹ / Device Status ²
Status group 0 ^{*1} / Device Specific Status 1 ^{*2}
Status group 1 ^{*1} / Device Specific Status 2 ^{*2}
Status group 2 ^{*1} / Device Specific Status 3 ^{*2}
Status group 3 ^{*1} / Device Specific Status 4 ^{*2}
Status group 4*1 / Device Specific Status 5*2
Status group 5 ⁺¹ / Device Specific Status 6 ⁺²
Ext dev status ^{*1} / Extended Device Status ^{*2}
Device Diagnostic Status 0 ^{*1} / Standardized Status 0 ^{*2}
Device Diagnostic Status 1 ^{*1} / Standardized Status 1 ^{*2}
AO saturated ^{*1} / Analog Channel Saturated ^{*2}
I/O and Subdevice Status ^{*1} / Standardized Status 2 ^{*2}
WirelessHART Status ^{*1} / Standardized Status 3 ^{*2}
AO fixed ^{*1} / Analog Channel Fixed ^{*2}
Status group 14 ^{*1} / Device Specific Status 15 ^{*2}
Status group 15 ¹ / Device Specific Status 16 ²

*1 For Device revision 1 and DD revision 1 or 2 *2 For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

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Condensed status map

Condensed status map

Reset condensed status map	(M)
Device status ^{*1} / Device Status ^{*2}	
Status group 0 ^{*1} / Device Specific Status 1 ^{*2}	1
Status group 1 ^{*1} / Device Specific Status 2 ^{*2}	1
Status group 2 ^{*1} / Device Specific Status 3 ^{*2}	1
Status group 3 ^{*1} / Device Specific Status 4 ^{*2}	1
Status group 4 ^{*1} / Device Specific Status 5 ^{*2}	1
Status group 5 ^{*1} / Device Specific Status 6 ^{*2}	1
Ext dev status ^{*1} / Extended Device Status ^{*2}	1
Device Diagnostic Status 0 ^{*1} / Standardized Status 0 ^{*2}	
Device Diagnostic Status 1 ^{*1} / Standardized Status 1 ^{*2}	
AO saturated ^{*1} / Analog Channel Saturated ^{*2}]
I/O and Subdevice Status ^{*1} / Standardized Status 2 ^{*2}]
WirelessHART Status ^{*1} / Standardized Status 3 ^{*2}]
AO fixed ^{*1} / Analog Channel Fixed ^{*2}]
Status group 14 ^{*1} / Device Specific Status 15 ^{*2}	
Status group 15 ^{*1} / Device Specific Status 16 ^{*2}	

Device status ¹	/ Device Status ^{*2}	Status group 0 ⁻¹ / Device Specific Status 1 ⁻²	Status group 1 ⁻¹ / Device Specific Status
Primary Variable Out of Limits Map		010:CPU failure	016:ADC circuit failure
Non-Primary Variable Out of Limits Map		011:CPU failure	017:Signal circuit failure
Loop Current Saturated Map		012:Main storage failure	018:Power circuit failure
Loop Current Fixed Map		013:Sub storage failure	020:Flow sensor failure
More Status Available Map		014:Main ASIC failure	021:Temperature sensor failure
Cold Start Map		015:Sub ASIC failure	023:Analog input failure
Configuration Changed Map			
Device Malfunction Map			
Status man 211 / Davias Spacific Status 212	Chatus aroun 211 / Davies Cresific Status 412	Chabus ansur 411 / Davies Creatific Chabus 512	Status group 51 / Davias Spacific Status
Status group 2 */ Device Specific Status 3*	Status group 3 7 Device Specific Status 4 2	Status group 4 7 Device Specific Status 52	Status group 5 7 Device Specific Status
J30:Fluctuation	040: Temperature out of range	050:Flow span set error	060:Sensor backup error
J31: Iransient noise	042:Analog output out of range	051: Iemperature span set error	
032:High vibration	043:Pulse output out of range	053:Flow calculation set error	
033:Critical vibration	044:Analog input out of range	054:Analog output set error	
	045:T/P compensation out of range	055:Pulse output set error	
		056:Analog input set error	
Ext dev status ^{*1} / Extended Device Status ^{*2}	Device Diagnostic Status 0" / Standardized Status 0"	Device Diagnostic Status 1" / Standardized Status 1"	AO saturated ¹ / Analog Channel Saturate
Maintenance Required Map	Device Variable Simulation Active Map	Status Simulation Active Map	Secondary Analog Channel Saturated Ma
Device Variable Alert Map	Non-Volatile Memory Defect Map	Discrete Variable Simulation Active Map	Tertiary Analog Channel Saturated Map
Critical Power Failure Map	Volatile Memory Defect Map	Event Notification Overflow Map	Quaternary Analog Channel Saturated Ma
Failure Map	Watchdog Reset Executed Map	Battery or Power Supply needs Maintenance ^{*1} / Undefined ^{*2}	Quinary Analog Channel Saturated Map
Out of Specification Map	Power Supply Conditions Out of Range Map		
Function Check Map	Environmental Conditions Out of Range Map		
	Electronic Defect Map		
	Device Configuration Locked Map		
VO and Subdevice Status" / Standardized Status 2 ² WirelessHART Status" / Standardized		AO fixed ^{*1} / Analog Channel Fixed ^{*2}	Status group 14 ⁻¹ / Device Specific Status
Sub-Device List Changed Map	Capacity Denied Map	Secondary Analog Channel Fixed Map	070:Sensor communication error
Duplicate Master Detected Map	Bandwidth Allocation Pending Map	Tertiary Analog Channel Fixed Map	071:Flow sensor error
Sub-Device Mismatch Map	Block Transfer Pending Map	Quaternary Analog Channel Fixed Map	072:Clogging
Sub-Devices with Duplicate IDs Found Map	Radio Failure Map	Quinary Analog Channel Fixed Map	073:Degradation
Stale Data Notice Map	J		074:Board temperature out of range

074:Board temperature out of range

Status group 15" / Device Specific Status 16"2 080:Simulation running 081:Verification running 082:Incorrect PIN 083:Device ID not entered

*1 For Device revision 1 and DD revision 1 or 2 $\,$

*2 For Device revision 1 and DD revision 3 or more, Device revision 2 and DD revision 1 or more

Sensor signal

Sensor signal

Sensor signal		
	Signal latch execution	(M)
	Signal latch target	
	Signal latch alarm	
	Signal latch date	
	Signal latch time	
	Signal latch operation time	
	Band data	
	Daila data	Signal latch vortex frequency
		Signal latch velocity
		Signal latch max band
		Signal latch noise ratio
		Signal latch noise band 1
		Signal latch noise band 2
		Signal latch TLA
		Signal latch basic band
		Basic+0 band A
		Basic+0 band B
		Basic+0 band C
		Basic+0 band NJLS
		Basic+1 band A
		Basic+1 band B
		Basic+1 band C
		Basic+1 band NJLS
		Basic+2 band A
		Basic+2 band B
		Basic+2 band C
		Basic+2 band NJLS
		Basic+3 band A
		Basic+3 band B
		Basic+3 band C
		Basic+3 band NJLS
		Basic+4 band A
		Basic+4 band B
		Basic+4 band C
		Basic+4 band NJLS
		Basic+5 band A
		Basic+5 band B
		Basic+5 band C
		Basic+5 band NJLS
		Basic+6 band A
		Basic+6 band B
		Basic+6 band C
		Basic+6 band NJLS
		Basic+7 band A
		Basic+7 band B
		Basic+7 band C
		Basic+7 band NJLS
		Basic+8 band A
		Basic+8 band B
		Basic+8 band C
		Basic+8 band NJLS

Process Variables

Process Variables

	_
Device variable	
	Flow rate(%)
	Flow rate
	Temperature(%)
	Temperature
	Total
	Loop current
	_
Device variable status	
	Flow rate(%) data quality
	Flow rate(%) limit status
	Flow rate data quality
	Flow rate limit status
	Temperature(%) data quality
	Temperature(%) limit status
	Temperature data quality
	Temperature limit status
	Totalizer data quality
	Totalizer limit status
	Loop current data quality
	Loop current limit status

Maintenance

Maintenance

Test/Simulation		
	Auto release time	
	Test/Simulation	(M)
	Display test	│ (M)
	Squawk	│ (̀M)
	Device reset	│ (̀M)
	Sensor reset	│ (̀M)
	Self test	│ (̀M)
	Loop test ^{*1} / Force Loop	
	Current ^{*2}	(171)
	Device variable simulation	(M)
	Device status bit simulation] (̀M)́
		_ 、 ,
Adjustment] →Page 176	
Signal controls	1	
oignaí controid	Signal band	7
	Signal level	-
	Trigger level mode	-
	Trigger level(TLA)	-
	Noise balance mode	
	Noise ratio(auto)	
	Noise ratio(manual)	
	Tuning at zero	「(M)
	Tuning status	
	Velocity	
	Velocity span	
	Velocity lowcut	-
	Vortex frequency	-
	Vortex frequency span	
	Vortex frequency lowcut	
	Board temperature	
	Built-in temperature]
	Analog input(mA)	
	Analog input	
	Variable status	
		Vortex frequency data quality
		Vortex frequency limit status
		Built-in temperature data quality
		Built-in temperature limit status
		Analog input data quality
		Analog input limit status

Adjustment

justinent	Analog output trim		
		Analog output trim] /N
		Analog output trim cloar	
		Poforonco motor(4mA)	- (1)
		Reference meter(20mA)	-
		Analog output trim(4mA)	-
		Analog output trim(411A)	-
		Analog output thim(20mA)	
	Analog input trim		
		Analog input trim] (N
		Analog input trim clear) (N
		Analog input trim(4mA)	Ì
		Analog input trim(8mA)	
		Analog input trim(12mA)	
		Analog input trim(16mA)	
		Analog input trim(20mA)	
	Flow rate gain	_	
	Tiow rate gain		
	Instrument error adjust		-
		Instrument error adjust] (N
		Instrument error adjust	
		Adjust vortex frequency 1	
		Adjust value 1	
		Adjust vortex frequency 2	1
		Adjust value 2	
		Adjust vortex frequency 3	
		Adjust value 3	
		Adjust vortex frequency 4	
		Adjust value 4	
		Adjust vortex frequency 5	
		Adjust value 5	
	Povroldo odiust		
		Revnolds adjust] (N
		Reynolds adjust	1
		Reynolds number	1
		Viscosity unit	1
		Viscosity	1
		Adjust reviside number 1	1
		Readiust value 1	1
		Adjust revnolde number ?	1
		Readiust value 2	1
		Adjust reveales number ?	-
		Readiust value ?	-
		Adjust roypolds pumber 4	-
		Readingt value 4	-
		Adjust roypolds symbor 5	-
		Readiust value 5	-
		I ne aujust value 3	
	Expansion factor adjust	_	

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Revision Information

Title

: Vortex Flowmeter VY Series HART Communication Type

• Manual No. : IM 01F07A02-01EN

Edition	Date	Page	Revised Item
1st	Feb. 2022	-	New issue
2nd	Aug. 2022		Revised as a whole.
3rd	May 2023	15	Revised number of display digits.
		37	Corrections. (Waveform monitoring->Frequency analysis)
		48	Added explanations and a note.
		50, 51	Minor fix.
		53, 54	Minor fix.
		59	Corrections. (A30)
		73	Added a note to Limit switch output.
		90, 93	Minor fix. (Warning->Warnings)
		91	Corrections. (∎System alarm)
		92	Corrections. (∎Process alarm)
		105	Correction to (3) Squawk function.
		112	Added a note to 4.15.6 Predictive Diagnosis.
		124	Correction to 4.17.2 Operation Levels (User Role).
		130	Corrections to 5.3 Basic Setting Items.
		134	Corrections to the parameter list. (D19, 155, 156)
		135	Minor fix.
		168	Minor fix. (Diagnostic->Diagnostics)
4th	Oct. 2023	12	2.2.2 Minor fix.
		13	2.3 Corrections and add note *1, a table
		41	4.1.3 Add a note
		71	4.8.2 Add a note
		77	4.9.1, 4.9.2 Add a parameter item
		90	4.12.1 Minor fix.
		105, 106	4.13.4 Corrections
		108	4.14.1 Corrections
		113	4.15.6 Add an item of NOTE
		124	4.17.1 Corrections of NOTE
		139	5.5 Minor fix.
5th	Aug. 2024	24 - 34	3. Revisions for DD rev.up
		44	4.1.4 Add Long Neck Type
		52	■Pressure basic setting add a NOTE
		89	4.12.1 ■System alarm add a note for remote type
		109 - 121	4. Revisions for DD rev.up
		131-133	5.3 Corrections, add notes
		140, 141	5.6 Corrections for DD rev.up
		154	5.15 Revisions for DD rev.up
		158	5.18 Corrections for DD rev.up
		163 - 175	6. Add Method(M), add note for DD rev.up

	-	_	
Edition	Date	Page	Revised Item
6th	Oct. 2024	24	3.2.1 Device revision update
		25	3.2.2 Device revision update
		28 - 31	3.6.1, 3.6.2 Device revision update
		34	3.6.4 Device revision update
		52	■Pressure basic setting add notes
		77 - 78	4.9.1 Add notes to parameter list
		79	4.9.2 Add notes to parameter list
		108 - 109	4.14.1, 4.14.2, 4.14.3 Add notes to parameter list
		110	4.14.5 Add notes
		113	4.15.6 Add notes to parameter list and NOTE
		121	4.16.4 Add notes
		139	5.5 Add notes to parameter list
		151	5.13 Add notes to parameter list
		154	5.15 Add notes to parameter list
		156 - 157	5.17 Add notes to parameter list
		158	5.18 Add notes to parameter list
		163	Add notes to Menu Tree
		165 - 168	Add notes to Menu Tree
		170 - 172	Add notes to Menu Tree
		175	Add notes to Menu Tree